

Diagonalizability

(Sections 3.3 and 8.2)

Wish: every matrix is diagonal!

We'd wish this because finding determinants is easy for diagonal matrices, any two diagonal matrices commute with respect to matrix multiplication, and more.

Clearly this isn't a realistic wish, so what can we wish for?

Diagonalizability

Let A be an $n \times n$ matrix. We

say A is **diagonalizable** if

there is an invertible $n \times n$ matrix

S and a diagonal $n \times n$ matrix D

with

$$A = SDS^{-1}$$

Q: Is every $n \times n$ matrix diagonalizable?

A: NO! not even for 2×2 matrices...

Example 1: Let $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$.

Suppose A was diagonalizable,

$$A = S D S^{-1} \text{ where } D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}.$$

Calculating the eigenvalues of A ,

$$\det(A - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix})$$

$$= \det \left(\begin{bmatrix} -\lambda & 1 \\ 0 & -\lambda \end{bmatrix} \right)$$

$$= \lambda^2.$$

Setting this equal to zero, we

see that $\lambda = 0$ is the only

eigenvalue of A .

But

$$\lambda^2 = \det(A - \lambda I_2) = \det(S D S^{-1} - \lambda I_2)$$

$$= \det(S D S^{-1} - \lambda S \cdot S^{-1})$$

$$= \det(S D S^{-1} - \lambda S I_2 S^{-1})$$

$$= \det(S (D - \lambda I_2) S^{-1})$$

$$= \det(S) \det(D - \lambda I_2) \det(S^{-1})$$

$$= \cancel{\det(S)} \det(D - \lambda I_2) \frac{1}{\cancel{\det(S)}}$$

$$= \det(D - \lambda I_2)$$

$$= \det\left(\begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}\right)$$

$$= \det\left(\begin{bmatrix} d_1 - \lambda & 0 \\ 0 & d_2 - \lambda \end{bmatrix}\right)$$

$$= (d_1 - \lambda)(d_2 - \lambda)$$

$$\text{So } \lambda^2 = (d_1 - \lambda)(d_2 - \lambda),$$

which implies $d_1 = d_2 = 0$.

$$\text{Then } D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix},$$

and so if

$$A = SDS^{-1}, \text{ then}$$

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = S \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} S^{-1}$$

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix},$$

which is not true!

This shows that $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

is not diagonalizable!

Q: When is a matrix diagonalizable?

Unfortunately, there is no really good answer to this question, in that all conditions are seemingly as hard as diagonalizability to check.

Linear Independence, Bases, and Dimension

A collection of vectors S in a vector space V is said to be **linearly independent** if no vector in S is a linear combination of other vectors in S . Written formally, if $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n \in S$ and there are scalars c_1, c_2, \dots, c_n with

$$c_1 \vec{x}_1 + c_2 \vec{x}_2 + \dots + c_n \vec{x}_n = \vec{0}_V,$$

then $c_1 = c_2 = \dots = c_n = 0$

($c_i = 0$ for all $1 \leq i \leq n$)

A subset B of V is called a **basis** for V if both

1) B is linearly independent

2) $\text{span}(B) = V$.

Finally, we can define the **dimension**

of V to be the number of elements in a basis, denoted $\dim(V)$.

If V has no finite basis, we

set $\dim(V) = \infty$.

Aside: (summing up spans) We now have the terminology to say:

1) If $\vec{v} = \vec{0}_V$, then $\text{span}(\vec{v})$ is a point, and zero-dimensional.

2) If $\vec{v} \neq \vec{0}_V$, then $\text{span}(\vec{v})$ is a line, and one-dimensional.

3) If $\vec{v} \neq \vec{0}_V \neq \vec{w}$, then $\text{span}(\{\vec{v}, \vec{w}\})$ is either a line (one-dimensional) or a plane, and two-dimensional.

4) Given three nonzero vectors \vec{v} , \vec{w} , and \vec{x} , then $\text{span}(\{\vec{v}, \vec{w}, \vec{x}\})$ is

either a line (one-dimensional),
a plane (two-dimensional), or
three-dimensional.

Eigenspaces

If A is an $n \times n$ matrix and

λ is an eigenvalue of A ,

define the eigenspace $E_\lambda \subseteq \mathbb{R}^n$

to be

$$E_\lambda = \{ \vec{x} \in \mathbb{R}^n \mid A\vec{x} = \lambda\vec{x} \}$$

Note: here, $\vec{x} = \vec{0}$ is allowed,

and E_λ is a subspace of \mathbb{R}^n .

Criteria for Diagonalizability

Let A be an $n \times n$ matrix.

Then A is diagonalizable precisely when either of the following two conditions hold:

1) There is a basis B for \mathbb{R}^n consisting of eigenvectors of A .

2) For all eigenvalues δ of A ,

$$\underbrace{\dim(E_\delta)}_{\text{geometric multiplicity of } \delta} = \text{the number of factors of } (\lambda - \delta) \text{ in } \underbrace{\det(A - \lambda I_n)}_{\text{algebraic multiplicity of } \delta}$$

But... neither of these conditions are particularly easy to check. We want a condition that is easy to check, and implies diagonalizability.

Symmetric and Orthogonal matrices

A matrix $A \in M_n(\mathbb{R})$ is said to be **symmetric** if

$$A = A^t$$

A matrix $O \in M_n(\mathbb{R})$ is said to be **orthogonal** (**NOT** usually an "orthogonal projection") if

$$O^t O = I_n, \text{ i.e.,}$$

$$O^t = O^{-1}.$$

Orthogonal Diagonalizability

If A is an $n \times n$ symmetric matrix, then there is a diagonal matrix $D \in M_n(\mathbb{R})$ and an $n \times n$ orthogonal matrix O with

$$A = O D O^t$$

So symmetric matrices are not only diagonalizable, you can choose the invertible matrix to be orthogonal.

Example 2: Let $A = \begin{bmatrix} 1 & 3 \\ 3 & -4 \end{bmatrix}$.

Then A is symmetric.

Orthogonally diagonalize

A .

Solution: The diagonal matrix D will have the eigenvalues of A on the diagonal, so let's calculate the eigenvalues:

$$\det(A - \lambda I_2)$$
$$= \det\left(\begin{bmatrix} 1 & 3 \\ 3 & -4 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}\right)$$

$$= \det\left(\begin{bmatrix} 1-\lambda & 3 \\ 3 & -4-\lambda \end{bmatrix}\right)$$

$$= (1-\lambda)(-4-\lambda) - 9$$

$$= \lambda^2 + 3\lambda - 13$$

Set equal to zero:

$$0 = \lambda^2 + 3\lambda - 13$$

Use quadratic formula.

$$\lambda = \frac{-3 \pm \sqrt{9 - 4(-13)}}{2}$$

$$\lambda = \frac{-3 \pm \sqrt{61}}{2}$$

According to Wolfram Alpha,
the eigenvectors are

$$\begin{bmatrix} \frac{5 \pm \sqrt{61}}{6} \\ 1 \end{bmatrix}$$

for $\lambda_1 = \frac{-3 + \sqrt{61}}{2}$,

$$v_1 = \begin{bmatrix} \frac{5 + \sqrt{61}}{6} \\ 1 \end{bmatrix}$$

for $\lambda_2 = \frac{-3 - \sqrt{61}}{2}$,

$$v_2 = \begin{bmatrix} \frac{5 - \sqrt{61}}{6} \\ 1 \end{bmatrix}$$

Then

$$A = \begin{bmatrix} 1 & 3 \\ 3 & -4 \end{bmatrix} = O D O^t$$

where $D = \begin{bmatrix} \overset{\lambda_1}{-\frac{3+\sqrt{61}}{2}} & 0 \\ 0 & \overset{\lambda_2}{-\frac{3-\sqrt{61}}{2}} \end{bmatrix}$

and

$$O = \begin{bmatrix} \overset{\vec{v}_1}{\frac{5+\sqrt{61}}{6}} & \overset{\vec{v}_2}{\frac{5-\sqrt{61}}{6}} \\ 1 & 1 \end{bmatrix},$$

right?

$$O^t O = \begin{bmatrix} \frac{5+\sqrt{61}}{6} & 1 \\ \frac{5-\sqrt{61}}{6} & 1 \end{bmatrix}.$$

$$\begin{bmatrix} \frac{5+\sqrt{61}}{6} & \frac{5-\sqrt{61}}{6} \\ 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 + \left(\frac{5+\sqrt{61}}{6}\right)^2 & * \\ * & 1 + \left(\frac{5-\sqrt{61}}{6}\right)^2 \end{bmatrix}$$

where

$$* = \left(\frac{5+\sqrt{61}}{6}\right) \cdot \left(\frac{5-\sqrt{61}}{6}\right) + 1$$

So

$$* = \frac{1}{36} (25 - 61) + 1$$

$$* = \frac{-36}{36} + 1 = 0$$

Then

$$O^t O = \begin{bmatrix} 1 + \left(\frac{5 + \sqrt{61}}{6}\right)^2 & 0 \\ 0 & 1 + \left(\frac{5 - \sqrt{61}}{6}\right)^2 \end{bmatrix}$$

$$\neq I_2$$

So O is **NOT** orthogonal!

Easy fix:

replace \vec{v}_1 and \vec{v}_2 with
unit vectors

$$\vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|_2}, \quad \vec{w}_2 = \frac{\vec{v}_2}{\|\vec{v}_2\|_2}.$$

Then

$$A = O D O^t$$

with D as before and

$$O = \begin{bmatrix} \vec{w}_1 & \vec{w}_2 \end{bmatrix}.$$

Observations: (eigenvalues and eigenvectors)

If you can diagonalize $A = SDS^{-1}$,

then:

1) The diagonal entries of D are the eigenvalues of A , appearing as many times as their associated factor occurs in $\det(A - \lambda I_n)$.

2) The columns of S will be eigenvectors for A , corresponding to the eigenvalue in the same column of D . i.e., if

$$S = \begin{bmatrix} \vec{s}_1 & \vec{s}_2 & \dots & \vec{s}_n \end{bmatrix}$$

$\lambda_1 \quad \lambda_2 \quad \dots \quad \lambda_n$

eigenvectors