

Announcements

- 1) HW 6 up, due Monday
- 2) Final : Wednesday 12/19 11:30-2:30

Definition: (multilinearity)

If V_1, V_2, \dots, V_n, V are vector spaces over \mathbb{R} , then a function

$$M: V_1 \times V_2 \times \dots \times V_n \rightarrow V$$

is said to be **multilinear**

if for all (x_1, x_2, \dots, x_n) ,

$$(y_1, y_2, \dots, y_n) \in V_1 \times V_2 \times \dots \times V_n$$

and $\alpha \in \mathbb{R}$,

$$\begin{aligned}
 1) \quad & \alpha M((x_1, x_2, \dots, x_n)) \\
 &= M((\alpha x_1, x_2, \dots, x_n)) \\
 &= M((x_1, \alpha x_2, \dots, x_n)) \\
 &\vdots \\
 &= M((x_1, x_2, \dots, \alpha x_n))
 \end{aligned}$$

$$\begin{aligned}
 2) \quad & M((x_1, x_2, \dots, x_n) + (x_1, x_2, \dots, x_{i-1}, y_i, \dots, x_n)) \\
 &= M((x_1, x_2, \dots, x_{i-1}, x_i + y_i, \dots, x_n)) \\
 &\quad \forall 1 \leq i \leq n
 \end{aligned}$$

Example 1 : (trilinear map)

$$M: \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

$$\text{Let } f_1: \mathbb{R} \rightarrow \mathbb{R}, f_1(x) = 7x$$

$$f_2: \mathbb{R} \rightarrow \mathbb{R}, f_2(x) = 3x$$

$$f_3: \mathbb{R} \rightarrow \mathbb{R}, f_3(x) = 12x$$

$$M((x_1, x_2, x_3)) = f_1(x_1) f_2(x_2) f_3(x_3)$$

$$= 252 x_1 x_2 x_3$$

Let $\alpha \in \mathbb{R}$.

$$\alpha M((x_1, x_2, x_3))$$

$$= \alpha \cdot 252 \cdot x_1 x_2 x_3$$

$$= 252 \cdot (\alpha x_1) x_2 x_3 = M((\alpha x_1, x_2, x_3))$$

$$= 252 x_1 (\alpha x_2) x_3 = M((x_1, \alpha x_2, x_3))$$

$$= 252 x_1 x_2 (\alpha x_3) = M((x_1, x_2, \alpha x_3))$$

This shows property 1)

Now let $y \in \mathbb{R}$.

Then

$$M((x_1 + y, x_2, x_3))$$

$$= 252 (x_1 + y) \cdot x_2 \cdot x_3$$

$$= 252 (x_1 x_2 x_3 + y x_2 x_3)$$

$$= 252 x_1 x_2 x_3 + 252 y x_2 x_3$$

$$= M((x_1, x_2, x_3)) + M((y, x_2, x_3))$$

Similarly, we can show

$$M((x_1, x_2 + y, x_3)) = M((x_1, x_2, x_3)) + M((x_1, y, x_3))$$

and

$$M((x_1, x_2, x_3 + y)) = M((x_1, x_2, x_3)) + M((x_1, x_2, y))$$

and so M is trilinear.

Observation: (vector space structure)

Let $\mathcal{L}(V_1, V_2, \dots, V_n; V)$ denote the set of all multilinear maps from $V_1 \times V_2 \times \dots \times V_n$ to V .

If $f, g \in \mathcal{L}(V_1, V_2, \dots, V_n; V)$ and $\alpha \in \mathbb{R}$, we can endow $\mathcal{L}(V_1, V_2, \dots, V_n; V)$ with a vector space structure as follows:

If $(y_1, y_2, \dots, y_n) \in V_1 \times V_2 \times \dots \times V_n$,

$$(f + g)(y_1, y_2, \dots, y_n)$$

$$= f(y_1, y_2, \dots, y_n) + g(y_1, y_2, \dots, y_n)$$

$$(\alpha f)(y_1, y_2, \dots, y_n)$$

$$= \alpha \cdot f(y_1, y_2, \dots, y_n)$$

Zero vector is the zero function

$$0(y_1, y_2, \dots, y_n) = 0_V$$

Definition: (tensor & tensor product)

Given vector spaces V_1, V_2, \dots, V_n

over the tensor product of

V_1, V_2, \dots, V_n is the vector space

$$\mathcal{L}(V_1^*, V_2^*, \dots, V_n^*; \mathbb{R})$$

and is denoted by

$$V_1 \otimes V_2 \otimes \dots \otimes V_n$$

A tensor is merely an element

$$\text{of } V_1 \otimes V_2 \otimes \dots \otimes V_n$$

Note: This construction is sometimes referred to as the **algebraic** tensor product. If one of the V_i 's is infinite-dimensional, we usually impose additional restrictions on the tensor.

Example 2:

$$\mathbb{R} \otimes \mathbb{R} = \mathcal{L}(\mathbb{R}^*, \mathbb{R}^*; \mathbb{R})$$

$$= \mathcal{L}(\mathbb{R}, \mathbb{R}; \mathbb{R})$$

What is a bilinear function from

$\mathbb{R} \times \mathbb{R}$ to \mathbb{R} ?

Let $(x, y) \in \mathbb{R} \times \mathbb{R}$

If $B: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is bilinear,

$$B((x, y))$$

$$= B((x, y))$$

$$= x B((1, y))$$

$$= xy B((1, 1))$$

$\Rightarrow B((x, y))$ is completely determined by $B((1, 1))$ and the values of x & y .

We can write

$$B((x, y)) = xy B((1, 1))$$

$$= \langle x, y \rangle B((1, 1))$$

\Rightarrow B is a scalar multiple
of the inner product.

$$\Rightarrow \dim_{\mathbb{R}}(\mathbb{R} \otimes \mathbb{R}) = 1,$$

and so $\mathbb{R} \otimes \mathbb{R}$ is isomorphic
to \mathbb{R} as a vector space!

In general, if $M: \underbrace{\mathbb{R} \times \mathbb{R} \times \dots \times \mathbb{R}}_{n \text{ times}} \rightarrow \mathbb{R}$

is multilinear,

$$M((x_1, x_2, \dots, x_n)) \\ = x_1 x_2 \dots x_n \cdot M((1, 1, \dots, 1))$$

and so all $M \in \underbrace{\mathbb{R} \otimes \dots \otimes \mathbb{R}}_{n \text{ times}}$

are scalar multiples of

$$f((x_1, x_2, \dots, x_n)) = x_1 x_2 \dots x_n,$$

and so $\dim_{\mathbb{R}}(\mathbb{R} \otimes \mathbb{R} \otimes \dots \otimes \mathbb{R}) = 1!$

Example 3: Now let's consider

$$\begin{aligned}\mathbb{R}^2 \otimes \mathbb{R}^2 &= \mathcal{L}((\mathbb{R}^2)^*, (\mathbb{R}^2)^*; \mathbb{R}) \\ &= \mathcal{L}(\mathbb{R}^2, \mathbb{R}^2; \mathbb{R})\end{aligned}$$

Let $f \in \mathbb{R}^2 \otimes \mathbb{R}^2$

$$\begin{aligned}& f\left(\left((x_1, y_1), (x_2, y_2)\right)\right) \\ &= f\left(\left((x_1, 0) + (0, y_1), (x_2, y_2)\right)\right) \\ &= f\left(\left((x_1, 0), (x_2, y_2)\right)\right) + f\left(\left((0, y_1), (x_2, y_2)\right)\right)\end{aligned}$$

(additivity in 1st coordinate)

$$= f((x_1, 0), (x_2, 0) + (0, y_2))$$

$$+ f((0, y_1), (x_2, 0) + (0, y_2))$$

$$= f((x_1, 0), (x_2, 0))$$

$$+ f((x_1, 0), (0, y_2))$$

$$+ f((0, y_1), (x_2, 0))$$

$$+ f((0, y_1), (0, y_2))$$

additivity
in 2nd
coordinate

$$= x_1 x_2 f((1,0), (1,0))$$

$$+ x_1 y_2 f((1,0), (0,1))$$

$$+ y_1 x_2 f((0,1), (1,0))$$

$$+ y_1 y_2 f((0,1), (0,1))$$

Pull out
scalars
in each
coordinate

So f is a linear combination of

$$g_{1,1}((x_1, y_1), (x_2, y_2)) = x_1 x_2$$

$$g_{1,2}((x_1, y_1), (x_2, y_2)) = x_1 y_2$$

$$g_{2,1}((x_1, y_1), (x_2, y_2)) = y_1 x_2$$

$$g_{2,2}((x_1, y_1), (x_2, y_2)) = y_1 y_2$$

Claim: $\{g_{i,j} \mid 1 \leq i, j \leq 2\}$

is a basis for $\mathbb{R}^2 \otimes \mathbb{R}^2$

We already know the set spans $\mathbb{R}^2 \otimes \mathbb{R}^2$, so let's prove linear independence:

Suppose $\exists \alpha_{i,j} \in \mathbb{R}$, $1 \leq i, j \leq 2$,

with

$$\sum_{i,j=1}^2 \alpha_{i,j} g_{i,j} = 0$$

Let $e_1 = (1, 0)$, $e_2 = (0, 1)$ be the standard basis of \mathbb{R}^2 .

By construction,

$$g_{i,j}((e_s, e_t)) = \begin{cases} 1, & s=i, t=j \\ 0, & \text{otherwise} \end{cases}$$

So for example,

$$0 = \sum_{i,j=1}^2 \alpha_{i,j} g_{i,j}((e_1, e_2))$$

$$= \alpha_{1,2} g_{1,2}((e_1, e_2))$$

$$= \alpha_{1,2}. \quad \text{In this manner,}$$

we can show $\alpha_{i,j} = 0 \forall 1 \leq i, j \leq 2$

$\Rightarrow \{g_{i,j} \mid 1 \leq i, j \leq 2\}$ is a basis.