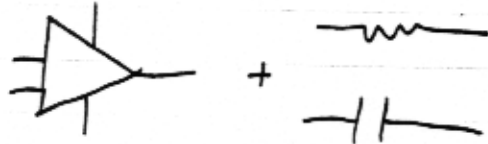
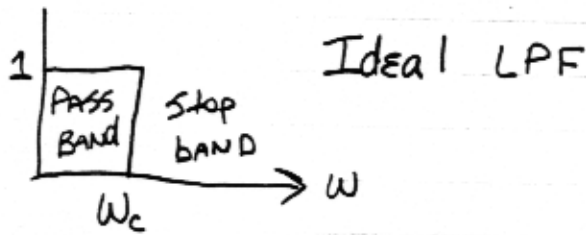


PASSIVE LPF <sup>5/11/98</sup>

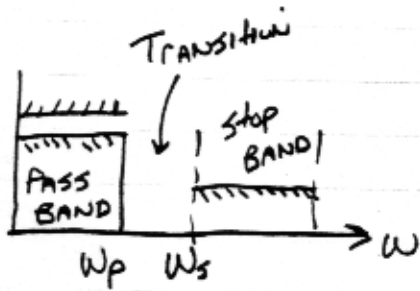


Active RC Filters



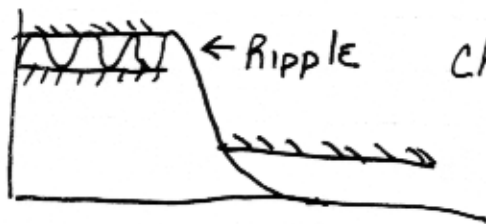
Ideal LPF

NON-CAUSAL



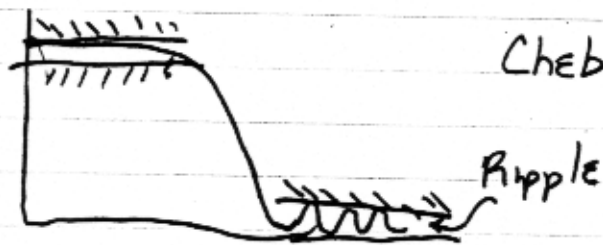
Butterworth LPF - monotonic

$n_B \equiv$  order of filter



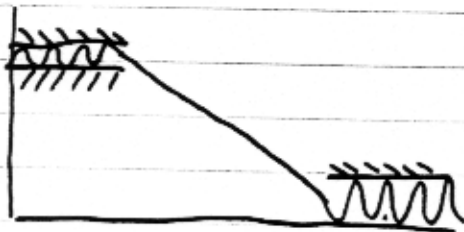
Chebyshev I

$n_{ch}$



Chebyshev II

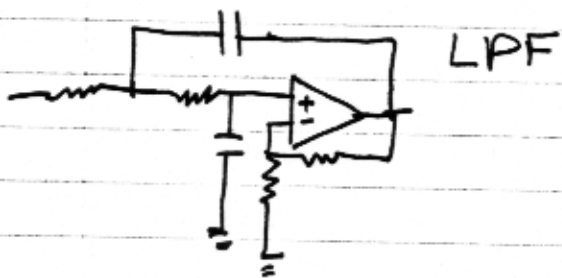
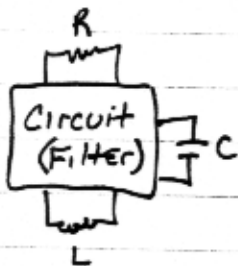
Ripple



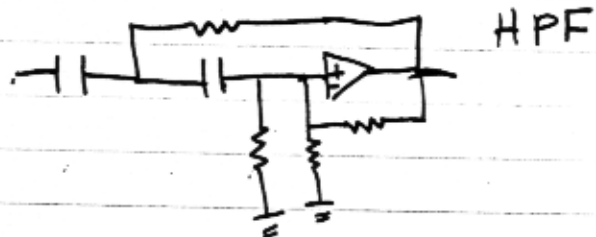
Elliptic

$\epsilon_{\text{Elliptic}} \ll \epsilon_{\text{Ch}} \& \epsilon_{\text{B}}$

### Sensitivity Analysis



LPF



HPF

# Intro.



$$V_O(t) = T\{V_L(t)\}$$

↓  
TRANSFORMATION

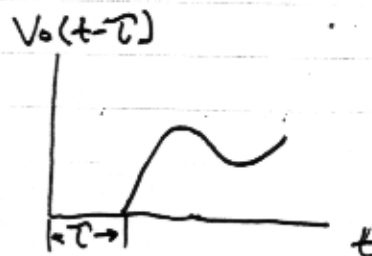
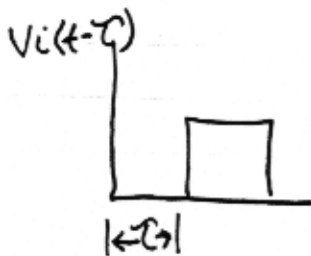
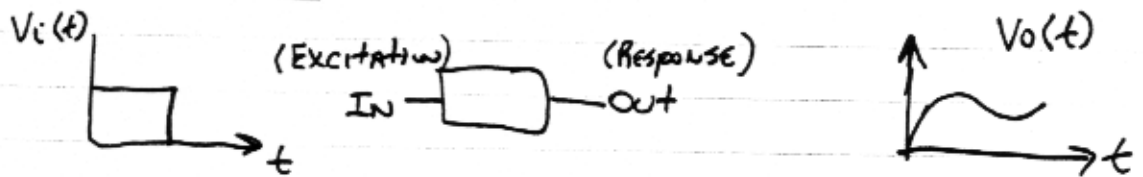
LINEAR:  $V_{i_1}(t) \rightarrow V_{o_1}(t)$

$$V_{i_2}(t) \rightarrow V_{o_2}(t)$$

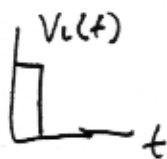
$$\alpha V_{i_1}(t) + \beta V_{i_2}(t) \rightarrow \alpha V_{o_1}(t) + \beta V_{o_2}(t)$$

← Superposition →

## TIME INVARIANT



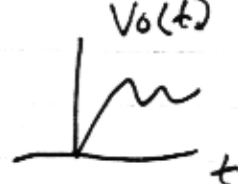
## CAUSAL:



## NON-CAUSAL:

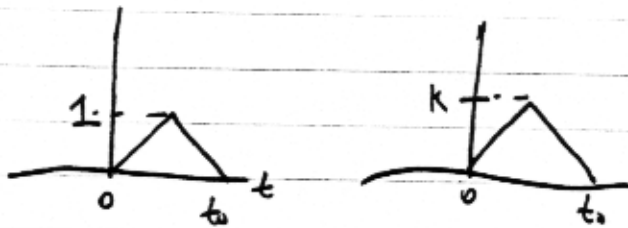


## CAUSAL



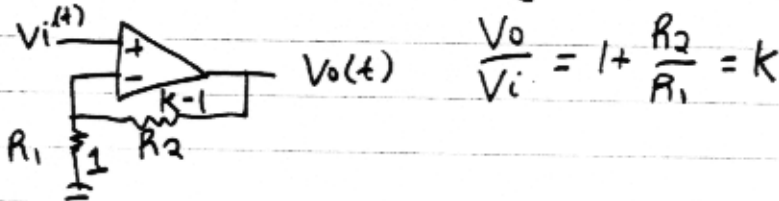
# EXAMPLES

Amplifier

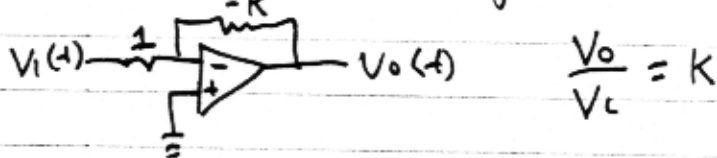


CAUSAL  
LINEAR  
MEMORY-less

$\Rightarrow K > 0$  (Non-inverting)



$\Rightarrow K < 0$  (Inverting)

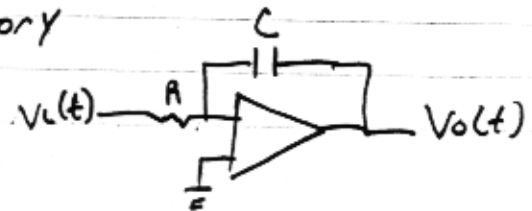


$\Rightarrow$  Integrator

CAUSAL  
LINEAR  
MEMORY



$V_o(t) = K \int_{\text{constant}}^t V_i(\tau) d\tau$



$V_o(t) = -\frac{1}{RC} \int^t V_i(\tau) d\tau$

# Filter Description

## ① TIME - DOMAIN

A - Differential Equation

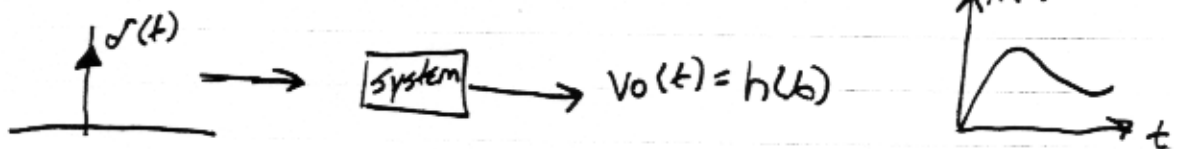
$$\frac{d^2 V_o(t)}{dt^2} + 2 V_o(t) = \frac{d V_i(t)}{dt} - V_i(t)$$

LINEAR Constant Coeff. Diff. Eq.

## ② FREQUENCY DOMAIN

↓  
S-DOMAIN  $H(s)$       FREQUENCY Resp

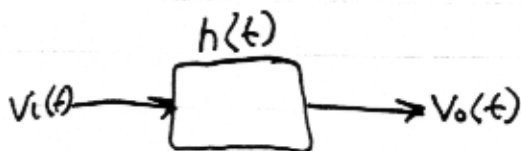
## B. - Impulse Response



Properties:

$$\int_{-\infty}^{\infty} \delta(t) dt = 1 \text{ (Area)}$$

$$f(t) \delta(t - t_0) = f(t_0) \delta(t - t_0)$$



$$\int_{-\infty}^{\infty} f(t) \delta(t - t_0) dt = \int_{-\infty}^{\infty} f(t_0) \delta(t - t_0) dt = f(t_0)$$

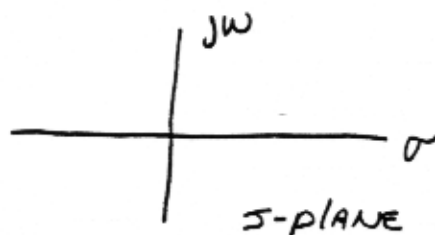
$$= V_i(t) * h(t) = h(t) * V_i(t)$$

$$= \int_{-\infty}^{\infty} V_i(\tau) h(t - \tau) d\tau = \int_{-\infty}^{\infty} h(\tau) V_i(t - \tau) d\tau$$

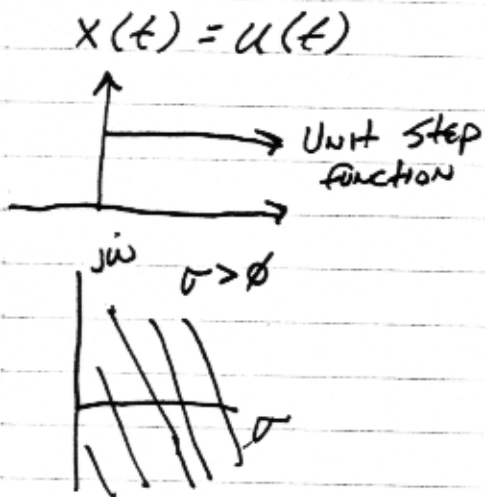
## 2 - S-DOMAIN REPRESENTATION

$$X(t) \xleftrightarrow{LT} X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

$s = \sigma + j\omega$   
↳ complex number



R.O.C. - a strip in the s-DOMAIN



$$\begin{aligned}
 X(s) &= \int_0^{\infty} e^{-st} dt = \frac{1}{s} \quad \text{R.O.C. } \sigma > 0 \\
 &= \int_0^{\infty} e^{-(\sigma + j\omega)t} dt \\
 &= \int_0^{\infty} e^{-\sigma t} |e^{-j\omega t}| dt \quad \rightarrow 1 \\
 |e^{jx}| &= \sqrt{\cos^2 x + \sin^2 x} = 1 \\
 \int_0^{\infty} e^{-\sigma t} dt < \infty \quad \sigma > 0
 \end{aligned}$$

$\rightarrow V_i(t) \rightarrow \boxed{\phantom{H(s)}} \rightarrow V_o(t) = V_i(t) * h(t)$   
 LT  $\downarrow$                       LT  $\downarrow$   
 $V_o(s) = V_i(s) H(s)$   $\rightarrow$  TRANSFER FUNCTION  
 $H(s) = \frac{V_o(s)}{V_i(s)}$

$\rightarrow \frac{dV_o(t)}{dt} + V_o(t) = V_i(t)$

$sV_o(s) + V_o(s) = V_i(s)$      $V_o(s)(s+1) = V_i(s)$      $\frac{V_o(s)}{V_i(s)} = \frac{1}{s+1}$   
 $H(s) = \frac{1}{s+1}$

S-domain representation

5/13/98

$$V_i(t) \xrightarrow{\text{LTI}} V_o(t) = V_i(t) * h(t)$$

LT  $\longrightarrow$

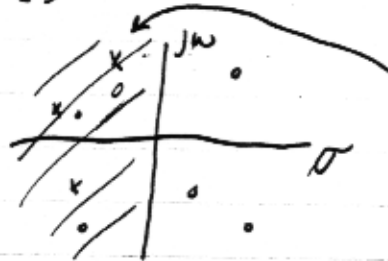
$$V_i(s) \quad V_o(s) = V_i(s) H(s) \quad H(s) = \text{LT}\{h(t)\} = \frac{V_o(s)}{V_i(s)}$$

$\Downarrow$   
TRANSFER FUNCTION

$$H(s) = \frac{N(s)}{D(s)} = \frac{k(s-z_1)(s-z_2)\dots(s-z_m)}{(s-p_1)(s-p_2)\dots(s-p_n)}$$

$Z_i = i=1, 2, 3, \dots, m \quad H(z_i) = 0 \quad \text{ZEROS}$   
 $P_l = l=1, 2, 3, \dots, n \quad H(p_l) = \infty \quad \text{POLES}$

For a stable filter

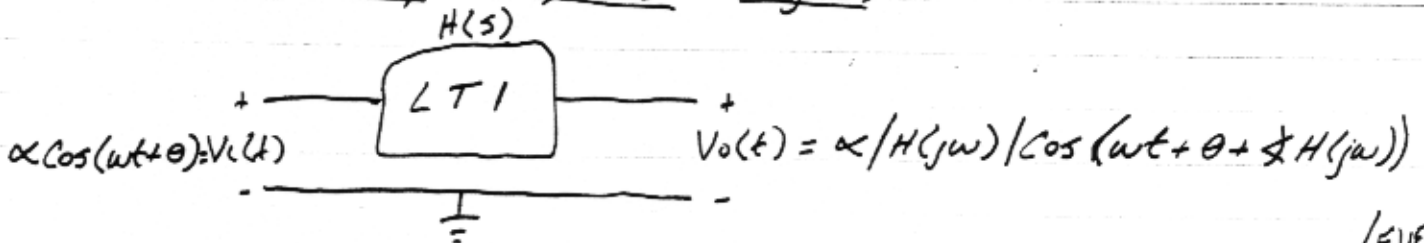


POLES MUST LIE IN LHS OF S-PLANE

ZEROS MAY LIE ANYWHERE

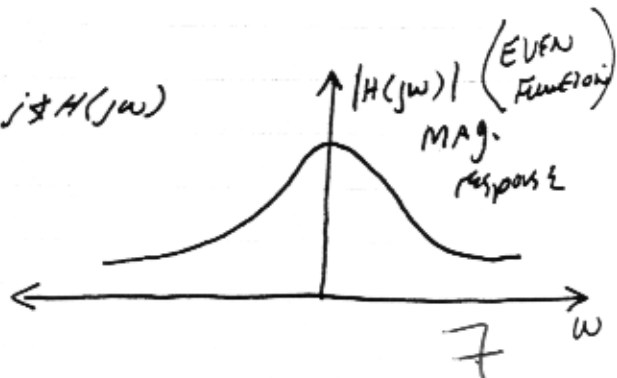
$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$

FREQUENCY RESPONSE  $H(jw)$

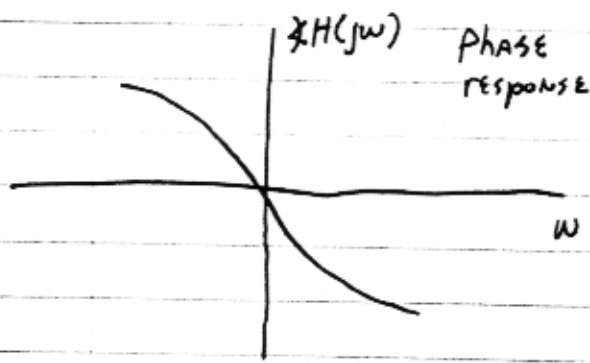


FREQUENCY RESPONSE  $\uparrow$

$$H(jw) = H(s) \Big|_{s=jw} = |H(jw)| e^{j\phi_H(jw)}$$

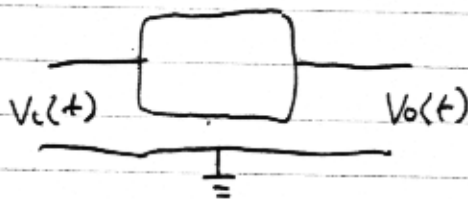


(ODD Function)



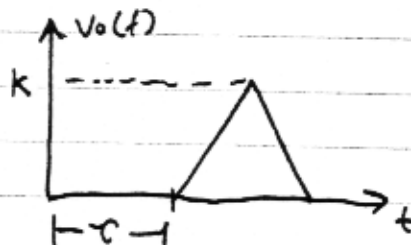
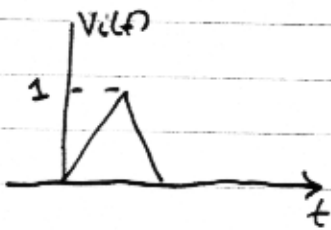
## Types of filters (ideal)

### ① Distortionless Transmission Filter

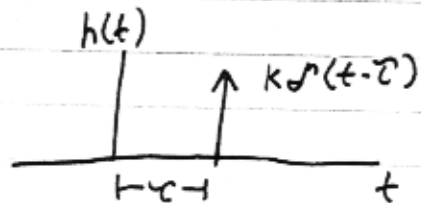


$V_o(t)$  is a delay of  $V_i(t)$

$$V_o(t) = k V_i(t - \tau)$$



### ① Impulse response, h(t)



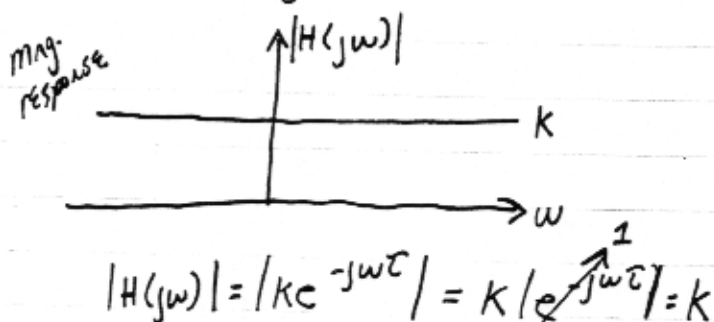
### ② Transfer function, H(s)

$$\begin{aligned} H(s) &= \text{LT} \{ h(t) \} = \text{LT} \{ k \delta(t - \tau) \} \\ &= k e^{-s\tau} \end{aligned}$$



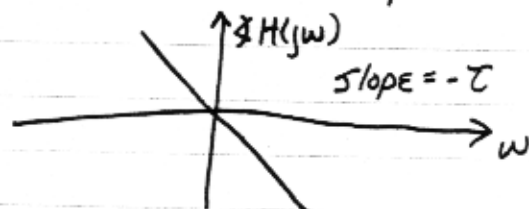
### ③ FREQUENCY RESPONSE, $H(j\omega)$

$$H(j\omega) = k e^{-j\omega\tau}$$



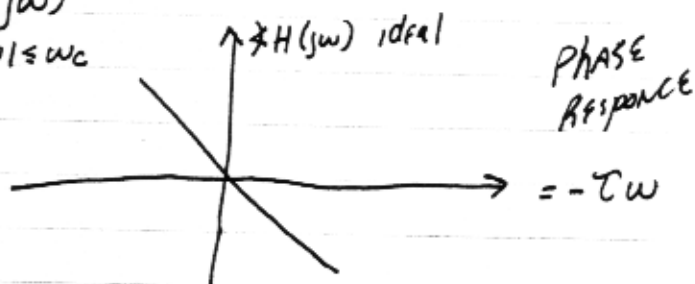
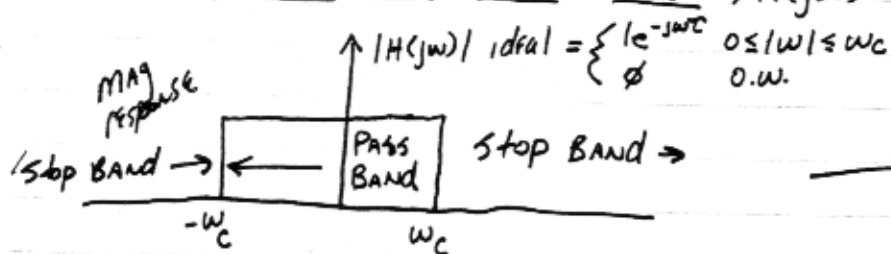
$$\begin{aligned} \angle H(j\omega) &= \angle k e^{-j\omega\tau} \\ &= \angle k + \angle e^{-j\omega\tau} \\ &= 0 - \omega\tau = -\omega\tau \end{aligned}$$

PHASE RESPONSE



Note:  $-\text{Slope} = \tau$  (DELAY)

### ② IDEAL LOW PASS FILTER, $H(j\omega)$



Ideal

$$\begin{cases} |H(j\omega)| = 1 \\ \text{for } 0 \leq |\omega| \leq \omega_c \\ |H(j\omega)| = 0 \text{ o.w.} \end{cases}$$

TEST CAUSALITY: If  $h(t) = 0$  for all  $t < 0$ , then CAUSAL  
o.w.  $\Rightarrow$  NONCAUSAL

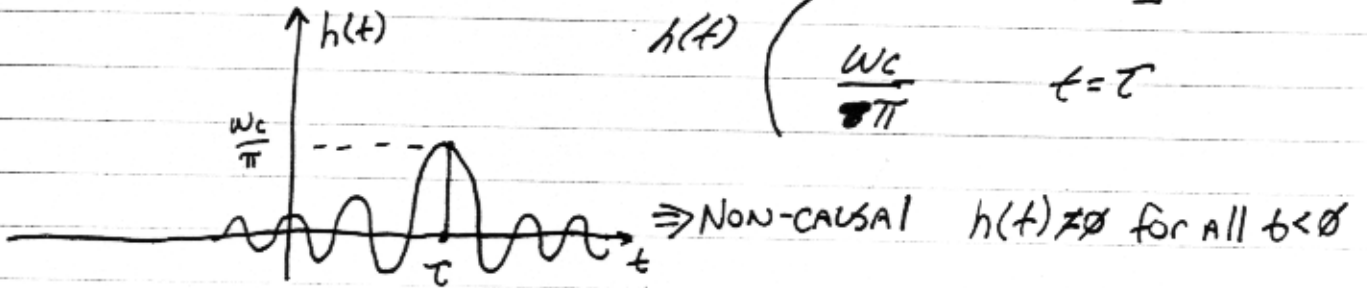
Inverse four x-form

$$\begin{aligned} h(t) &= \mathcal{F}^{-1}\{H(j\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) e^{j\omega t} d\omega \\ &= \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{-j\omega\tau} e^{j\omega t} d\omega \end{aligned}$$

CONTINUE  $\rightarrow$

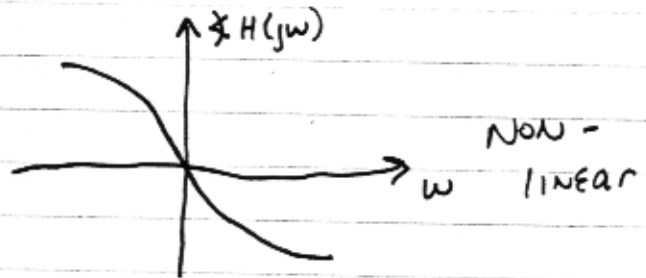
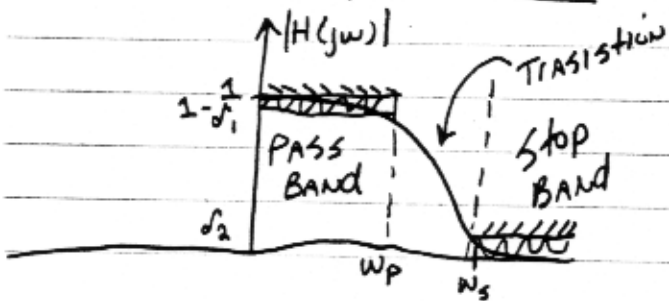
$$h(t) = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega(t-\tau)} d\omega \quad \boxed{\text{X-tra work}} \rightarrow h(\tau) = h(t) \Big|_{t=\tau} = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} d\omega = \frac{\omega_c}{\pi}$$

$$h(t) (t \neq \tau) = \frac{1}{2\pi} \frac{e^{j\omega(t-\tau)} \Big|_{-\omega_c}^{\omega_c}}{j(t-\tau)} = \left\{ \begin{array}{l} \frac{1}{\pi} \left[ \frac{\sin \omega_c(t-\tau)}{(t-\tau)} \right], (t \neq \tau) \\ \frac{\omega_c}{\pi}, t = \tau \end{array} \right.$$

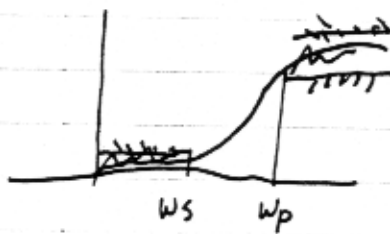


### Real Filter

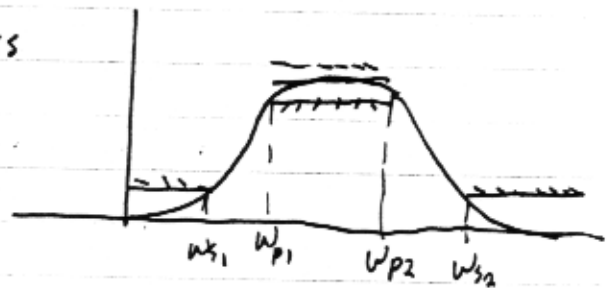
#### LOW-PASS filter



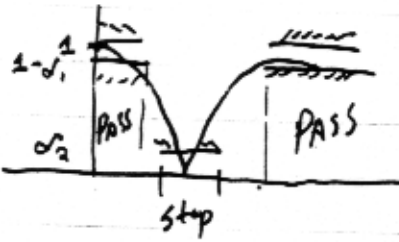
#### Highpass filter



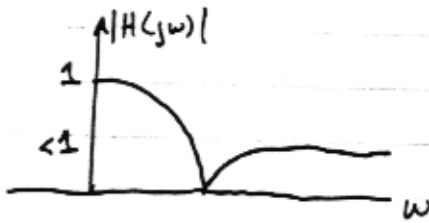
#### Bandpass



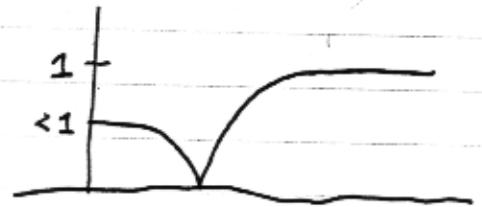
④ BAND reject - notch  
 a - Symmetrical Notch



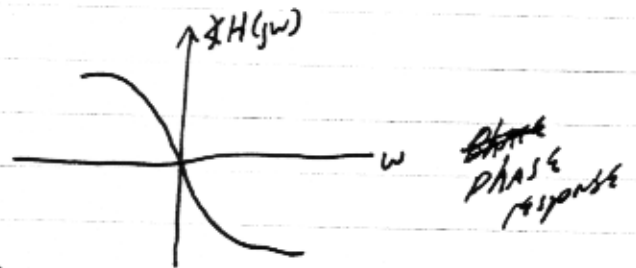
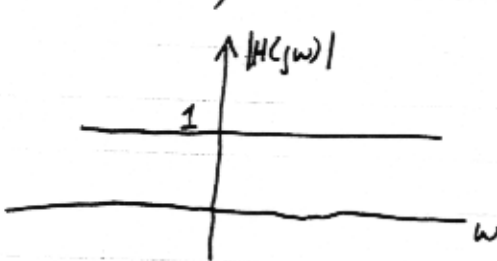
b - low-pass notch



c - High-pass notch



⑤ All pass filter

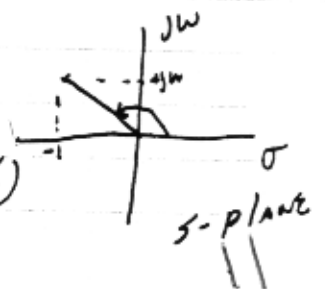


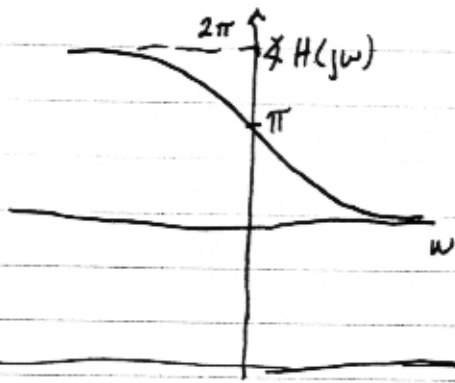
EXAMPLE:

$$H(s) = \frac{s-1}{s+1} \Rightarrow \text{(1st order all pass)}$$

$$H(jw) = \frac{jw-1}{jw+1} \quad |H(jw)| = \frac{\sqrt{1^2+w^2}}{\sqrt{1^2+w^2}} = 1$$

$$\begin{aligned} \angle H(jw) &= \angle(jw-1) - \angle(jw+1) \\ &= \pi - \tan^{-1}(w/1) - \tan^{-1}(w/1) = \pi - 2 \tan^{-1}(w/1) \end{aligned}$$



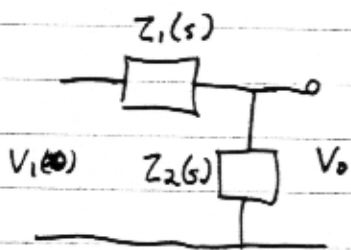
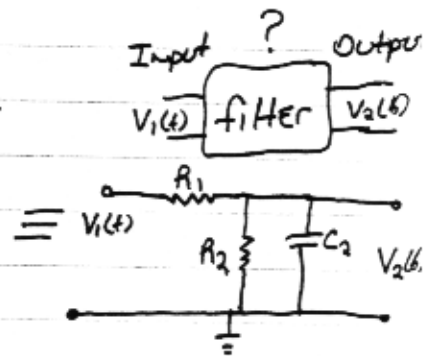
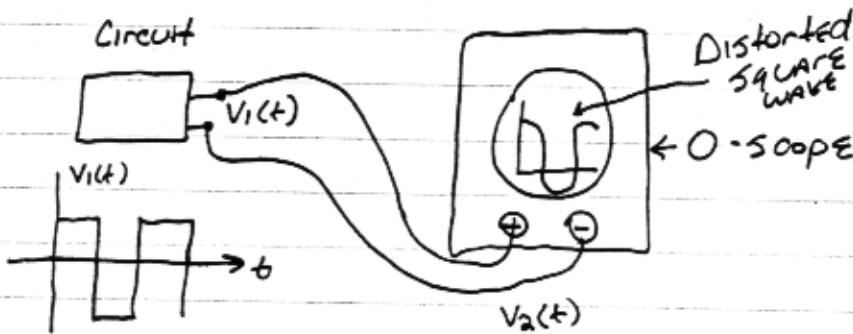


$$\tan^{-1} \omega = \pi/2$$

$$\omega \rightarrow \infty$$

$$\therefore H(j\omega) \rightarrow \emptyset \text{ as } \omega \rightarrow \infty$$

Example:

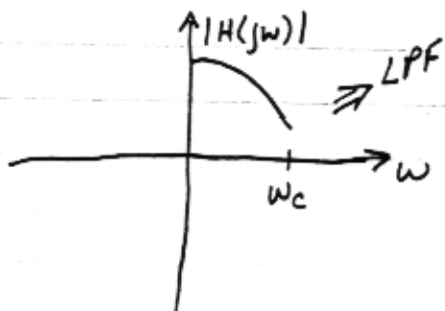


$$H(s) = \frac{V_2(s)}{V_1(s)} = \frac{Z_2(s)}{Z_1(s) + Z_2(s)} = \frac{1}{1 + \frac{Z_1(s)}{Z_2(s)}}$$

$$H(s) = \frac{1}{1 + Z_1(s) Y_2(s)} = \frac{1}{1 + R_1 \left\{ \frac{1}{R_2} + sC_2 \right\}}$$

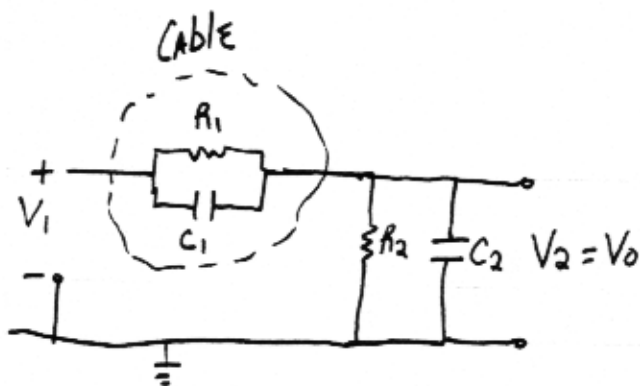
$$H(s) = \frac{1}{1 + \frac{R_1}{R_2} + sC_2(R_1)}$$

Freq. RESP.  $\Rightarrow H(j\omega) = \frac{1}{1 + \frac{R_1}{R_2} + j\omega C_2(R_1)}$



What do we do??

- Next Page -



$$H(s) = \frac{1}{1 + \frac{Y_2(s)}{Y_1(s)}}$$

$$H(s) = \frac{1}{1 + \left[ \frac{\frac{1}{R_2} + sC_2}{\frac{1}{R_1} + sC_1} \right]}$$

F14↑  
RSP

$$H(j\omega) = \frac{1}{1 + \left[ \frac{\frac{1}{R_2} + j\omega C_2}{\frac{1}{R_1} + j\omega C_1} \right]} = 1 + \frac{R_1}{R_2} \frac{(1 + j\omega R_2 C_2)}{(1 + j\omega R_1 C_1)}$$

↑  
MAKE  
CONSTANT

Choose  $R_1 C_1 = R_2 C_2$

$$\therefore H(j\omega) = \frac{1}{1 + \frac{R_1}{R_2}} = \frac{1}{K}$$

$$K = 1 + \frac{R_1}{R_2}$$

$K = 1, 10, 100, \dots$

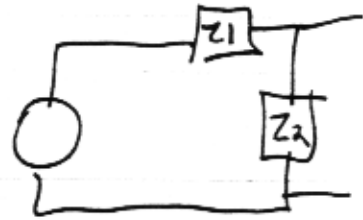
$K = .01, .1, \dots$

# First Order

$$\frac{1}{sC_2} \quad \frac{1}{R_1 + \frac{1}{sC_2}} \quad \frac{1}{sC_2 R_1 + 1}$$

$$\frac{V_0(s)}{V_1(s)} = H(s)$$

$$\frac{Z_2(s)}{Z_1(s) + Z_2(s)}$$



$$Z_1(s) = R_1 \quad Z_2(s) = \frac{1}{sC_2}$$



(Pole 1)

$$H(s) = \frac{1}{sC_2 + R_1} = \frac{1}{1 + sC_2 R_1}$$

$$P_1 = -\frac{1}{C_2 R_1}$$

$$1 + sC_2 R_1 = 0$$

$$s = -\frac{1}{C_2 R_1}$$

$$P_1 = -\frac{1}{C_2 R_1}$$

## Frequency Response

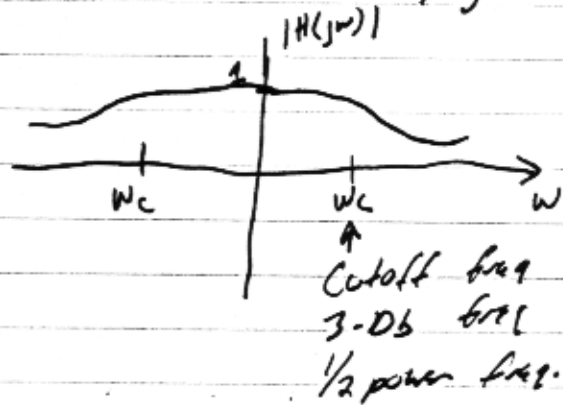
$$H(j\omega) = \frac{1}{1 + j\omega C_2 R_1}$$

$$\tau = C_2 R_1$$

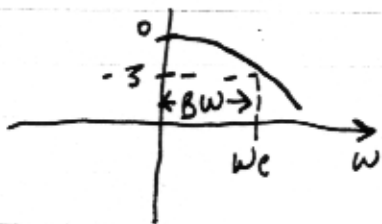
$$H(j\omega) = \frac{1}{1 + j\omega\tau}$$

## Magnitude Response

$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega\tau)^2}}$$



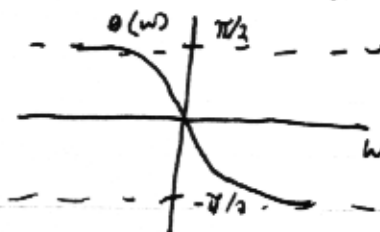
$$20 \log |H(j\omega)|$$



$$\theta(\omega) = \angle H(j\omega) \text{ - Phase Response}$$

$$= \angle 1 - \angle (1 + j\omega\tau)$$

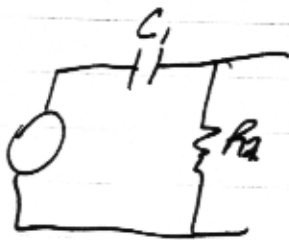
$$= -\tan^{-1}(\omega\tau)$$



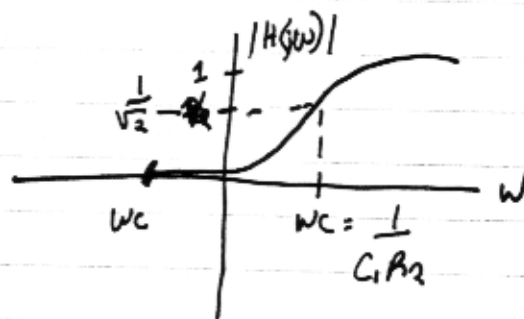
$$\omega_c = \frac{1}{\tau} \Rightarrow \frac{1}{R_1 C_2}$$

$$\theta(\omega_c) = -\tan^{-1}(1) = -\frac{\pi}{4} \quad -\tan^{-1} \frac{\omega R_1}{\tau}$$

First Order High Pass



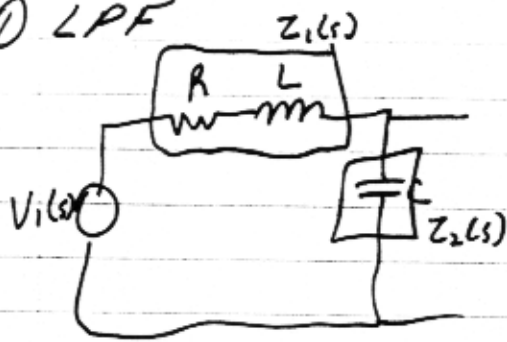
$$H(s) = \frac{R_2}{R_2 + \frac{1}{sC_1}} = \frac{sC_1 R_2}{1 + sC_1 R_2} = \frac{s}{s + \frac{1}{C_1 R_2}}$$



$$H(j\omega) = \frac{j\omega}{j\omega + \frac{1}{C_1 R_2}}$$

## 2nd Order Filter

① LPF



$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_2(s)}{Z_1(s) + Z_2(s)} = \frac{1}{1 + \frac{Z_1(s)}{Z_2(s)}}$$

$$Z_1(s) = R + sL \quad Z_2(s) = \frac{1}{sC}$$

$$H(s) = \frac{1}{1 + sC(R + sL)}$$

$$H(s) = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{\omega_0^2}{s^2 + \frac{\omega_0}{Q}s + \omega_0^2} \quad \leftarrow \text{Standard form}$$

$$\omega_0^2 = \frac{1}{LC} \Rightarrow \omega = \frac{1}{\sqrt{LC}} \text{ rad/sec (Undamped Natural freq)}$$

$$\frac{\omega_0}{Q} = \frac{R}{L} \Rightarrow Q = \frac{L}{R}(\omega_0) \Rightarrow Q = \frac{L}{R} \left( \frac{1}{\sqrt{LC}} \right) \Rightarrow Q = \frac{1}{R} \sqrt{\frac{L}{C}}$$

Quality Factor

## 2nd Order Filter Finding Poles

$$s^2 + \frac{s\omega_0}{Q} + \omega_0^2 = 0 \quad \text{Assume that poles are}$$

$$s_{p1,2} = -\alpha \pm j\beta$$

Two complex conjugate poles

$$s^2 + \frac{s\omega_0}{Q} + \omega_0^2$$

$$(s - s_{p1})(s - s_{p2}) = (s - s_{p1})(s - s_{p1}^*)$$



Note:

$$\omega_0^2 = s p_1 s p_1^* = \alpha^2 + \beta^2 \quad \text{①} \quad (\alpha + j\beta)(\alpha - j\beta) = \alpha^2 + \beta^2$$

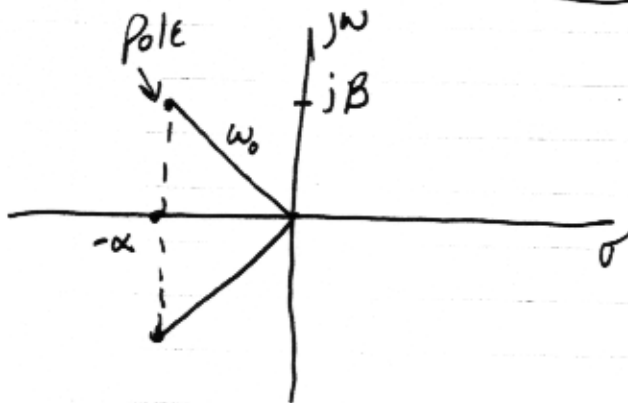
$$\frac{\omega_0}{Q} = -\{s p_1 + s p_1^*\}$$

$$= 2 \text{ RE } \{s p_1\}$$

$$\frac{\omega_0}{Q} = 2\alpha$$

$$\alpha = \frac{\omega_0}{2Q}$$

Using 1  $\omega_0 = \sqrt{1 - \frac{1}{4Q^2}}$

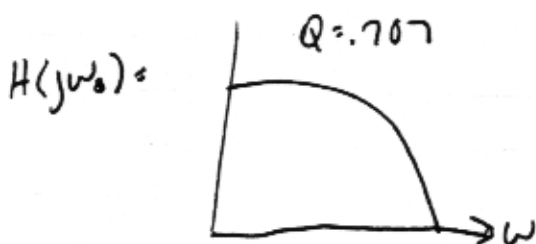
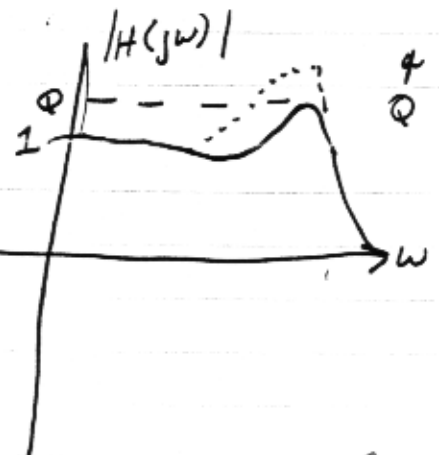


### FREQUENCY RESPONSE

$$H(s) = \frac{\omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2} \Rightarrow H(j\omega) = \frac{\omega_0^2}{(j\omega)^2 + (j\omega) \frac{\omega_0}{Q} + \omega_0^2}$$

$$= \frac{\omega_0^2}{-\omega^2 + j\omega \frac{\omega_0}{Q} + \omega_0^2}$$

$$|H(j\omega)| = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (\omega \omega_0 / Q)^2}}$$

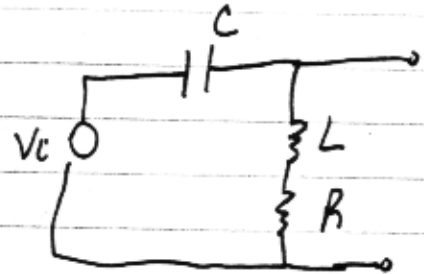


$$H(s) = \underline{H_0 (w_0^2)} \rightarrow H_0 \text{ IS A CONSTANT}$$

$$H_0 = 1 \text{ IN PASS CIRCUIT}$$

### HPF (2<sup>nd</sup> Order)

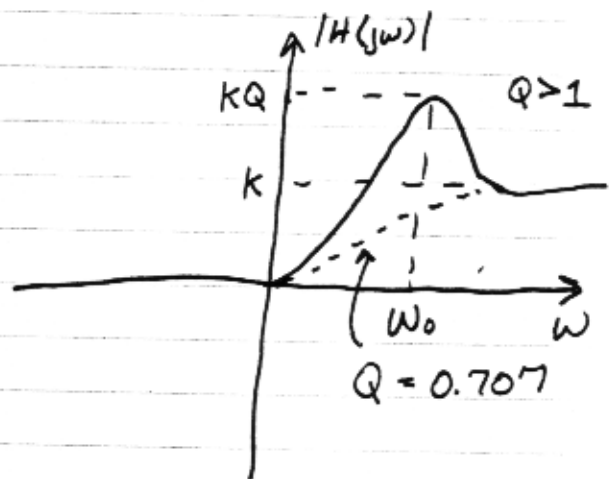
$$H(s) = \frac{Ks^2}{s^2 + \frac{sw_0}{Q} + w_0^2}$$



### FREQUENCY RESPONSE

$$H(jw) = \frac{-Kw^2}{w_0^2 - w^2 + jww_0/Q}$$

$$|H(jw)| = \frac{Kw^2}{\sqrt{(w_0^2 - w^2)^2 + \left(\frac{ww_0}{Q}\right)^2}}$$

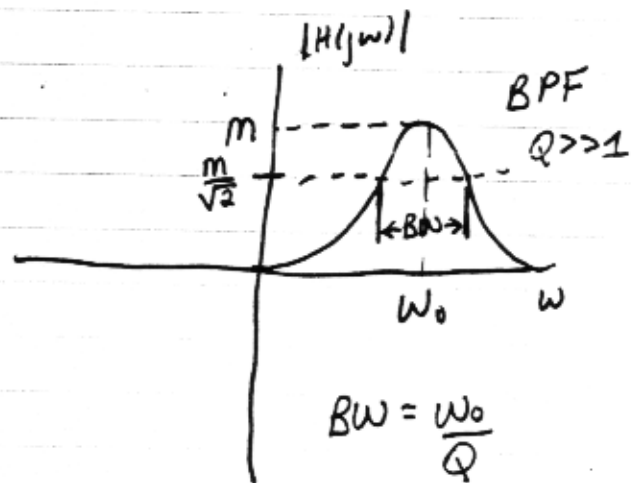


### BANDPASS FILTER (2<sup>nd</sup> Order)

$$H(s) = \frac{m \left(\frac{w_0}{Q}\right) s}{s^2 + s \frac{w_0}{Q} + w_0^2}$$

$$H(jw) = \frac{m \left(\frac{w_0}{Q}\right) jw}{w_0^2 - w^2 + jww_0/Q}$$

$$|H(jw)| = \frac{m \left(\frac{w_0}{Q}\right) |w|}{\sqrt{(w_0^2 - w^2)^2 + \left(\frac{ww_0}{Q}\right)^2}}$$



# BAND Stop filter (aka notch)

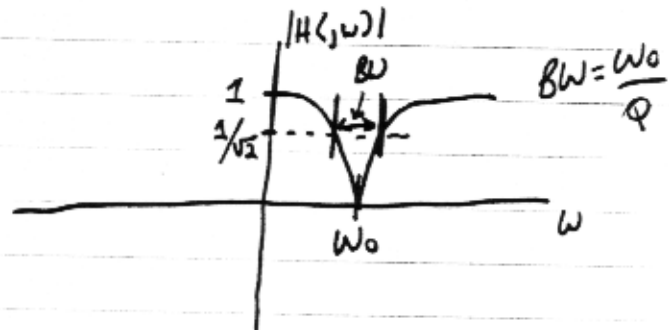
a) Symmetrical

$$H(s) = \frac{s^2 + \omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2} \leftarrow \text{ZEROS}$$

$$s^2 + \omega_0^2 = 0$$

$$s_{z1,2} = \pm j\omega_0$$

$$|H(j\omega)| = \frac{|\omega_0^2 - \omega^2|}{\sqrt{(\omega_0^2 - \omega^2)^2 + \left(\frac{\omega\omega_0}{Q}\right)^2}}$$



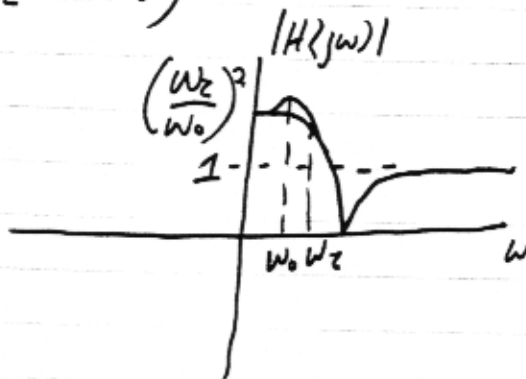
b) Non-symmetrical

LP Notch

$$H(s) = \frac{s^2 + \omega_z^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$$

$$|H(j\omega)| = \frac{|\omega_z^2 - \omega^2|}{\sqrt{(\omega_0^2 - \omega^2)^2 + \left(\frac{\omega\omega_0}{Q}\right)^2}}$$

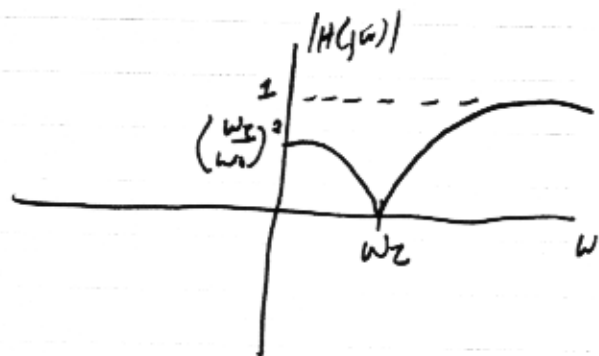
( $\omega_z > \omega_0$ )



High Pass Notch

$\omega_z < \omega_0$

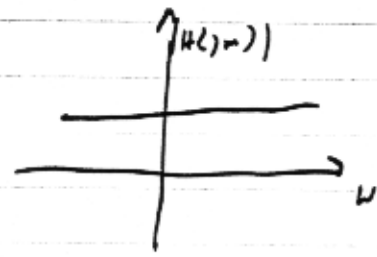
$$H(s) = \frac{s^2 + \omega_z^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$$



# ALLPASS FILTER

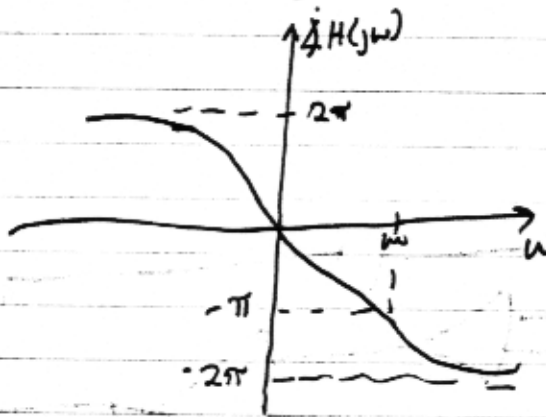
$$H(s) = \frac{s^2 - s \frac{\omega_0}{Q} + \omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$$

$$H(j\omega) = \frac{\omega_0^2 - \omega^2 - j\omega\omega_0/Q}{\omega_0^2 - \omega^2 + j\omega\omega_0/Q}$$



$$|H(j\omega)| = 1$$

$$\theta(\omega) = \angle H(j\omega) = \angle N(j\omega) - \angle D(j\omega)$$

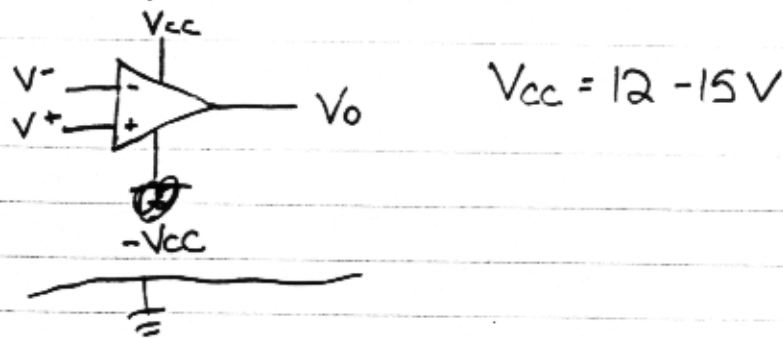


$$= -\tan^{-1} \frac{\omega\omega_0/Q}{\omega_0^2 - \omega^2} - \tan^{-1} \frac{\omega\omega_0/Q}{\omega_0^2 - \omega^2}$$

$$\angle H(j\omega) = -2 \tan^{-1} \frac{\omega\omega_0/Q}{\omega_0^2 - \omega^2}$$

$$\omega = \omega_0 \quad \theta(\omega_0) = -\pi$$

# THE OPERATIONAL AMPLIFIER

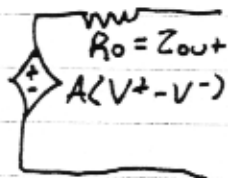


ASSUME IDEAL OPAMP

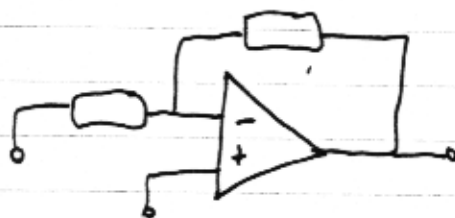
$$V_o = A(V^+ - V^-)$$

$$A \rightarrow \infty \text{ \& \textit{A is real}}$$

$I_n = I_p = \emptyset$       Input impedance  $\rightarrow \infty$   
 Output impedance  $\rightarrow \emptyset$



$\rightarrow$  Apply NEGATIVE feedback in order to render the circuit in the LINEAR region



$$V_o = A(V_p - V_n)$$

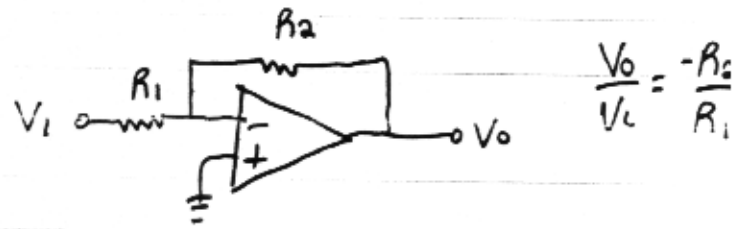
$$\frac{V_o}{A} = V_p - V_n$$

$$\lim_{A \rightarrow \infty} \frac{V_o}{A} = \emptyset = V_p - V_n$$

$$V_p - V_n = \emptyset \quad V_p = V_n$$

# BASIC Circuits

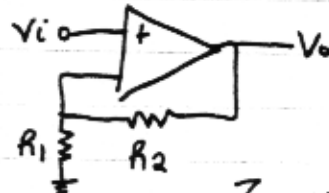
→ INVERTING



$$\frac{V_o}{V_i} = -\frac{R_2}{R_1}$$

$$Z_{IN} = R_1$$

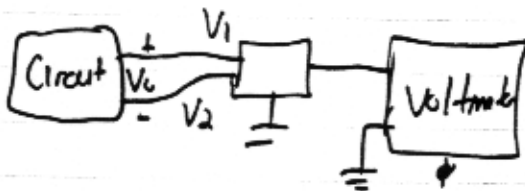
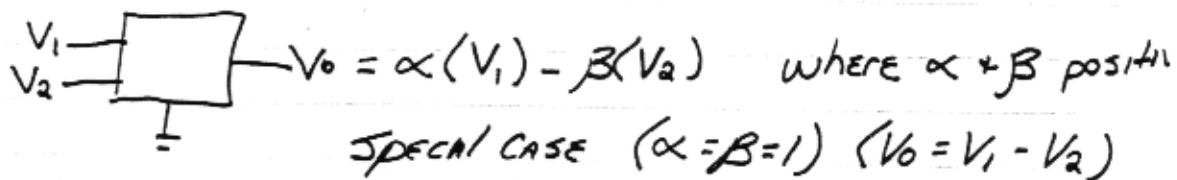
→ NON-INVERTING



$$\frac{V_o}{V_i} = 1 + \frac{R_2}{R_1}$$

$$Z_{IN} = \infty$$

→ Differential Amplifier

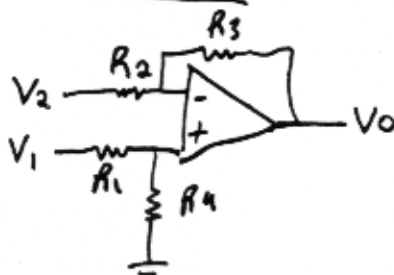


$$V_1 = V_i + V_{noise}$$

$$V_2 = V_{noise} \quad (\text{Common mode noise})$$

$$V_o = V_1 - V_2 = V_i + V_{noise} - V_{noise} = V_i$$

- REALIZATION



$$V_o = \alpha V_1 - \beta V_2$$

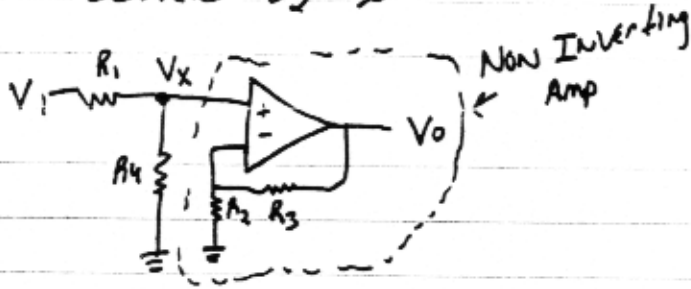
$$\alpha = ? \quad \beta = ?$$

LINEAR Circuit

Finding  $\alpha$ , Assume  $V_2 = 0$

$$\alpha = \frac{V_o}{V_i} \text{ if } V_2 = 0$$

When  $V_2 = \emptyset$



$$\frac{V_o}{V_x} = 1 + \frac{R_3}{R_2} \quad (1)$$

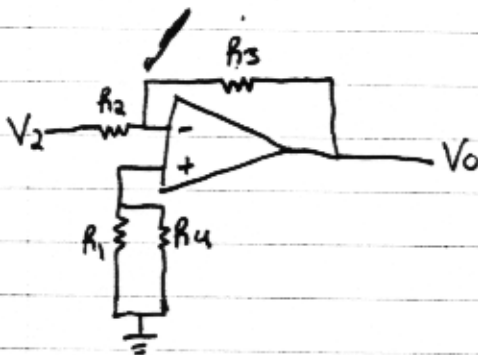
$$\frac{V_x}{V_1} = \frac{R_4}{R_1 + R_4} \quad (2)$$

$$\alpha = \frac{V_o}{V_1} = \frac{V_o}{V_x} \left( \frac{V_x}{V_1} \right)$$

$$\alpha = 1 + \frac{R_3}{R_2} \left( \frac{R_4}{R_1 + R_4} \right) = \frac{1 + \frac{R_3}{R_2}}{1 + \frac{R_1}{R_4}}$$

Divide by  $R_4$

To find  $\beta$ ,  $V_1 = \emptyset$   $\beta = \frac{-V_o}{V_2}$



$$\beta = \frac{-V_o}{V_2} = \frac{R_3}{R_2}$$

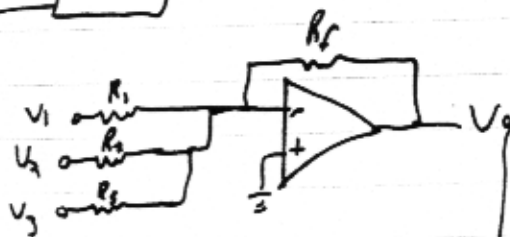
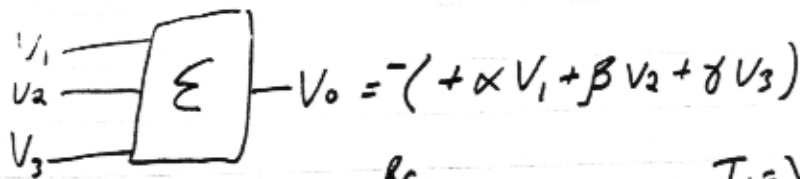
SPECIAL CASE  $V_o = V_1 - V_2 \Rightarrow \alpha = \beta = 1$

$$(\alpha) \quad \frac{R_3}{R_2} = \frac{R_1}{R_4}$$

$$(\beta) \quad R_3 = R_2$$

$$\therefore R_1 = R_2 = R_3 = R_4$$

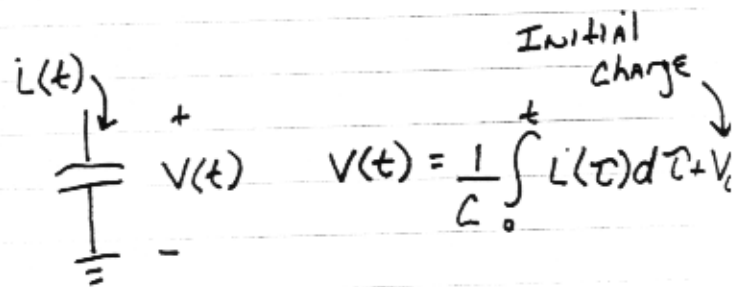
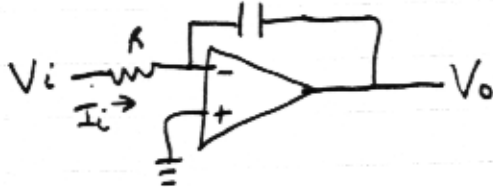
# AN INVERTER ADDER



$$I_1 = \frac{V_1}{R_1} \quad I_2 = \frac{V_2}{R_2} \quad I_3 = \frac{V_3}{R_3}$$

$$V_0 = -\left(\frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2 + \frac{R_f}{R_3} V_3\right)$$

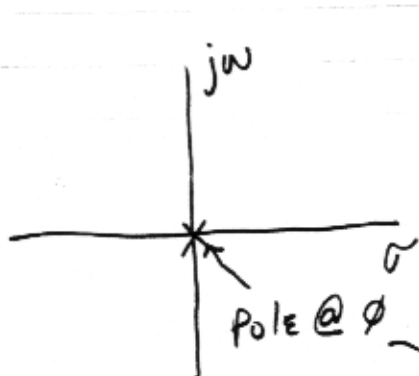
## Integrators



$$I_i = \frac{V_i}{R} \quad V_0(t) = -\frac{1}{C} \int_0^t i(\tau) d\tau + V(0)$$

$$V_0(t) = -\frac{1}{RC} \int_0^t V_i(\tau) d\tau + V(0)$$

Assume  $V_0(0) = 0$        $V_0(t) = -\frac{1}{RC} \int_0^t V_i(\tau) d\tau$



$$\frac{dV_0(t)}{dt} = -\frac{1}{RC} V_i(t)$$

$$s V_0(s) = -\frac{1}{RC} V_i(s)$$

$$\frac{V_0(s)}{V_i(s)} = \boxed{-\frac{1}{sRC}}$$

UNSTABLE

POLES must be on LEFT H. S.

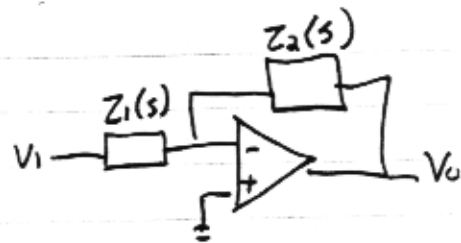


## Practical Integrator

Lossy Integrator

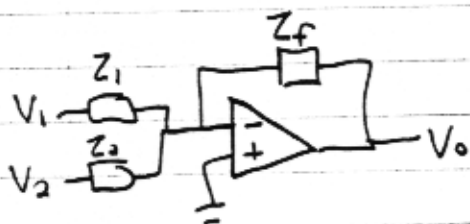


$$R_x \gg \left| \frac{1}{\omega_{in} C} \right|$$



$$\frac{V_o(s)}{V_i(s)} = \frac{-Z_2(s)}{Z_1(s)} \quad \begin{matrix} Z_1(s) = R \\ Y_2(s) = \frac{1}{R_x} + sC \end{matrix}$$

$$= \frac{-1}{Z_1(s) Y_2(s)} = \frac{-1}{R \left( \frac{1}{R_x} + sC \right)} = \frac{-1}{\left( \frac{R}{R_x} + sCR \right)}$$

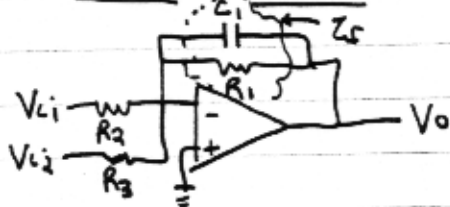


$$V_o = (\dots) V_1(s) + (\dots) V_2(s)$$

$$V_o = -\frac{Z_f}{Z_1} V_1 - \frac{Z_f}{Z_2} V_2$$

## The Biquad Circuit

### First Block

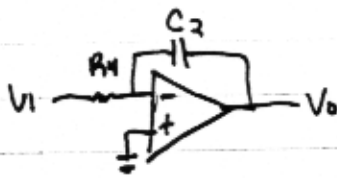


$$V_o(s) = -\frac{Z_f}{R_2} V_{i1} - \frac{Z_f}{R_3} V_{i2}$$

$$= -\frac{1}{Y_f R_2} V_{i1} - \frac{1}{Y_f R_3} V_{i2}$$

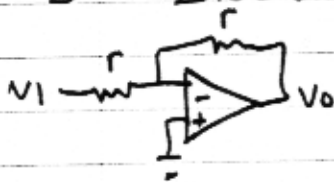
$$= -\frac{1}{\left( \frac{1}{R_1} + sC_1 \right) R_2} V_{i1} - \frac{1}{\left( \frac{1}{R_1} + sC_1 \right) R_3} V_{i2} \quad \text{①}$$

## 2nd Block



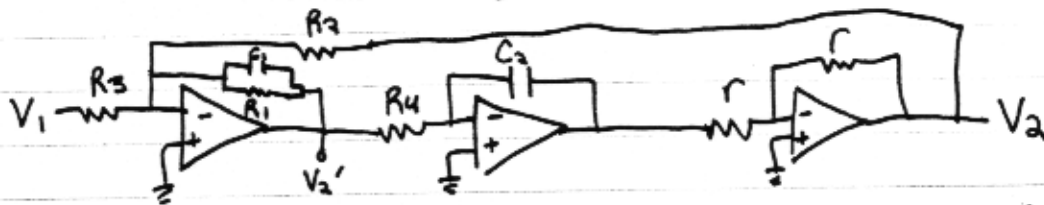
$$\frac{V_0(s)}{V_1(s)} = \frac{-1}{sC_2 R_4} \quad (-2)$$

## 3rd Block



$$\frac{V_0}{V_1} = -1 \quad (-3)$$

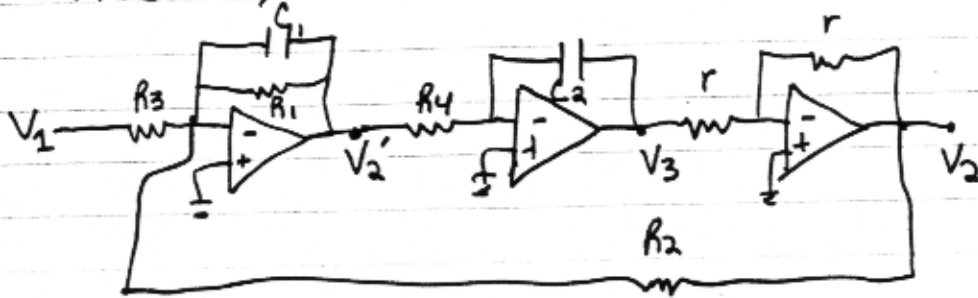
## The Complete Circuit



$$\frac{V_2(s)}{V_1(s)} = ? \quad \text{LRF}$$

$$\frac{V_2'(s)}{V_1(s)} = ? \quad \text{BPF}$$

# THE BIQUAD FILTER



ANALYSIS

$$R_2 = R \quad C_1 = C \quad R_1 = QR$$

$$R_3 = \frac{R}{H} \quad R_4 = R \quad C_2 = C \quad r = R$$

$$V_2 = -V_3 \quad (-1)$$

$$V_3 = \frac{-1}{sC_2 R_4} V_2' \quad (-2)$$

$$V_2' = - \left\{ \frac{1}{R_3 \left( \frac{1}{R_1} + sC_1 \right)} \right\} V_1 - \left\{ \frac{1}{R_3 + \frac{1}{R_2} + sC_1} \right\} V_2 \quad (-3)$$

$$\frac{V_2}{V_1} = ?$$

From 1 & 2

$$V_2 = \frac{1}{sC_2 R_4} V_2' \Rightarrow V_2' = sC_2 R_4 V_2$$

$$sC_2 R_4 V_2 = - \left\{ \frac{1}{R_3 \left( \frac{1}{R_1} + sC_1 \right)} \right\} V_1 - \left\{ \frac{1}{R_3 + \frac{1}{R_2} + sC_1} \right\} V_2 \quad (-4)$$

$$\frac{V_2}{V_1} = \frac{-1 / [C_1 C_2 R_3 R_4]}{s^2 + s / C_1 R_1 + \frac{1}{R_2 R_4 C_1 C_2}}$$

↑  
AN INVERTING LOW-PASS FILTER

$$\frac{-H\omega_0^2}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$$

↑  
STANDARD LPF

$$\omega_0^2 = \frac{1}{R_2 R_4 C_1 C_2} \quad (1)$$

$$H = \frac{R_2}{R_3} \quad (2) \quad \frac{\frac{1}{C_1 C_2 R_3 R_4}}{\frac{1}{R_2 R_4 C_1 C_2}} = \frac{R_2}{R_3}$$

$$\frac{\omega_0}{Q} = \frac{1}{C_1 R_1} \Rightarrow Q = C_1 R_1 \omega_0 \Rightarrow Q = C_1 R_1 \frac{1}{\sqrt{R_2 R_4 C_1 C_2}} \quad (3)$$

DESIGN EQUATIONS:

$$C_1 = C_2 = C$$

$$R_2 = R_4 = r = R$$

$$\therefore \omega_0 = \frac{1}{RC} \quad (1)$$

$$Q = \frac{R_1}{R} \quad (3)$$

$$H = \frac{R}{R_3} \quad (2)$$

$$\omega_0 = \frac{1}{RC}$$

$$\frac{V_2}{V_1} = \frac{-H\omega_0^2}{s^2 + \frac{5\omega_0}{Q}s + \omega_0^2} \quad \text{INVERTING LOW-PASS}$$

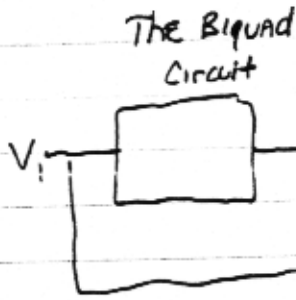
$$\frac{V_3}{V_2} = \frac{-1}{5CR} \quad \frac{V_3}{V_1} = \frac{-V_2}{V_1} = \frac{H\omega_0^2}{s^2 + \frac{5\omega_0}{Q}s + \omega_0^2} \quad \text{NON-INVERTING LOW PASS}$$

$$\text{look @ circuit} \quad \frac{V_2'}{V_1} = \frac{V_2''}{V_3} \cdot \frac{V_3}{V_1} = \frac{-5CR \cdot H\omega_0^2}{s^2 + \frac{5\omega_0}{Q}s + \omega_0^2} = \frac{-H\omega_0 5}{s^2 + \frac{5\omega_0}{Q}s + \omega_0^2}$$

$\downarrow$   $\frac{1}{RC} = \omega_0$  ↑  $Q$   
 INVERTING BANDPASS FILTER

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## Notch AND All-PASS Realizations



$$V_0 = -(V_2' + V_1) \quad (1)$$

INVERTING ADDER

$$\frac{V_0}{V_1} = -1 - \frac{V_2'}{V_1} \quad (2)$$

From Before

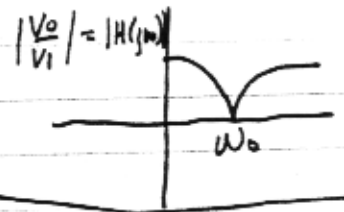
$$\frac{V_0}{V_1} = -1 + \frac{H\omega_0 s}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2} = \frac{-(s^2 + s\frac{\omega_0}{Q} + \omega_0^2 - H\omega_0 s)}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$$

$$= \frac{-(s^2 + s(\frac{\omega_0}{Q} - H\omega_0) + \omega_0^2)}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$$

Notch Filter

$$H(s) = \frac{-(s^2 + \omega_0^2)}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$$

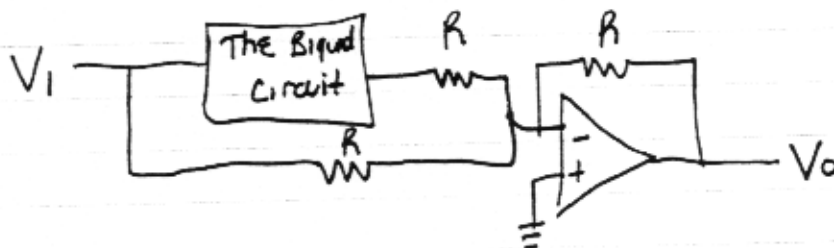
For notch  $\frac{\omega_0}{Q} = H\omega_0 \Rightarrow H = \frac{1}{Q}$



All PASS      All PASS

$$H(s) = \frac{-(s^2 - s\frac{\omega_0}{Q} + \omega_0^2)}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$$

$$H\omega_0 - \frac{\omega_0}{Q} = \frac{\omega_0}{Q} \Rightarrow H = \frac{2}{Q}$$



Example:

DESIGN a BPF WITH  $\omega_0 = 1000 \text{ rad/sec}$   
 $BW = 200 \text{ rad/sec}$   
 $H = 1$

---

$$Q = \frac{\omega_0}{BW} = \frac{1000}{200} = 5$$

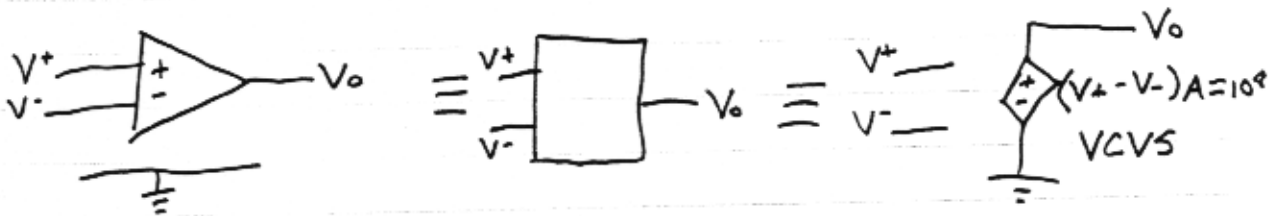
$$\omega_0 = \frac{1}{RC} \Rightarrow 1000 = \frac{1}{RC}$$

CHOOSE  $C = 0.1 \mu\text{F}$   
 $\therefore R = 10 \text{ k}\Omega$

BACK TO ORIGINAL CIRCUIT \* FILL IN VALUES.

$$R = 10 \text{ k}\Omega \quad C = 0.1 \mu\text{F} \quad QR = 50 \text{ k}\Omega \quad \frac{R}{H} = 10 \text{ k}\Omega$$

---



GB  $\rightarrow$  1 MHz

$$H(s) = \frac{s^2 + 100}{s^2 + 2s + 100}$$

$$\omega_0^2 = 100 \Rightarrow \omega_0 = 10$$

$$\frac{\omega_0}{Q} = 2 \Rightarrow \frac{10}{Q} \quad Q = 5$$

$$\text{NUM} = [1 \ 0 \ 100];$$

$$\text{DEN} = [1 \ 2 \ 100];$$

$$w = [0 : .1 : 50]; \text{ frequency vector}$$

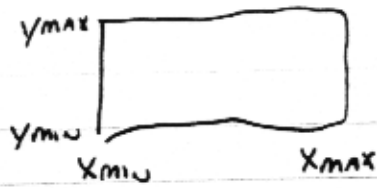
$$H = \text{freqs}(\text{NUM}, \text{DEN}, w);$$

$$\text{mag} = \text{abs}(H); \text{ mag. response}$$

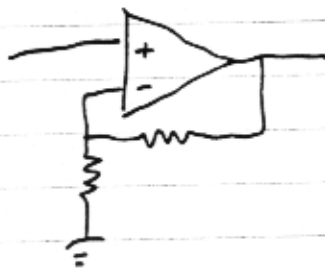
$$\text{magdb} = 20 * \log_{10}(\text{mag}); \text{ decibels}$$

cont  $\rightarrow$

$\text{Phase} = \text{ANGLE}(H)$ ; PHASE RESPONSE (ADIANS)

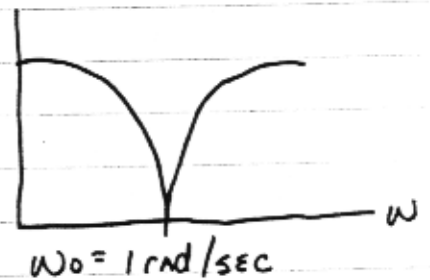
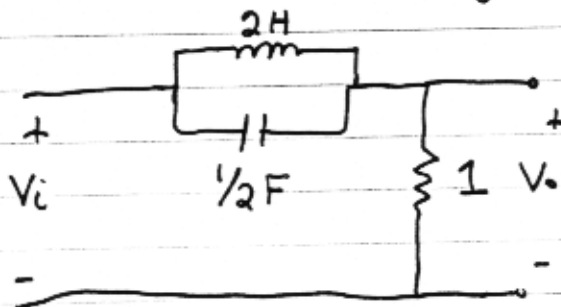


$V = [X_{\min} \quad X_{\max} \quad Y_{\min} \quad Y_{\max}]$ ;  
 AXIS (V);

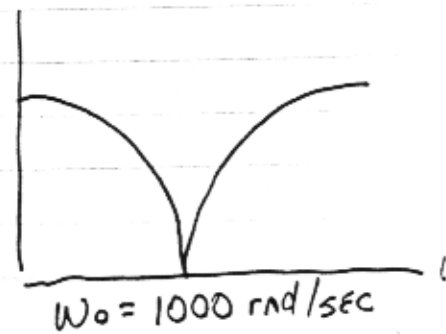


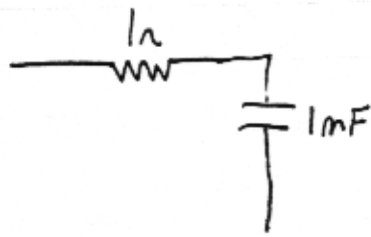
SCALING

- ① FREQUENCY SCALING (DENORMALIZATION)
- ② IMPEDENCE SCALING



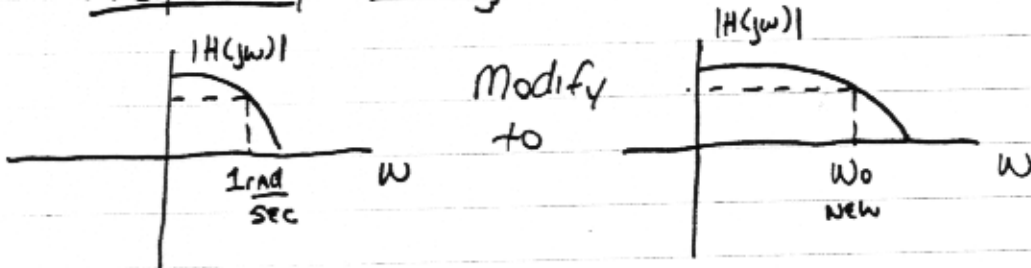
CHANGE L & C TO CHANGE  $\omega_0$ .





Change to more realistic values.

### FREQUENCY SCALING



$$H(jw) = \frac{f(Z_C(jw), Z_L(jw), R)}{g(Z_C(jw), Z_L(jw), R)}$$

$\frac{1}{C_{010}}$ $Z_{C010} = \frac{1}{jwC_{010}}$ $Z_{C010}(j1) = \frac{1}{jC_{010}}$	$K_f = \frac{w_0(\text{NEW})}{w_0(\text{OLD})}$	$C_{\text{NEW}} = \frac{K_f}{C_{010}}$	$\frac{1}{C_{\text{NEW}}}$ $Z_{C\text{NEW}}(jK_f) = Z_{C010}(j1)$ $\frac{1}{jw_{\text{NEW}}C_{\text{NEW}}} = \frac{1}{jC_{010}(1)}$
--	---	--	---

$Z_L = jwL$ $Z_{L010} = jw_{010}L_{010}$ $Z_{L\text{NEW}} = jw_{\text{NEW}}L_{\text{NEW}}$ $= jK_f L_{\text{NEW}}$	$L_{\text{NEW}} = \frac{L_{010}}{K_f}$
---	--

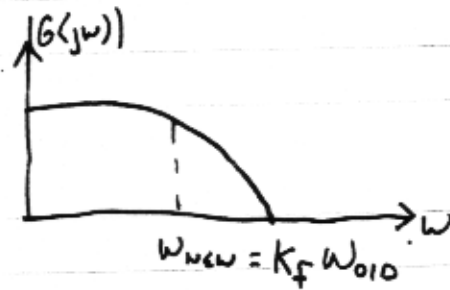
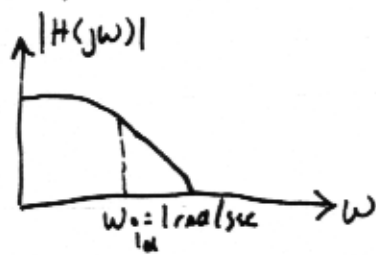
$R_{\text{NEW}} = R_{010}$  ← DOES NOT CHANGE WITH FREQUENCY

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# FREQUENCY SCALING

5/27/98



$L_{old} \sim \omega$   
 $C_{old} \sim \frac{1}{\omega}$   
 $R_{old} \sim \omega$

$$H(j\omega) = \frac{f(j\omega L_{old} \frac{1}{j\omega C_{old}} R_{old})}{g(j\omega L_{old} \frac{1}{j\omega C_{old}} R_{old})}$$

$$Z_{old}(L) = j\omega L_{old} \Big|_{\omega=1 \text{ rad/sec}} = j\omega L_{new} \Big|_{\omega=K_f \times 1}$$

$$L_{old} = K_f L_{new}$$

$$L_{new} = \frac{L_{old}}{K_f}$$

$K_f$  - frequency scaling factor (denormalization factor)

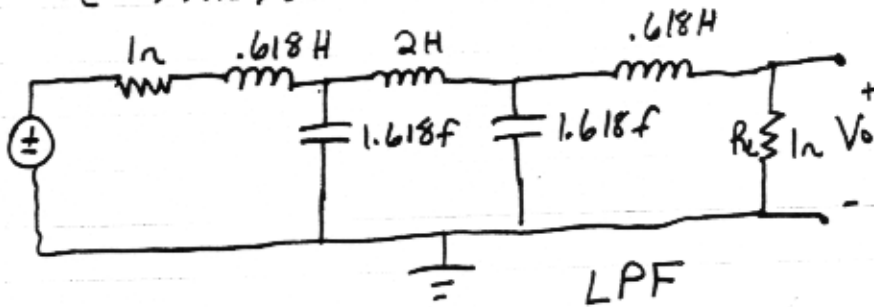
$$Z_{old}(C) = \frac{1}{j\omega C_{old}} \Big|_{\omega=1} = \frac{1}{j\omega C_{new}} \Big|_{\omega=K_f \times 1}$$

$$C_{new} = \frac{C_{old}}{K_f}$$

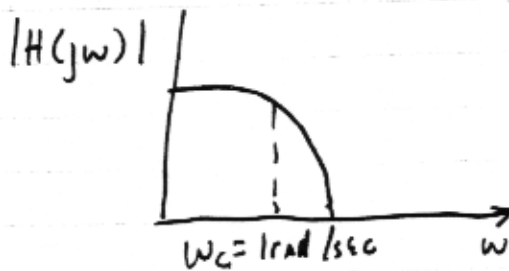
$$R_{new} = R_{old}$$

## EXAMPLE

$$\omega_c = 1 \text{ rad/sec}$$



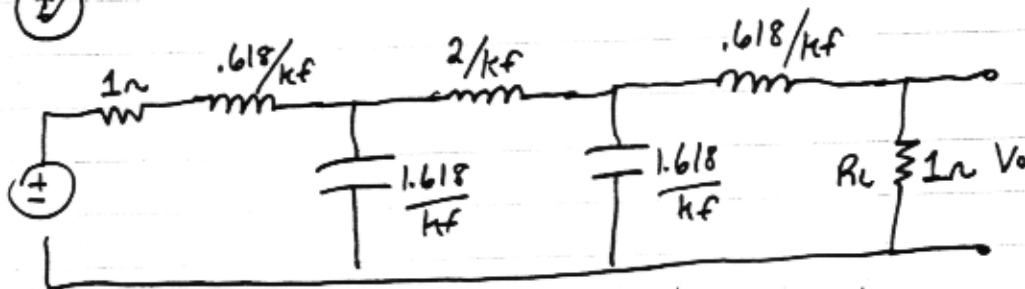
Denormalize the circuit such that  $\omega_c = 10^4 \text{ rad/sec}$



$$K_f = \frac{\omega_{c(\text{new})}}{\omega_{c(\text{old})}} = \frac{10^4}{1} = 10^4$$

$$\omega_{c(\text{new})} = \frac{\omega_{c(\text{old})}}{K_f} = \frac{1}{10^4} = 10^{-4}$$

$$C_{\text{new}} = \frac{C_{\text{old}}}{K_f}$$



Now we need to scale all values for practical values

$$Z_{\text{new}} = K_m Z_{\text{old}} \text{ at same } f_{\text{req}}$$

$$R_N \rightarrow K_m R_0$$

$$j\omega L_{\text{new}} \rightarrow K_m j\omega L_{\text{old}} \therefore L_N \rightarrow K_m L_{\text{old}}$$

$$\frac{1}{j\omega C_{\text{new}}} \rightarrow K_m \left( \frac{1}{j\omega C_{\text{old}}} \right) \therefore C_N \rightarrow \frac{C_{\text{old}}}{K_m}$$

If  $R_L$  must = 1k $\Omega$

then  $K_m = 1000$

$\therefore$  scale all component values

# PROTOTYPE CIRCUIT

$$\omega_c = 1 \text{ rad/sec}$$

$$K_f = \frac{\omega_c(\text{new})}{\omega_c(\text{old})}$$

$$R_{\text{NEW}} = K_m R_{\text{OLD}}$$

$K_m \equiv$  impedance scaling factor

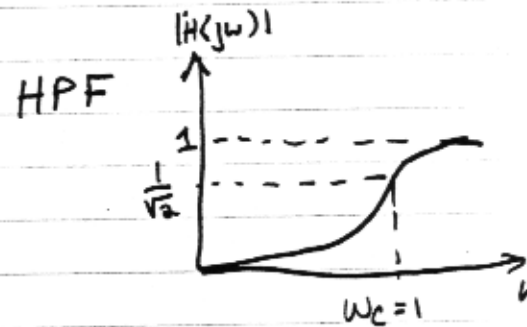
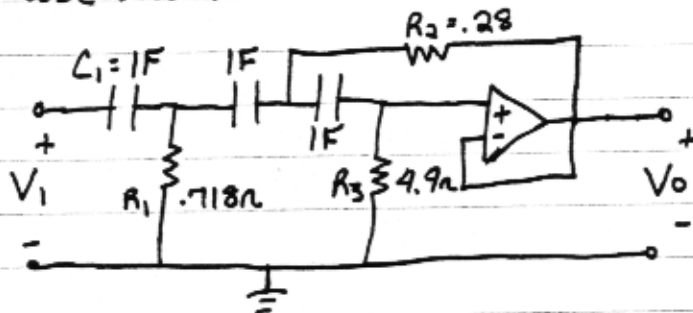
$$L_{\text{NEW}} = \frac{L_{\text{OLD}}}{K_f K_m}$$

$$C_{\text{NEW}} = \frac{C_{\text{OLD}}}{K_f K_m}$$

$$A_{\text{mp OLD}} = A_{\text{mp NEW}}$$

EXAMPLE:

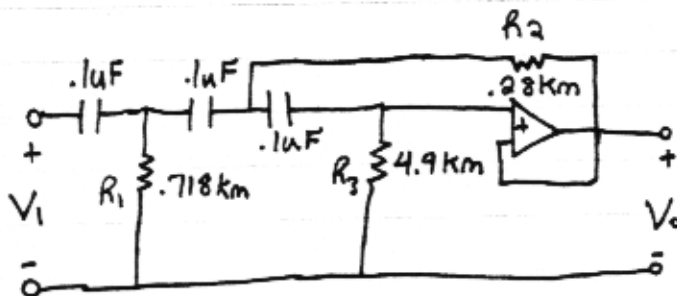
Design a third order HPF such that the 3db cutoff freq. is 200 Hz. given that only 0.1  $\mu$ F caps are available. CHOOSE AN ACTIVE REALIZATION.



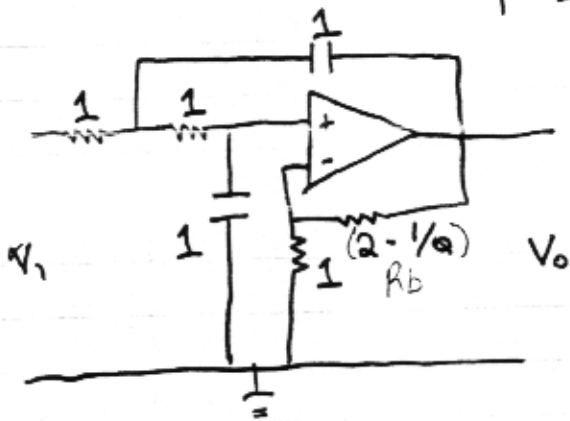
$$K_f = \frac{2\pi(200)}{1} = 4\pi \times 10^2$$

$$K_m \Rightarrow C_{\text{OLD}} \Rightarrow C_{\text{NEW}} \quad C_{\text{NEW}} = \frac{C_{\text{OLD}}}{K_f K_m}$$

$$K_m = \frac{1}{K_f \times .1 \times 10^{-6}} = 795$$



PSPICE it



$\Downarrow \omega_c = 1 \text{ rad/sec} \rightarrow \omega_{c\text{new}} = 2\pi \times 10^3$   
 with  $C = 10 \text{ nF}$   
 with  $Q = 0.707$

$\therefore K_F = 2\pi \times 10^3$   
 $K_m = 15915.5$

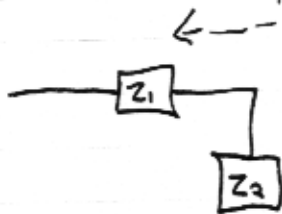
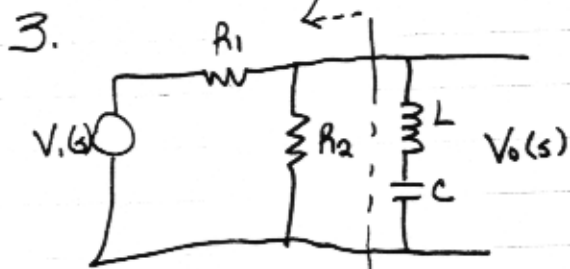
$C_N = \frac{C_0}{K_F K_m}$   
 $K_m = \frac{C_{old}/C_{new}}{K_F}$

$.000000010 = \frac{1}{2\pi \times 10^3 K_m}$

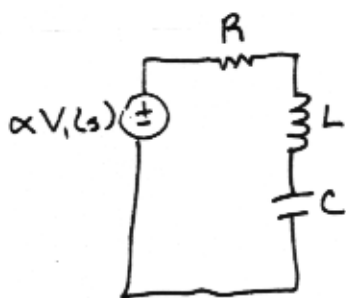
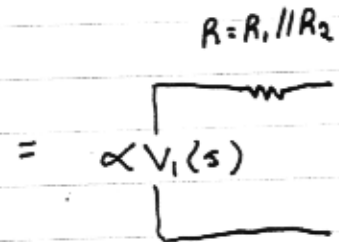
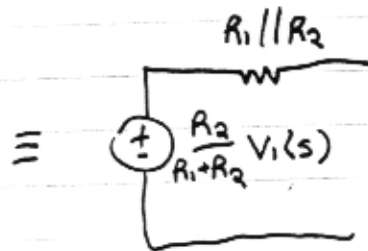
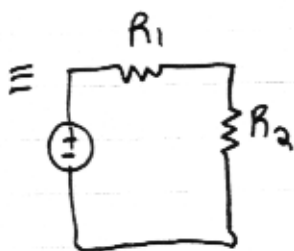
$R_{\text{new}} = 15915.5 \Omega$

$R_b = 9319.7 \Omega$

$H(s) = \frac{V_o(s)}{V_i(s)}$



$\frac{Z_2}{Z_1 + Z_2} = H(s)$  - ONE WAY

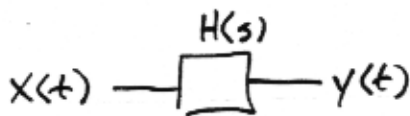


$\frac{V_o(s)}{\propto V_i(s)} = \frac{sL + \frac{1}{sC}}{sL + \frac{1}{sC} + R}$

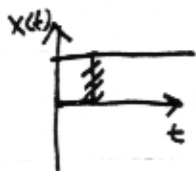
$\frac{K(s^2 + \omega_0^2)}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$

Notch Filter

$$K = \alpha = \frac{R_2}{R_1 + R_2} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$



$X(t)$  is a step function



$$X(s) = \text{LT}\{X(t)\}$$

$$Y(s) = \text{LT}\{Y(t)\}$$

$$\therefore H(s) = \frac{Y(s)}{X(s)} \quad \therefore Y(s) = H(s)X(s)$$

If  $X(t) = u(t)$

$$X(s) = \frac{1}{s}$$

$$Y(s) = \frac{2s}{s^2 + 2s + 100} \left( \frac{1}{s} \right) = \frac{2}{s^2 + 2s + 100}$$

$$\therefore Y(t) = \text{LT}^{-1} \left\{ \frac{2}{s^2 + 2s + 100} \right\}$$

$$Y(s) = \frac{A}{s - P_1} + \frac{B}{s - P_2} \quad P_1, P_2 \text{ poles or roots of } s^2 + 2s + 100 = 0$$

$$P_1 = -1 + j9.95 \quad P_2 = -1 - j9.95 = P_1^*$$

$$Y(s) = \frac{A}{s - P_1} + \frac{A^*}{s - P_1^*}$$

$$Y(t) = \text{LT}^{-1}\{Y(s)\} = \text{LT}^{-1}\left\{ \frac{A}{s - P_1} \right\} + \text{LT}^{-1}\left\{ \frac{A^*}{s - P_1^*} \right\}$$

$$= (Ae^{P_1 t} + A^* e^{P_1^* t}) u(t)$$

$$= 2 \text{real}\{Ae^{P_1 t}\} u(t) \quad A = |A| e^{j\phi_A}$$

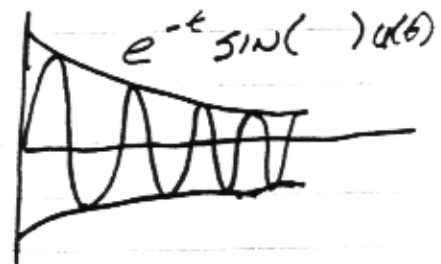
$$2 \operatorname{real} \{ |A| e^{j\phi} e^{P_1 t} \} u(t)$$

$$P_1 = \alpha + j\beta = -1 + j9.95$$

$$y(t) = 2 \operatorname{real} \{ |A| e^{j(\beta t + \phi)} e^{\alpha t} \} u(t) \quad \left( \operatorname{Real} e^{jx} = \cos x \right)$$

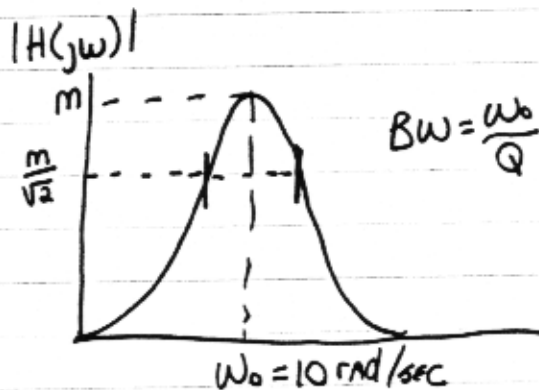
$$= 2 e^{\alpha t} |A| \{ \operatorname{real} e^{j(\beta t + \phi)} \} u(t)$$

$$= 2 |A| e^{\alpha t} \cos(\beta t + \phi) u(t)$$



$$H(s) = \frac{2s}{s^2 + 2s + 100} = \frac{Y(s)}{X(s)} \quad s^2 Y(s) + 2s Y(s) + 100 Y(s) = 2s X(s)$$

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 100 y(t) = \frac{dx(t)}{dt}$$



$$H(s) = \frac{M s \frac{\omega_0}{Q}}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2} \quad 2s = 2s \quad \therefore M = 1$$

$$M = 1 \quad \omega_0 = 10 \text{ rad/sec} \quad Q = 5$$

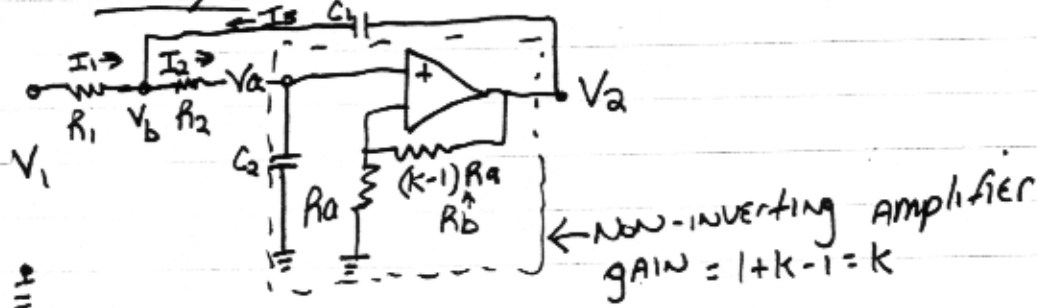
$$BW = 2 \text{ rad/sec}$$

# 2<sup>ND</sup> ORDER ACTIVE FILTERS USING A SINGLE OPAMP

6/1/98

## LOW PASS FILTER

EXAMPLE: THE Sallen & Key L.P.F.



$$\frac{V_2(s)}{V_1(s)} = H(s) = ?$$

ANALYSIS:

$$\frac{V_2}{V_a} = k \quad \therefore V_a = \frac{V_2}{k} \quad \text{--- (1)}$$

$$I_1 + I_3 = I_2 \quad I_1 = \frac{V_1 - V_b}{R_1} \quad I_3 = \frac{V_2 - V_b}{1/sC_1} \quad I_2 = V_a sC_2$$

$$\frac{V_1 - V_b}{R_1} + \frac{V_2 - V_b}{1/sC_1} = V_a sC_2 = \frac{V_1 - V_b}{R_1} + (V_2 - V_b) sC_1 = V_a sC_2 \quad \text{--- (2)}$$

$$\frac{V_a}{V_b} = \frac{\frac{1}{sC_2}}{\frac{1}{sC_2} + R_2} = \frac{1}{1 + sC_2 R_2} = \frac{V_a}{V_b} \quad \text{--- (3)}$$

From (3)

$$V_b = V_a (1 + sC_2 R_2)$$

$$V_b = \frac{V_2}{k} (1 + sC_2 R_2)$$

From ① ② + ④

$$\frac{V_2(s)}{V_1(s)} = \frac{K / (R_1 R_2 C_1 C_2)}{s^2 + \left( \frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2} - \frac{K}{R_2 C_2} \right) s + \frac{1}{R_1 R_2 C_1 C_2}}$$

2<sup>nd</sup> order LPF

$$\frac{K \omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$$

$$\omega_0^2 = \frac{1}{R_1 R_2 C_1 C_2}$$

$$\frac{\omega_0}{Q} = \frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} + \frac{1}{R_2 C_2} - \frac{K}{R_2 C_2}$$

DESIGN EQUATIONS

$$\therefore \omega_0 = \frac{1}{RC}$$

$$R_1 = R_2 = R \quad C_1 = C_2 = C$$

$$\frac{\omega_0}{Q} = \frac{3}{RC} - \frac{K}{RC} = \frac{(3-K)}{RC}$$

$$R_A = R$$

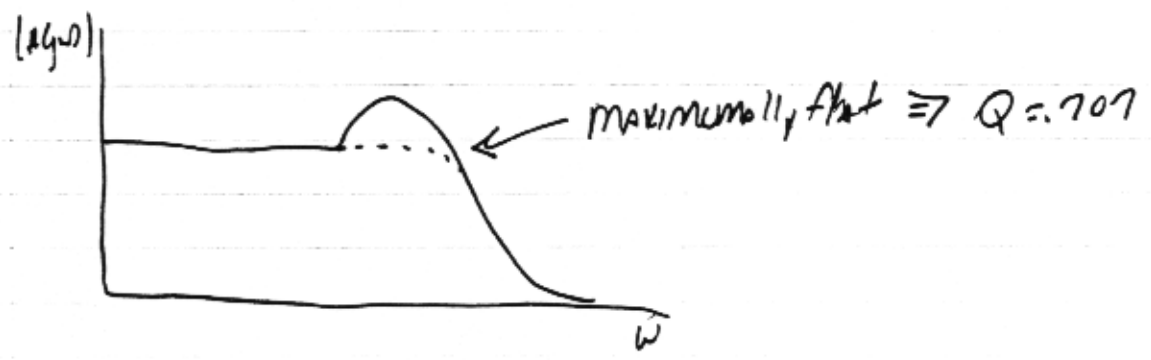
$$R_B = (K-1)R_A = 3 - \frac{1}{Q} - 1 = 2 - \frac{1}{Q} = R_B \quad \therefore Q = \frac{1}{(3-K)} \quad \therefore K = 3 - \frac{1}{Q}$$

Normalized circuit

$$\text{LET } \omega_0 = 1 \text{ rad/sec} \Rightarrow R = 1 \Omega \quad C = 1 \text{ F}$$

EXAMPLE:

DESIGN A SECOND ORDER LPF TO HAVE A MAXIMALLY FLAT MAG. RESPONSE + 3db cutoff freq. = 1 kHz GIVEN THAT C'S = 0.1 uF ARE THERE.





$$\omega_0 = 2\pi f_0 = 2\pi(1k) = 2\pi \times 10^3 \text{ rad/sec}$$

$$C_{\text{NEW}} = 0.1 \mu\text{F} \quad C_{\text{NEW}} = \frac{C_{\text{OLD}}}{K \cdot K_m} = \frac{1}{K \cdot K_m (20 \times 10^3)} \Rightarrow K_m = 1.5915 \times 10^3$$

$$R_{\text{NEW}} = K_m R_{\text{OLD}} = 1.5915 \times 10^3 \Omega \quad C = 0.1 \mu\text{F}$$

$$R_a = 1.5915 \times 10^3 \Omega$$

$$\uparrow R_b = 795.7 \Omega \quad \uparrow$$

Plug VALUES into old circuit.

$$K = 1.58$$

## DESIGN #2

$$\omega_0 = 1 \text{ rad/sec}$$

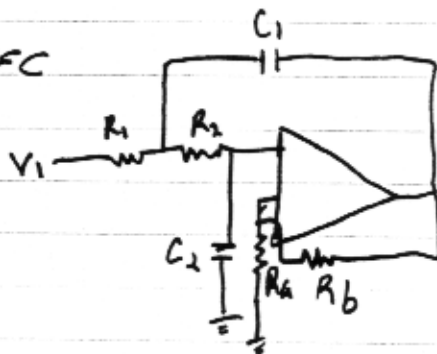
$$K = 1$$

$$R_1 = R_2 = 1 \Omega$$

$$Q = \frac{C_1}{2} \quad C_1 = 2Q$$

$$C_1 C_2 = 1$$

$$\therefore C_2 = \frac{1}{2Q}$$



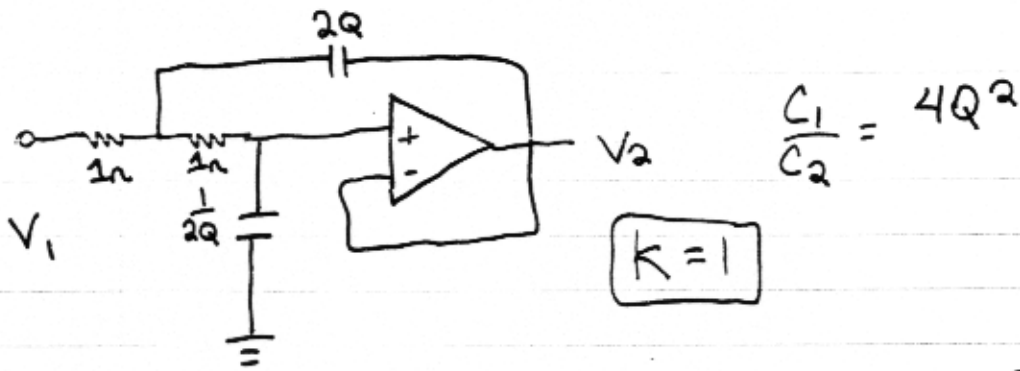
$$\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

$$\frac{\omega_0}{Q} = \frac{1}{R_2 C_1} + \frac{1}{R_1 C_1} + \frac{1}{R_2 C_2} - \frac{K}{R_2 C_2}$$

$$\frac{\omega_0}{Q} = \frac{1}{R_1 C_1} + \frac{1}{R_2 C_1} = \frac{1}{Q}$$

$$\omega_0 = \frac{1}{\sqrt{C_1 C_2}} = 1$$

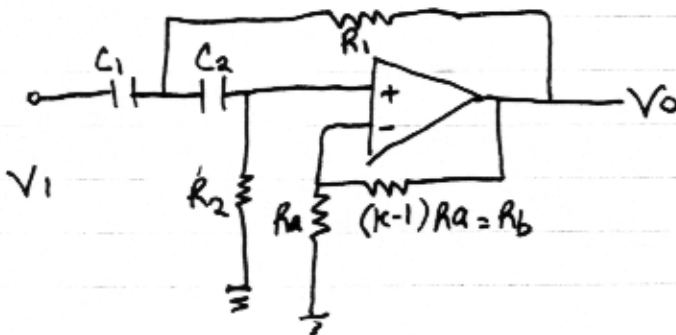
$$\frac{1}{2Q} = \frac{1}{C_1}$$



DESIGN #3  $\omega_0 = 1 \text{ rad/sec}$

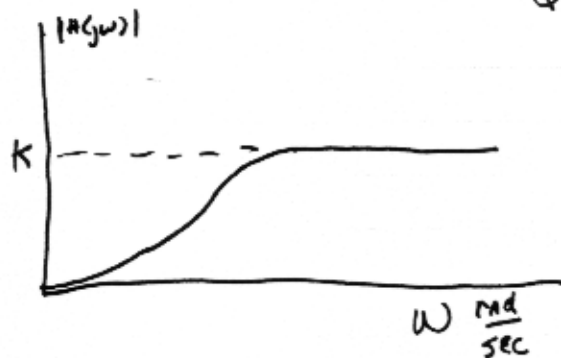
$$\frac{C_1}{C_2} = Q \quad \frac{R_2}{R_1} = Q \quad H(s) = \frac{V_2(s)}{V_1(s)} = \frac{2}{s^2 + \frac{s}{Q} + 1}$$

Sallen & Key HPF DESIGN

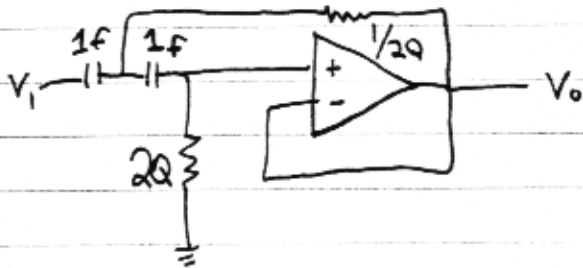


DESIGN #1: Equal R + Equal C  $\omega_0 = 1 \text{ rad/sec}$

$$R_2 = 1\Omega \quad R_a = 1\Omega \quad R_b = 2 - \frac{1}{Q}\Omega \quad C_1 = C_2 = 1\text{f} \quad R_1 = 1\Omega$$



DESIGN #2  
UNITY GAIN ( $k=1$ )



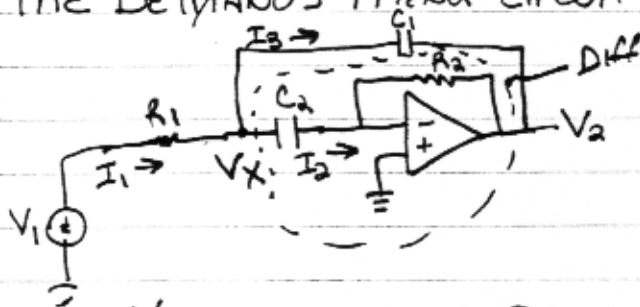
DESIGN #3

$$R_1 = 1\Omega \quad k=2 \quad C_1 = 1f \quad C_2 = \frac{1}{Q}f \quad R_2 = Q\Omega$$

$$R_A = R_B = 1\Omega$$

BANDPASS Filter

THE DELYANUS-FRIEND Circuit



$$\frac{V_2(s)}{V_1(s)} = H(s)$$

$$\frac{V_2}{V_X} = -sC_2R_2 \quad (-1)$$

$$V_X = \frac{-V_2}{sC_2R_2} \quad (-1)$$

KCL to Node X

$$I_1 = I_2 + I_3$$

$$\frac{V_1 - V_X}{R_1} = \frac{V_X sC_2 + (V_X - V_2) sC_1}{1} \quad (-2)$$

$$\frac{V_2(s)}{V_1(s)} = \frac{-\frac{1}{R_1 C_1} (s)}{s^2 + \frac{1}{R_2} \left( \frac{1}{C_1} + \frac{1}{C_2} \right) s + \frac{1}{R_1 R_2 C_1 C_2}}$$

$$C_1 = C_2 = C \quad \omega_0^2 = \frac{1}{R_1 R_2 C_1 C_2} \Rightarrow \omega_0 = \frac{1}{C \sqrt{R_1 R_2}}$$

$$\frac{\omega_0}{Q} = \frac{2}{R_2 C} \quad Q = \frac{1}{\frac{2}{\sqrt{R_1 R_2}}} \Rightarrow Q = \frac{\sqrt{R_2}}{2\sqrt{R_1}}$$

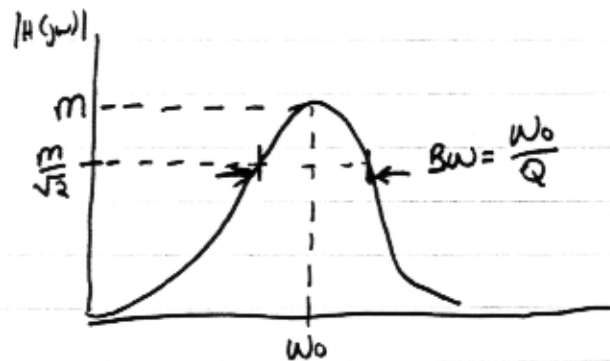
Let  $\omega_0 = 1 \frac{\text{rad}}{\text{sec}}$  ~~BPF =  $\frac{1}{s^2 + 2s + 1}$~~   $1 = \frac{1}{C \sqrt{R_1 R_2}} \therefore C = \frac{1}{\sqrt{R_1 R_2}}$

$$R_1 = 1 \Omega \therefore R_2 = 4Q^2 \Omega \therefore C = \frac{1}{2Q}$$

Normalized Circuit  $\Rightarrow \omega_0 = 1 \frac{\text{rad}}{\text{sec}}$

$$H(s) = \frac{-M \frac{\omega_0}{Q} s}{s^2 + \frac{2\omega_0}{Q} s + \omega_0^2}$$

Inverting BPF



$$H(s) = \frac{-\frac{1}{R_1 C_1} s}{s^2 + \frac{2}{R_2 C} s + \frac{1}{R_1 R_2 C^2}}$$

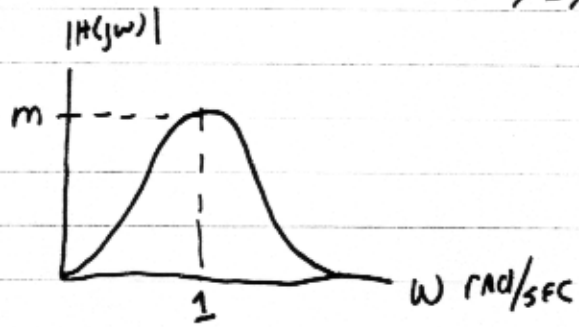
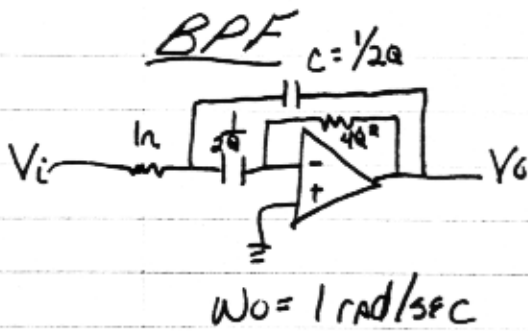
$$M \frac{\omega_0}{Q} = \frac{\omega_0}{Q}$$

$$\frac{-1}{R_1 C_1} = \frac{2}{R_2 C}$$

$$m - R_2 \omega_0 = 2 R_1 \omega_0 \quad m = \frac{R_2}{2 R_1}$$

$$\text{But } Q = \frac{1}{2} \sqrt{\frac{R_2}{R_1}} \therefore m = 2Q^2$$

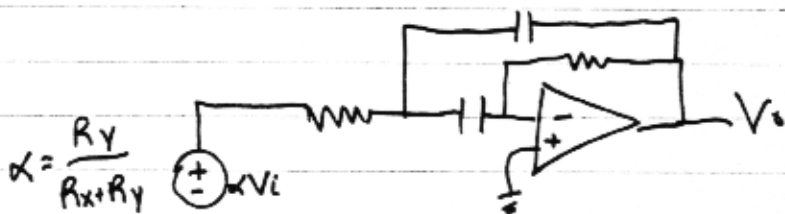
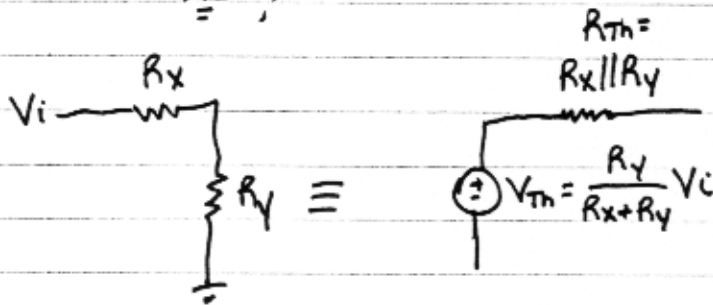
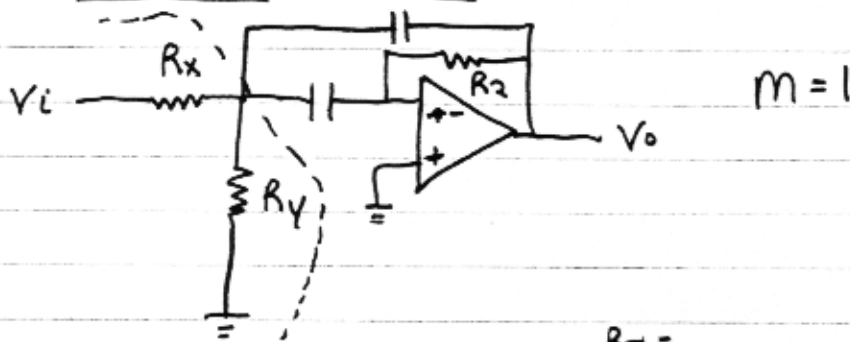
6/3/98



$$H(s) = \frac{-\frac{m}{Q} s}{s^2 + \frac{s}{Q} + 1}$$

$$m = 2Q^2$$

Modified Circuit



$$R_{Th} = 1 \Omega \quad \frac{R_x R_y}{R_x + R_y} = 1 \quad \text{--- (1)}$$

$$\frac{V_o}{\alpha V_i} = \frac{-\frac{2Q^2}{Q} s}{s^2 + \frac{s}{Q} + 1}$$

$$= \frac{-2Qs}{s^2 + \frac{s}{Q} + 1}$$

$$\frac{V_o}{V_i} = \frac{-\alpha 2Qs}{s^2 + \frac{s}{Q} + 1}$$

$$\text{At } \omega_0 = 1 \quad \left| \frac{V_0}{V_i} \right| = \alpha 2Q^2 = 1$$

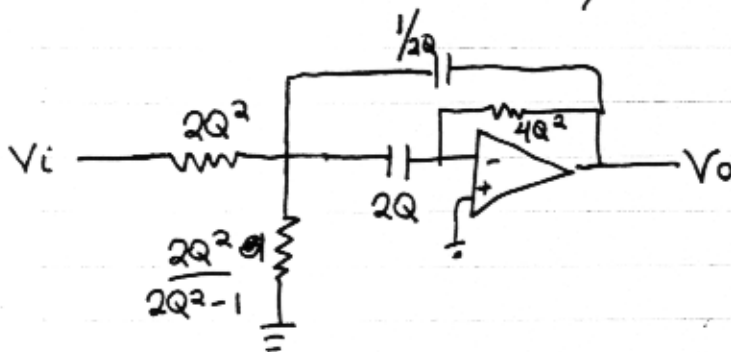
$$\therefore \alpha = \frac{1}{2Q^2} = \frac{R_Y}{R_X + R_Y} \quad \text{--- (2)}$$

- Using 1 & 2 we find  $R_X \times R_Y$  -

$$\text{From 2} \quad \frac{1}{2Q^2} = \frac{1}{1 + \frac{R_X}{R_Y}} \quad \text{Find } \frac{R_X}{R_Y}$$

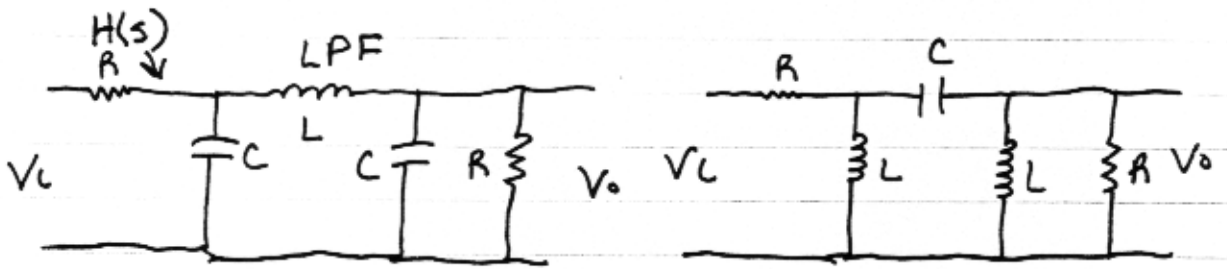
$$\text{From 1} \quad \frac{R_X}{1 + \frac{R_X}{R_Y}} = 1 \Rightarrow \text{Get } R_X$$

$$\therefore R_X = 2Q^2 \quad R_Y = \frac{2Q^2}{2Q^2 - 1}$$



$$H(s) = \frac{-s/Q}{s^2 + s/Q + 1}$$

# Filter Transformation



Transformation

$$G(s) = H(s) \Big|_{s = \frac{\omega_0}{s}}$$

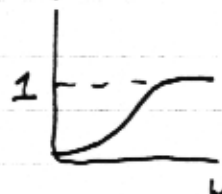
## Example

$$H(s) = \frac{1}{s+1}$$



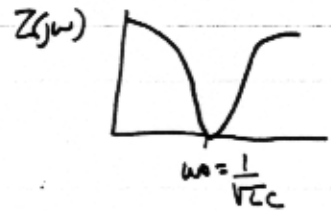
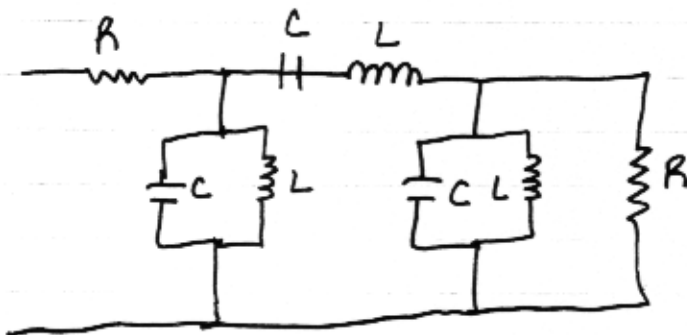
1st order LPF

$$G(s) = H(s) \Big|_{s = \frac{1}{s}} = \frac{1}{\frac{1}{s} + 1} = \frac{s}{s+1}$$

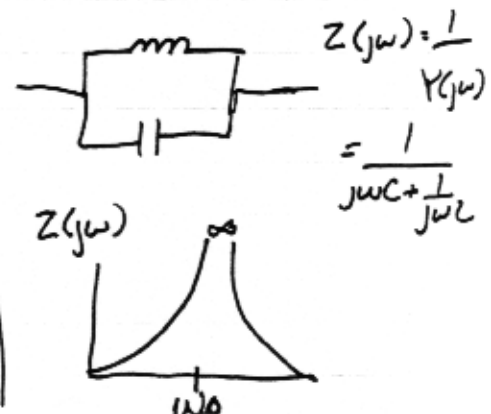
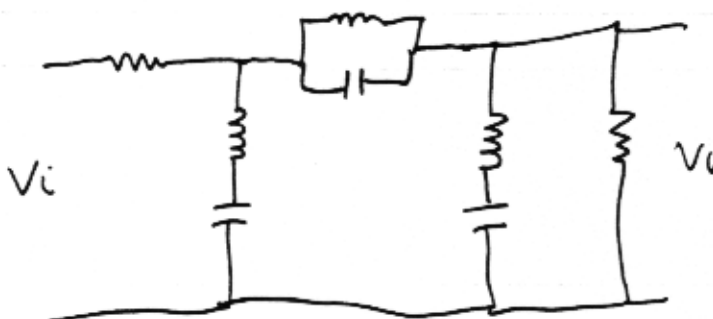


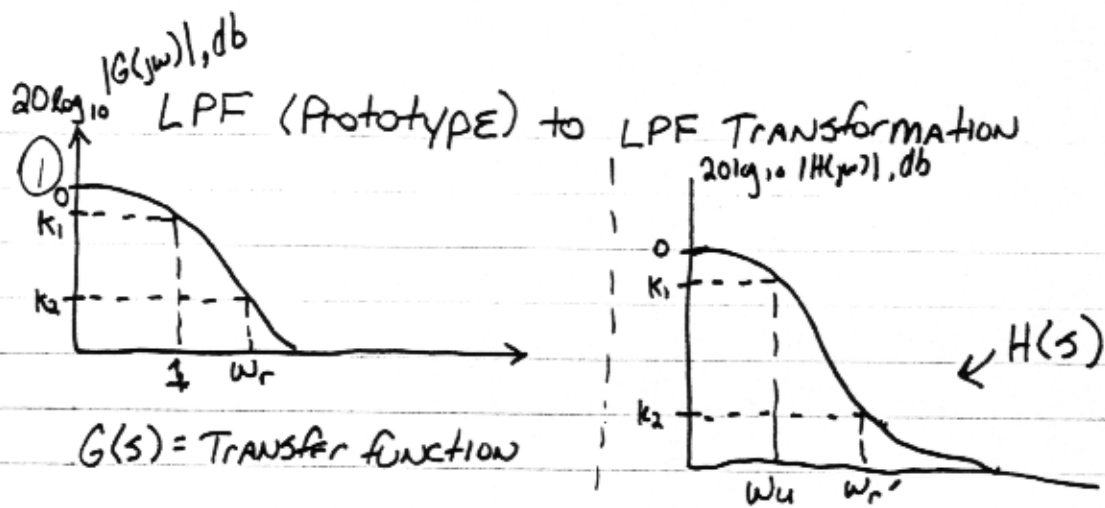
1st order HPF

BPF



Notch





$$H(s) = G(s) \Big|_{s = \frac{s}{\omega_u}}$$

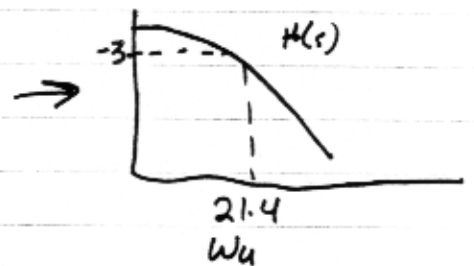
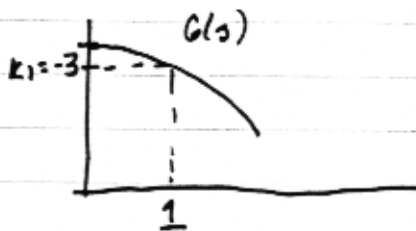
DESIGN EQUATIONS

GIVEN: Normalized

$$\omega_r' = \omega_u \omega_r$$

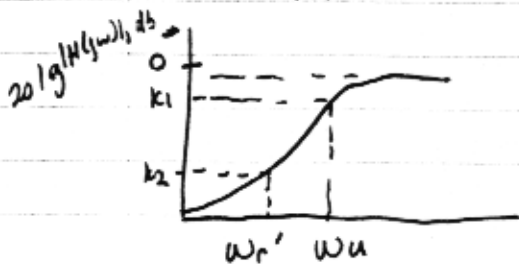
$$(s^2 + 0.765s + 1)(s^2 + 1.85s + 1)$$

$$\omega_r = \frac{\omega_r'}{\omega_u}$$



$$H(s) = G(s) \Big|_{s = s/\omega_u \Rightarrow s = s/21.4}$$

LPF  $\Rightarrow$  HPF



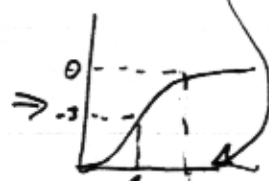
$$H(s) = G(s) \Big|_{s = \frac{\omega_u}{s}}$$

DESIGN EQUATIONS:

$$\omega_r' = \frac{\omega_u}{\omega_r}$$

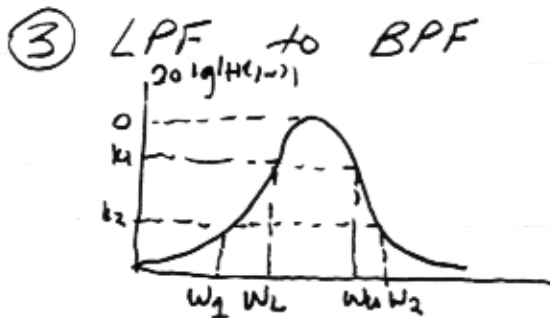
$$\omega_r = \frac{\omega_u}{\omega_r'}$$

Ex  $G(s) = \frac{1}{s^3 + 2s^2 + 2s + 1}$



$$H(s) = G(s) \Big|_{s = \frac{\omega_u}{s}} = \frac{1}{s}$$





$$H(s) = G(s) \Big|_s = \frac{s^2 + w_L w_u}{s(w_u - w_L)} = \frac{s^2 + w_0^2}{s b_w}$$

$$w_0 = \sqrt{w_L w_u} \quad b_w = w_u - w_L$$

### DESIGN EQUATIONS

$$w_{AV} = (w_u - w_L) / 2$$

$$w_0 = 2 \quad w_L = 1 \quad w_u = 2$$

$$w_1 = (w_0^2 w_{AV}^2 + w_L w_u)^{1/2} - w_{AV} w_r$$

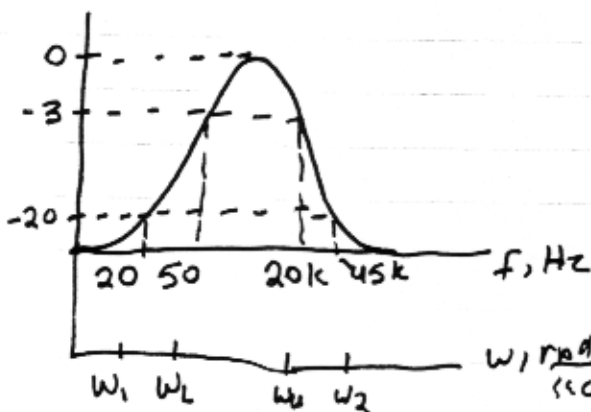
$$w_r = 1$$

$$w_2 = (w_0^2 w_{AV}^2 + w_L w_u)^{1/2} + w_{AV} w_r$$

$$w_r = \min\{|A|, |B|\} \text{ - minimum of either}$$

$$\text{WHERE } A = \frac{-w_1^2 + w_L w_u}{w_1 (w_u - w_L)} \quad + \quad B = \frac{w_2^2 - w_L w_u}{w_2 (w_u - w_L)}$$

### EXAMPLE:



$$w_1 = 2\pi(20)$$

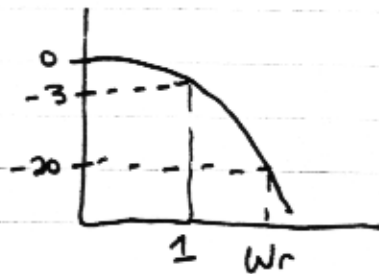
$$w_L = 2\pi(50)$$

$$w_u = 2\pi(20k)$$

$$w_2 = 2\pi(45k)$$

BPF  $\rightarrow$  LPF - BACKWARD DESIGN EQ.

CONTINUED!



$$\omega_r = 2.254 \text{ rad/sec}$$

Design the prototype LPF

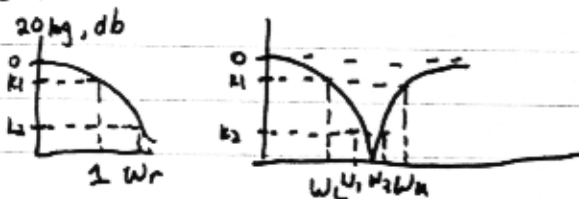
Ex | Use a Butterworth Approx.  $N=3$

$$G(s) = \frac{1}{s^2 + 2.5s + 2.5}$$

→ Apply LPF to BPF Transformation

$$H(s) = G(s) \Big|_s = \frac{s^2 + \omega_c \omega_L}{s(\omega_u - \omega_L)} = \frac{s^2 + 3.94784 \times 10^7}{s(1.25349 \times 10^5)}$$

#### ④ LPF to Notch X-formation



$$H(s) = G(s) \Big|_s = \frac{s(\omega_u - \omega_L)}{s^2 + \omega_c \omega_u}$$

#### DESIGN EQUATIONS

For  $\omega_c = \omega_{AV} (\omega_u - \omega_L) / 2$

$$\omega_1 = \left[ (\omega_{AV} / \omega_r)^2 + \omega_L \omega_u \right]^{1/2} - \frac{\omega_{AV}}{\omega_r}$$

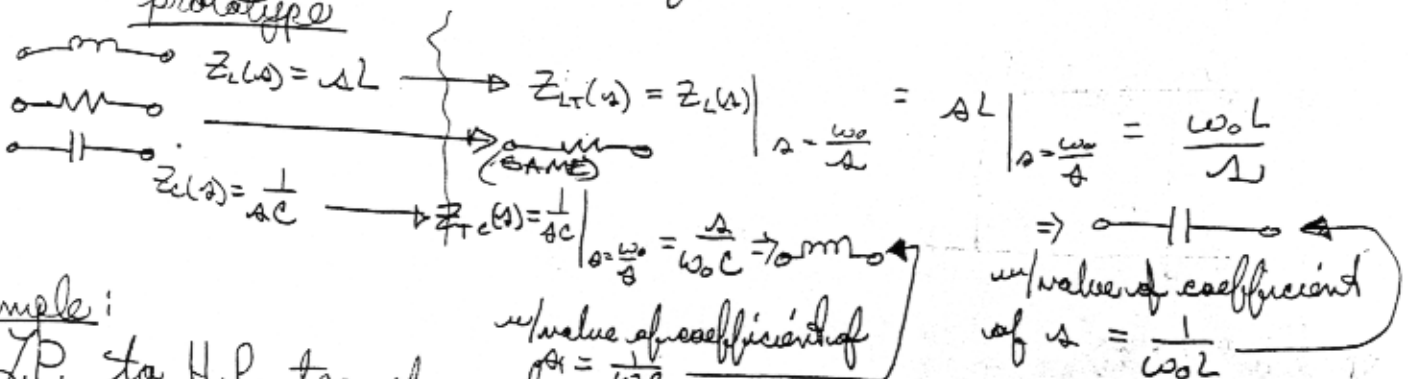
$$\omega_2 = \left[ (\omega_{AV} / \omega_r)^2 + \omega_L \omega_u \right]^{1/2} + \frac{\omega_{AV}}{\omega_r}$$

Back |  $\omega_r = \min\{|A|, |B|\}$

$$A = \frac{\omega_1 (\omega_u - \omega_L)}{-\omega_1^2 + \omega_L \omega_u}$$

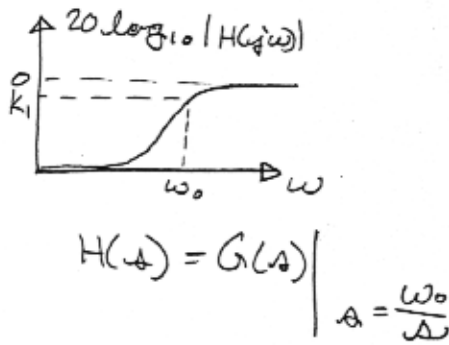
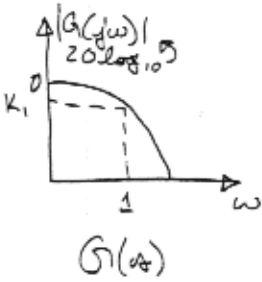
$$B = \frac{\omega_2 (\omega_u - \omega_L)}{-\omega_2^2 + \omega_L \omega_u}$$

Applying the transformation directly on the circuit elements.

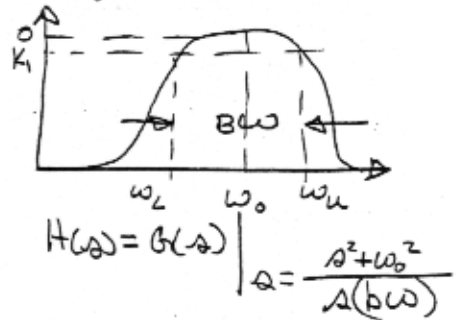


Example:

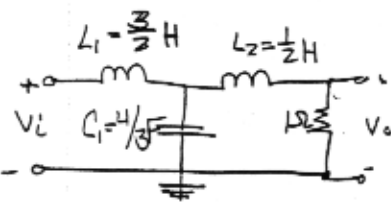
L.P. to H.P. transformation



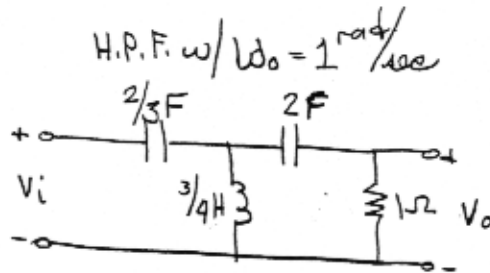
B.P.F. for below:



Example: Transform the given prototype 3rd order L.P.F. into a prototype 3rd order H.P.F.

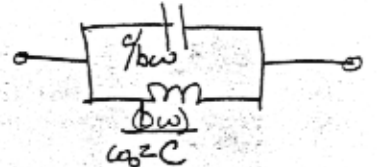


(Prototype L.P.F.)



Example: Transform L.P.F. to B.P.F.

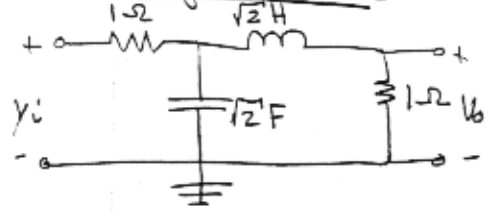
$(s) \rightarrow Z_{LT}(s) = sL \Big|_{s = \frac{s^2 + \omega_0^2}{s(b\omega)}} = \frac{s^2 + \omega_0^2}{s(b\omega)} L = \frac{L}{b\omega} s + \frac{\omega_0^2 L}{b\omega s} = \left( \frac{L}{b\omega} \right) + \left( \frac{b\omega}{\omega_0^2 L} \right)$   
 $(s) \rightarrow Z_{TC}(s) = \frac{1}{sC} \Big|_{s = \frac{s^2 + \omega_0^2}{s(b\omega)}} = \frac{s(b\omega)}{(s^2 + \omega_0^2) C} = \frac{Y(s)}{Z_{TC}(s)} = \frac{1}{s(b\omega)} = \frac{(s^2 + \omega_0^2) C}{s(b\omega)} = \left( \frac{sC}{b\omega} \right) + \left( \frac{\omega_0^2 C}{s(b\omega)} \right)$



Example: Given the prototype L.P.F. (normalized) circuit of a 2nd order Butterworth L.P.F., apply a L.P. to B.P. transformation

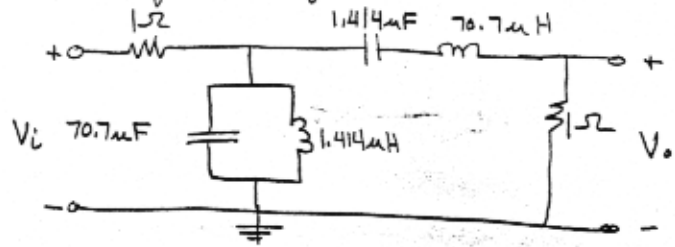
such that  $\omega_0(BP) = 100k \text{ rad/sec}$  and  $bw = 20k \text{ rad/sec}$

Original L.P.F.



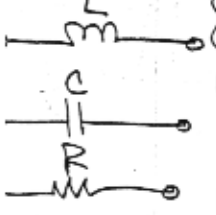
(prototype L.P.F.)

Transformed filter (B.P.F.)



P. to Band stop (notch) transformation:

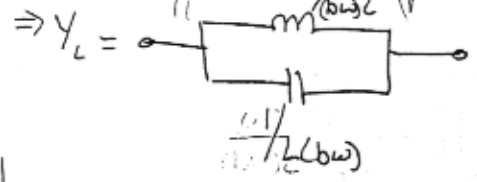
Prototype circuit composed of:



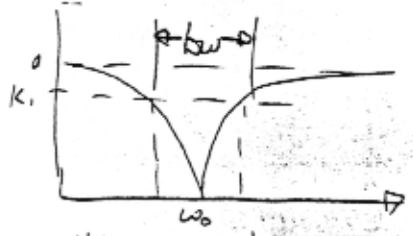
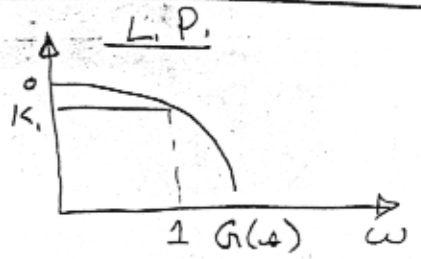
Transformed circuit components:

$$Z(s) = sL \Rightarrow Z_{LT}(s) \Big|_{s = \frac{j(bw)}{\omega^2 + \omega_0^2}} \Rightarrow Z_{LT}(s) = \frac{s(bw)L}{s^2 + \omega_0^2}$$

$$\Rightarrow Y_{LT}(s) = \frac{s^2 + \omega_0^2}{s(bw)L} = \frac{s}{s(bw)L} + \frac{\omega_0^2}{s(bw)L}$$



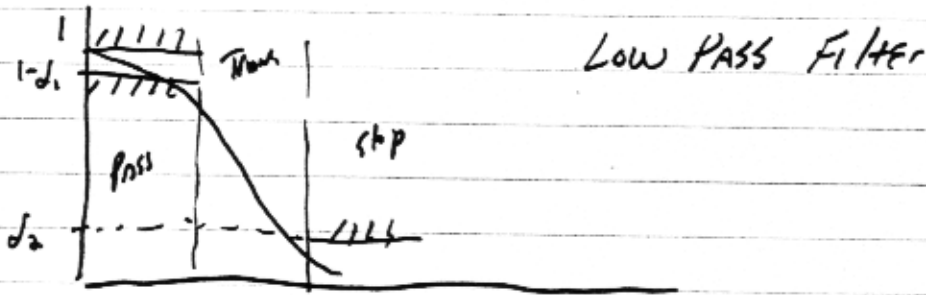
$$Y(s) = \frac{1}{sC} \Rightarrow Z_{TC}(s) \Big|_{s = \frac{j(bw)}{\omega^2 + \omega_0^2}} \Rightarrow Z_{TC}(s) = \frac{C}{bw} + \frac{bw}{C(\omega^2 + \omega_0^2)}$$



$$H(s) = G(s) \Big|_{s = \frac{j(bw)}{\omega^2 + \omega_0^2}}$$

# FILTER DESIGN

## Butterworth Approx

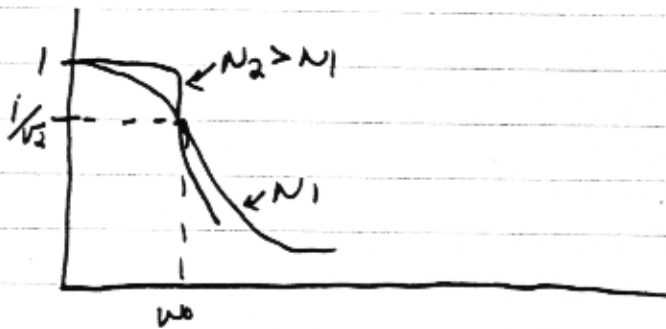


$$|H_N(j\omega)| = \frac{1}{\sqrt{1 + \left(\frac{\omega}{\omega_0}\right)^{2N}}$$

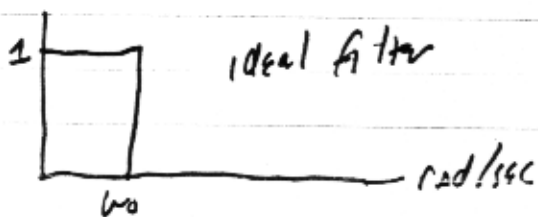
order

$N$ : order

$\omega_0$  = 3dB cutoff or bandwidth



As  $N \rightarrow \infty$



$$\begin{aligned} \omega < \omega_0 \\ |H_N(j\omega)| &= 1 \\ N &\rightarrow \infty \\ \omega > \omega_0 \\ H_N(j\omega) &= 0 \end{aligned}$$

- 1 -  $H_N(j\omega) = 1$  for all  $N$
  - 2 -  $H_N(j\omega) = 1/\sqrt{2}$
  - 3 -  $\frac{d^k |H_N(j\omega)|}{d\omega^k} \Big|_{\omega=\omega_0} = 0$   
for  $k = 2, 3, \dots, 2N-1$
- MAXIMALLY FLAT RESPONSE

## FINDING THE TRANSFER FUNCTION $H_N(s)$

$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\frac{\omega}{\omega_0})^{2N}}}$$

$$\frac{1}{s^2 + 1}$$

$$H_N(s)H_N(-s) = |H(j\omega)|^2 \Big|_{\omega = s/j}$$

$$= \frac{1}{1 + (\frac{\omega}{\omega_0})^{2N}} \Big|_{\omega = s/j}$$

$$= \frac{1}{1 + (\frac{s}{j})^{2N}} \Big|_{\omega = s/j}$$

Consider the normalized case  
 $\therefore \omega_0 = 1 \text{ rad/sec}$

$$\therefore H_N(s)H_N(-s) = \frac{1}{1 + (-1)^N s^{2N}} \rightarrow j^{2N} = (j^2)^N = (-1)^N \leftarrow$$

$$\begin{aligned} H(s) &= \frac{1}{s+1} \\ H(j\omega) &= H(s) \Big|_{s=j\omega} \\ &= \frac{1}{1+j\omega} \end{aligned}$$

$$\begin{aligned} |H(j\omega)|^2 &= H(j\omega)H^*(j\omega) \\ &= H(j\omega)H(-j\omega) \\ &= H(s)H(-s) \Big|_{s=j\omega} \\ \therefore H(s)H(-s) &= |H(j\omega)|^2 \Big|_{\omega = s/j} \end{aligned}$$

## FIND THE POLES:

$$1 + (-1)^N s^{2N} = 0 \quad N=1 \quad 1 + (-1)s^2 = 1 - s^2 \quad s = \pm 1$$

$$\therefore H_{N=2}(s)H_1(-s) = \left(\frac{1}{s+1}\right) \left(\frac{1}{s-1}\right) \text{ unstable}$$

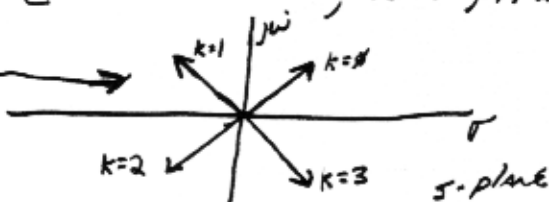
$$H_1(s) = \left(\frac{1}{s+1}\right)$$



$$1 + (-1)^N s^{2N} = 0 \quad N=2 \quad 1 + (1)s^4 = 1 + s^4 = 0 \Rightarrow s^4 = -1$$

$$s_4 = e^{j(\pi + 2k\pi)/4}, \quad k=0, 1, 2, 3$$

All have  
 mag = 1



$$\begin{aligned} k=0 \quad s &= e^{j\pi/4} \\ k=1 \quad s &= e^{j(\pi/4 + \pi/2)} \\ k=1 \text{ \& } k=2 & \text{ ARE STABLE} \end{aligned}$$

$k=0, 1, 2, 3$

$$H(s) = \frac{1}{(s - e^{j3\pi/4})(s - e^{-j3\pi/4})}$$

$$e^{j\frac{3\pi}{4}} = -0.707 + j.707$$

$$= \frac{1}{s^2 + \sqrt{2}s + 1}$$

$\sqrt{2}$  is from

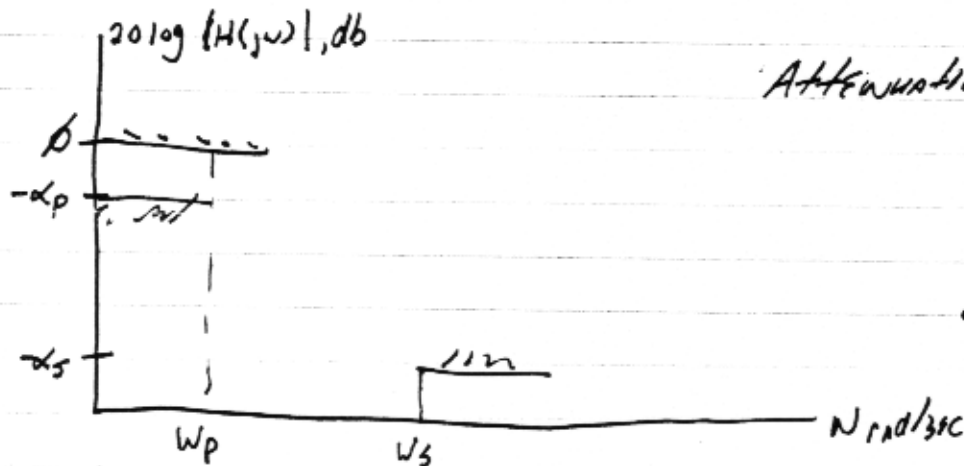
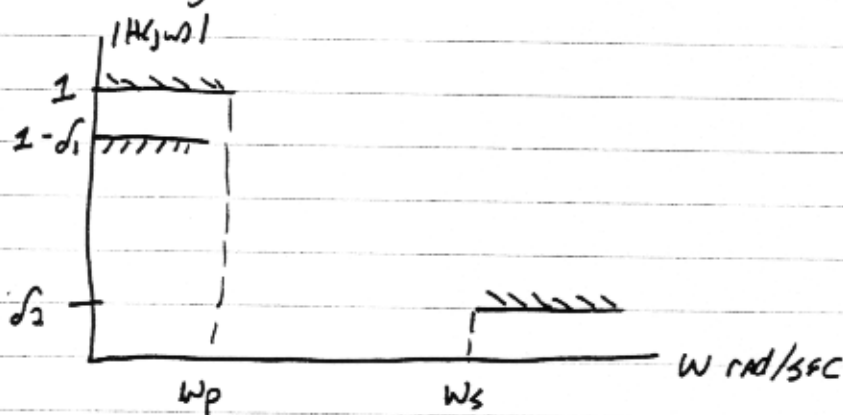
$$2 \cdot \frac{1}{\sqrt{2}} = \sqrt{2}$$

If  $N=3$

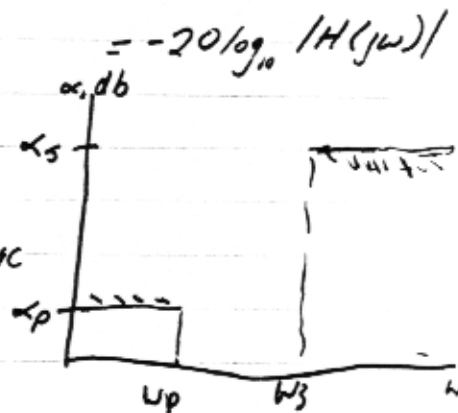
$$H_3(s) = \frac{1}{s+1} \frac{1}{s^2+s+1}$$

All poles are on page 165-166 in book.

### DESIGN EQUATIONS



$$\text{Attenuation in db} = 20 \log \left| \frac{V_i}{V_o} \right| = -20 \log_{10} |H(j\omega)|$$



NEED to find  $N = ?$  order  
 $\omega_0 = ?$  cutoff

$$\alpha = -20 \log_{10} |H(j\omega)| = -20 \log_{10} \frac{1}{\sqrt{1 + (\frac{\omega}{\omega_0})^{2N}}}$$

$$\alpha = 10 \log_{10} \left\{ 1 + \left(\frac{\omega}{\omega_0}\right)^{2N} \right\}$$

→  $\alpha = \alpha_p$  @  $\omega = \omega_p$  ←  
 $\alpha_p = 10 \log_{10} \left\{ 1 + \left(\frac{\omega_p}{\omega_0}\right)^{2N} \right\}$  (1)

$\frac{\alpha}{10} = \log_{10} \left\{ 1 + \left(\frac{\omega}{\omega_0}\right)^{2N} \right\}$   
 $10^{\alpha/10} = 1 + \left(\frac{\omega}{\omega_0}\right)^{2N}$

$\left[ \frac{\omega_0 = \omega}{[10^{\alpha/10} - 1]^{1/2N}} \right]$  GENERAL

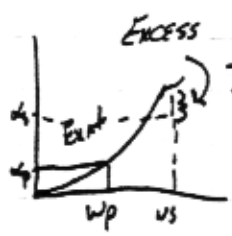
ceil → ∞  
 fix → -∞  
 round →

$\omega_0 = \frac{\omega_p}{[10^{\alpha_p/10} - 1]^{1/2N}}$  (1) Rewritten

→  $\alpha = \alpha_s$  @  $\omega = \omega_s$  ←

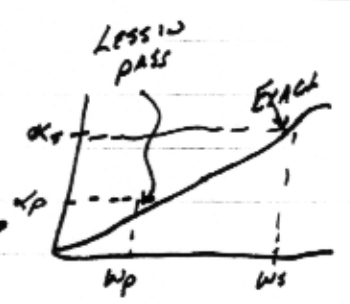
$\omega_0 = \frac{\omega_s}{[10^{\alpha_s/10} - 1]^{1/2N}}$  (2)

$N = \frac{\log \left\{ \frac{10^{\alpha_s/10} - 1}{10^{\alpha_p/10} - 1} \right\}}{2 \log \frac{\omega_s}{\omega_p}}$  Ex:  $N=2$   
 $\therefore N=3$



TAKE (1) to find  $\omega_0$

TAKE (2) to find  $\omega_0$



Example: Design Butterworth LPF with  $\omega_p = 1000 \text{ rad/sec}$   $\alpha_p = 5 \text{ dB}$   
 $\omega_s = 2000 \text{ rad/sec}$   $\alpha_s = 20 \text{ dB}$

Find N of filter using Eq.  $N=5$

Find  $\omega_0$  using Eq. (1)  $\omega_0 = 1263.2 \text{ rad/sec}$   
 Eq. (2)  $\omega_0 = 1234 \text{ rad/sec}$

Realizing the filters



ACTIVE

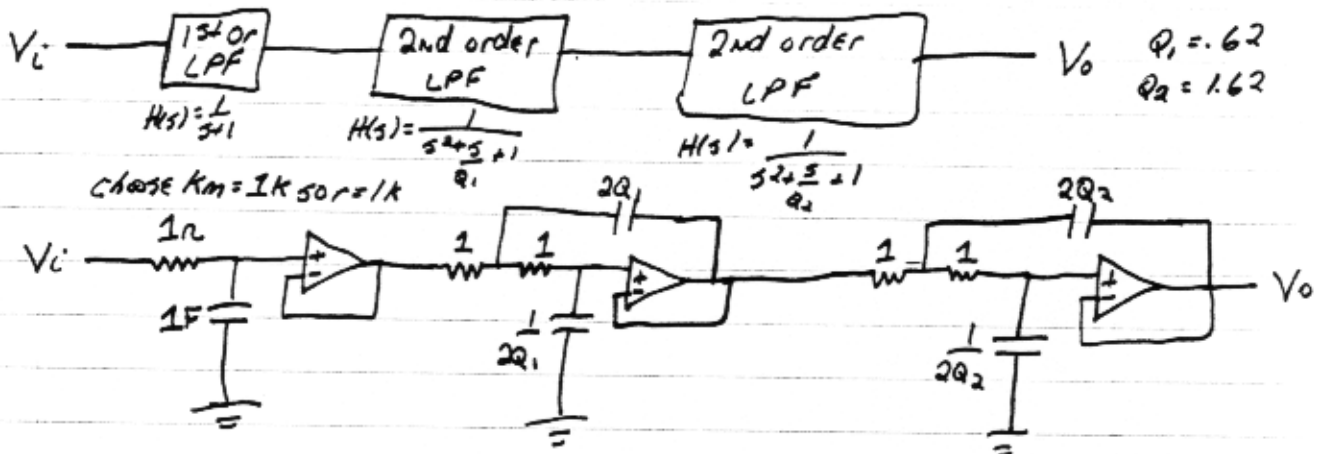
USE TABLE pg. 166 for N odd (NORMALIZED) ( $\omega_0 = 1$ )

$$H(s) = \frac{1}{(s+1)(s^2 + \frac{s}{Q_1} + 1)(s^2 + \frac{s}{Q_2} + 1)}$$

for N EVEN

$$H(s) = \frac{1}{(s^2 + \frac{s}{Q_1} + 1)(s^2 + \frac{s}{Q_2} + 1)}$$

normalized  $H(s) = \left( \frac{1}{s+1} \right) \left( \frac{1}{s^2 + \frac{s}{0.62} + 1} \right) \left( \frac{1}{s^2 + \frac{s}{1.62} + 1} \right)$  WHERE  $\omega_0 = 1 \text{ rad/sec}$



Now WE NEED TO FREQUENCY SCALE

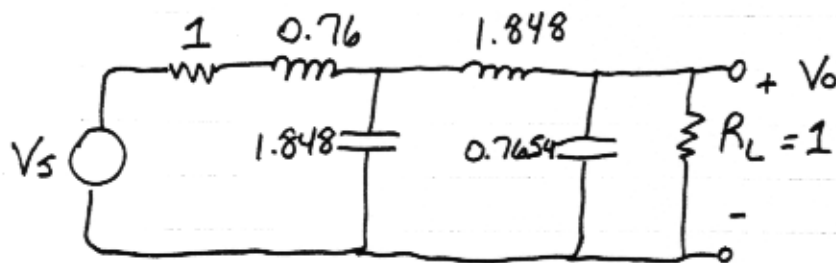
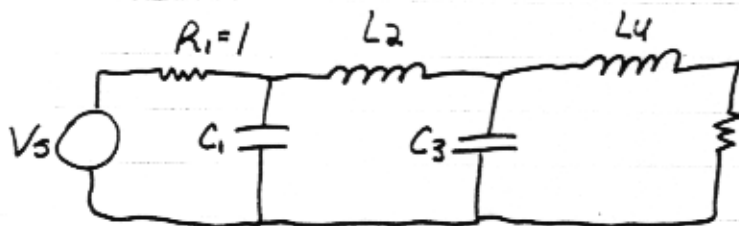
$K_f = \omega_0 = 1234 \text{ rad/sec}$  or  $1263.2 \text{ rad/sec}$   
for all stages

Example:

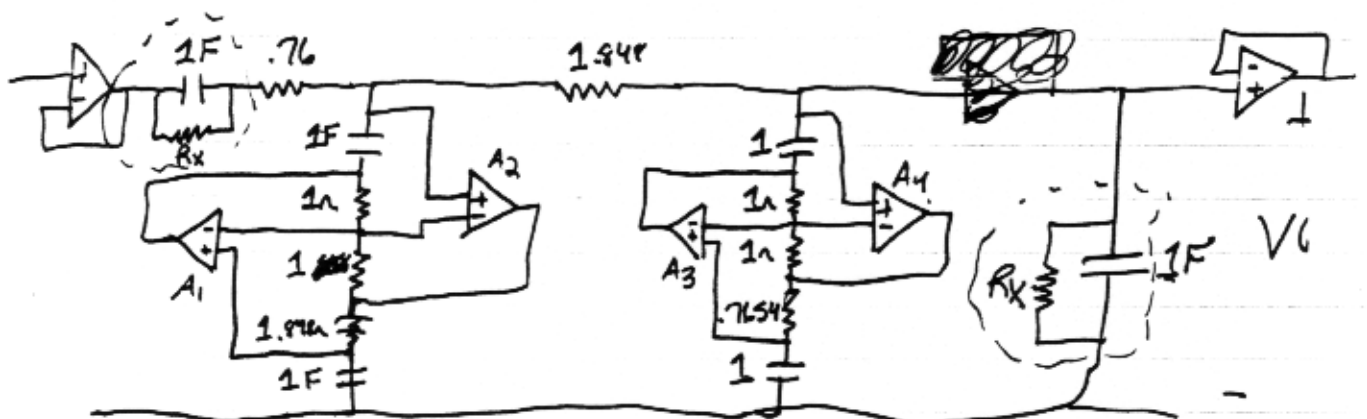
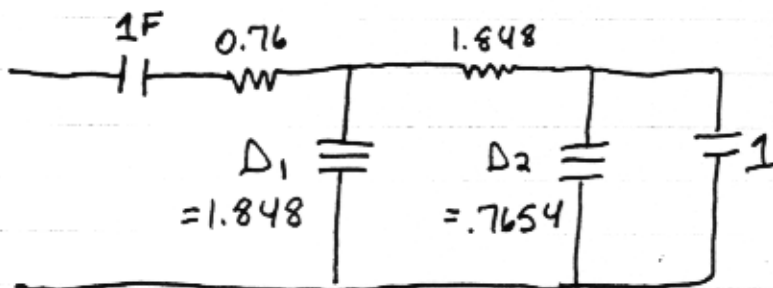
6/12/98

Design a fourth order LPF with  ~~$f_c = 1 \text{ kHz}$~~   
 $f_c = 1 \text{ kHz}$

USE a BUTTERWORTH APPROXIMATION:



BRUNTON'S TRANSFORMATION

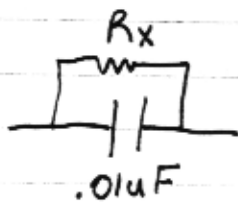


$$K_f = \frac{2\pi f_c}{1} = 2\pi \times 10^3 \quad C = 0.01 \mu F$$

$$.01 \times 10^{-6} = \frac{1}{K_f K_m} \quad \therefore K_m = 1.59 \times 10^4$$

→ OPAMPS MUST HAVE DC PATH TO GROUND. ←

$A_2$  &  $A_4$  are a problem - Add  $R_x$  on circuit as shown



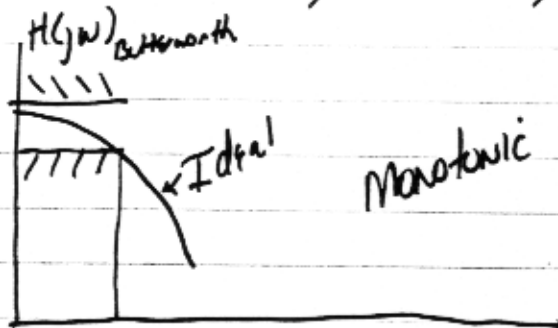
$$R_x = 10 \left( \frac{1}{\omega_{min} C} \right) \quad \text{CHOOSE } \omega_{min} = 100 \text{ Hz}$$

$$10 \left( \frac{1}{2\pi(100)(.01 \mu F)} \right)$$

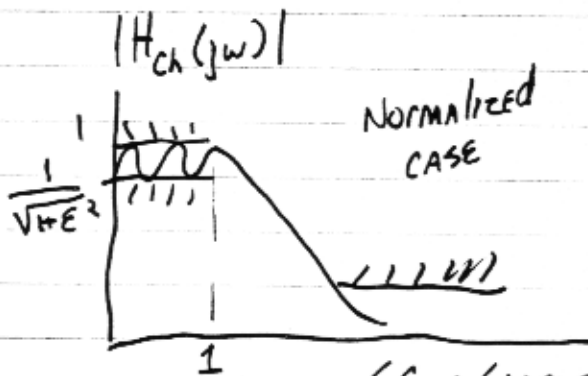
Add a buffer @ input AND ~~buffer~~ ~~buffer~~ @ output

{ PASSIVE HPF → ACTIVE  
 { PASSIVE LPF → ACTIVE

# The Chebyshev Approx



$$|H(jw)| = \frac{1}{\sqrt{1 + \left(\frac{w}{w_c}\right)^{2n}}}$$



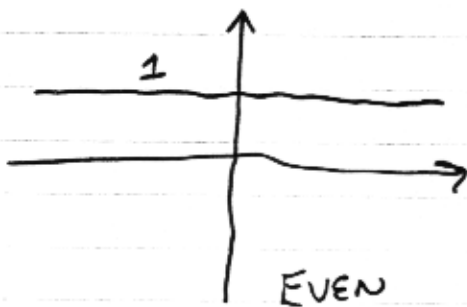
$$|H_{ch}(jw)| = \frac{1}{\sqrt{1 + \epsilon^2 C_N^2(w)}}$$

$C_N(w)$  = Chebyshev poly of order  $N$ .

$$C_N(w) = \begin{cases} \cos(N \cos^{-1} w) & 0 \leq w \leq 1 \\ \cosh(N \cosh^{-1} w) & w > 1 \end{cases}$$

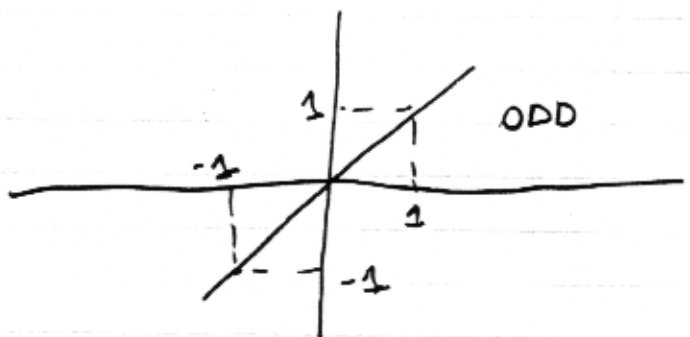
Properties of the Chebyshev polynomial

$$C_0(w) = \cos(0) = 1$$



$$N=1$$

$$C_1(w) = \cos(\cos^{-1} w) = w$$



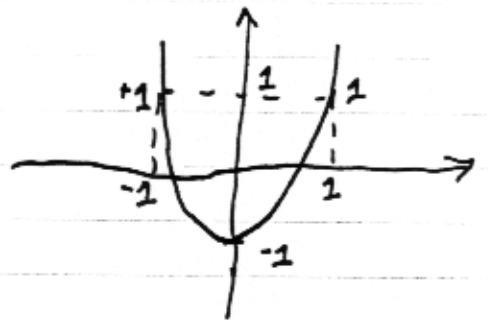
$$N=2$$

$$C_2(\omega) = \cos(2 \cos^{-1} \omega)$$

$$\text{Let } x = \cos^{-1} \omega \Rightarrow \omega = \cos x$$

$$C_2(\omega) = \cos(2x) = 2 \cos^2 x - 1$$

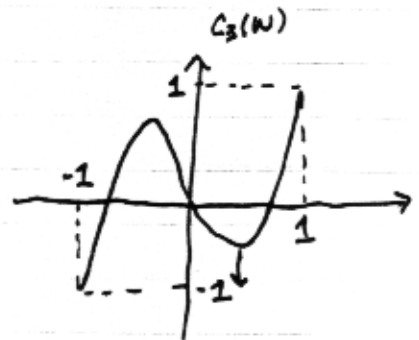
$$= 2\omega^2 - 1$$



$$C_{N+1}(\omega) = 2\omega C_N(\omega) - C_{N-1}(\omega)$$

$$C_3(\omega) = 2\omega C_2(\omega) - C_1(\omega)$$

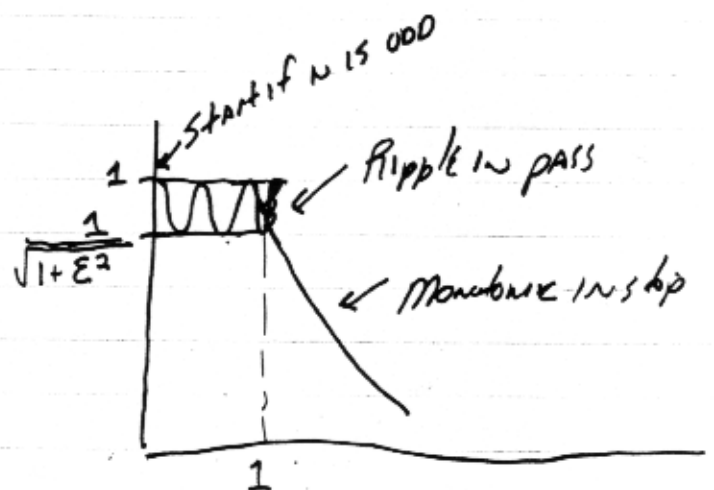
$$= 2\omega \{2\omega^2 - 1\} - \omega = 4\omega^3 - 3\omega$$



$$\frac{dC_3(\omega)}{d\omega} = 12\omega^2 - 3 \Rightarrow \omega^2 = \frac{1}{4} \quad \omega = \pm \frac{1}{2}$$

$$C_3\left(\frac{1}{2}\right) = -\frac{3}{2} + \frac{4}{8} = -1$$

$$|H_a(j\omega)| = \frac{1}{\sqrt{1 + \epsilon^2 C_N^2(\omega)}}$$



$N \equiv$  order

$\epsilon \equiv$  ripple

## REVIEW

$$e^{jx} = \cos x + j \sin x$$

$$\cos x = \frac{1}{2} \{ e^{jx} + e^{-jx} \}$$

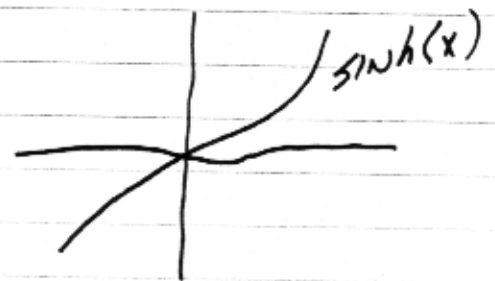
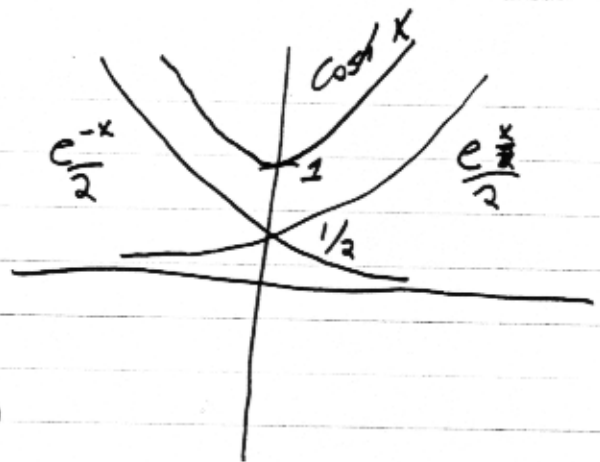
$$\sin x = \frac{1}{2j} \{ e^{jx} - e^{-jx} \}$$

$$\cosh x = \frac{e^x + e^{-x}}{2} = \cos(jx)$$

$$\sinh x = \frac{e^x - e^{-x}}{2}$$

$$\sin(jx) = \frac{1}{2j} \{ e^{-x} - e^x \}$$

$$= \frac{j}{2} \{ e^x - e^{-x} \} = j \sinh(x)$$



---

$$\cos(w) = \cos(N \cos^{-1} w)$$

If  $w > 1$

$$\cos^{-1}(w) = x$$

$$\cos x = w \leftarrow \text{real}$$

$$\frac{e^{jx} + e^{-jx}}{2} = w \quad x = jz \Rightarrow z \text{ real}$$

$$\frac{e^z + e^{-z}}{2} = w \quad x = jz$$

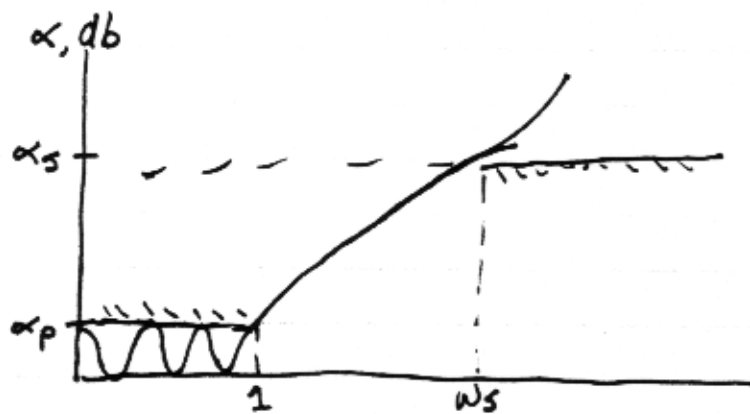
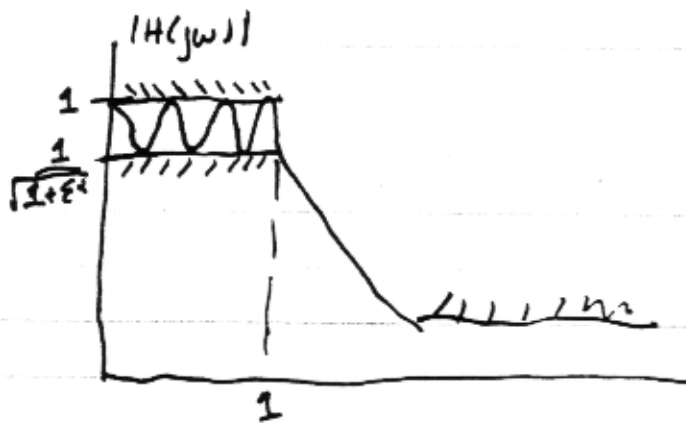
$$\cos(x) = w$$

$$\cos(w) = \cos(Nx) = \cos(Njz) = \cosh(Nz) \Rightarrow \boxed{\cosh(N \cosh^{-1} w)}$$

$$\cos(jz) = w \Rightarrow \cosh(z) = w$$

$$z = \cosh^{-1} w$$

## DESIGN EQUATIONS of normalized Chebyshev I LPF



$N = ?$   $\epsilon = ?$  poles? PASSIVE / ACTIVE.

$$\alpha(\omega) = -20 \log_{10} \{1 + \epsilon^2 C_N^2(\omega)\}$$

$$\alpha(1) = \alpha_p = 10 \log_{10} \{1 + \epsilon^2 C_N^2(1)\} = 10 \log_{10} \{1 + \epsilon^2\}$$

$$10^{\frac{\alpha_p}{10}} = 1 + \epsilon^2 \Rightarrow \epsilon = \sqrt{10^{\frac{\alpha_p}{10}} - 1} \quad (-1)$$

Finding order  $N$

$$\text{For } \omega > 1 \quad C_N(\omega) = \cosh(N \cosh^{-1} \omega)$$

$$\alpha(\omega_s) = \alpha_s = 10 \log_{10} (1 + \epsilon^2 C_N^2(\omega_s))$$

$$10^{\frac{\alpha_s}{10}} = 1 + \epsilon^2 C_N^2(\omega_s)$$

$$10^{\frac{\alpha_s}{10}} = 1 + \epsilon^2 (\cosh(N \cosh^{-1} \omega_s))^2$$

$$\frac{10^{\frac{\alpha_s}{10}} - 1}{\epsilon^2} = (\cosh(N \cosh^{-1} \omega_s))^2$$

$$\therefore \cosh(N \cosh^{-1} \omega_s) = \sqrt{\frac{10^{\frac{\alpha_s}{10}} - 1}{10^{\frac{\alpha_p}{10}} - 1}}$$

$$N \cosh^{-1} \omega_s = \left\{ \frac{10^{\frac{\alpha_s}{10}} - 1}{10^{\frac{\alpha_p}{10}} - 1} \right\}^{\frac{1}{2}} \cosh^{-1}$$

$$N = \text{Ceil} \left[ \frac{\cosh^{-1} \left( \sqrt{\frac{10^{\frac{\alpha_s}{10}} - 1}{10^{\frac{\alpha_p}{10}} - 1}} \right)}{\cosh^{-1} \omega_s} \right]$$

→ Finding the poles (normalized case)

$$|H_{ch}(j\omega)|^2 = H_{ch}(j\omega) H_{ch}(-j\omega) = H_{ch}(s) H_{ch}(-s) \Big|_{s=j\omega}$$

$$H(s) H(-s) = |H(j\omega)| \Big|_{s=\frac{s}{j}} = \frac{1}{1 + \epsilon^2 \cos^2(N \cos^{-1} s(j))}$$

Poles are equal to the roots of

$$1 + \epsilon^2 \cos^2(N \cos^{-1} s(j)) = 0$$

$$\cos^{-1} \left( \frac{s}{j} \right) = \omega = u + jv \quad \Rightarrow \quad \frac{s}{j} = \cos(\omega) = \cos(u + jv)$$

↑  
complex

$$s = j \{ \cos(u + jv) \} = j \{ \cos u \cos jv - \sin u \sin jv \}$$



$$= j \{ \cos u \cosh v - j \sin u \sinh v \}$$

$$= \sin u \sinh v + j \cos u \cosh v = \sigma + j\omega \leftarrow \text{imag.}$$

$$\Rightarrow 1 + \epsilon^2 \cos^2(N\omega) = 0$$

$$\cos^2(N\omega) = \frac{-1}{\epsilon^2} \Rightarrow \cos(N\omega) = \pm \frac{j}{\epsilon}$$

$$\cos(Nu + jNv) = \pm \frac{j}{\epsilon}$$

$$\cos Nu \cos jNv - \sin Nu \sin jNv = \pm \frac{j}{\epsilon}$$

$$\cos(Nu) \cosh(Nv) - j \sin(Nu) \sinh(Nv) = \pm \frac{j}{\epsilon}$$

$$\cos(Nu) \cosh(Nv) = 0 \Rightarrow \cos(Nu) = 0$$

$$Nu = \frac{(2k+1)\pi}{2}, \quad k = 0, 1, 2, 3, \dots$$

$$u_k = \frac{(2k+1)\pi}{2N}, \quad k = 0, 1, 2, 3, \dots$$

$$\sin(Nu) \sinh(Nv) = \pm \frac{1}{\epsilon} \Rightarrow \sinh(Nv) = \pm \frac{1}{\epsilon}$$

$$Nv = \pm \sinh^{-1} \frac{1}{\epsilon}$$

$$v_k = \pm \frac{1}{N} \sinh^{-1} \left( \frac{1}{\epsilon} \right) \quad k = 0, 1, 2, 3, \dots$$

$$S = \sin u \sinh v + j \cos u \cosh v$$

$$= \sigma + j\omega$$

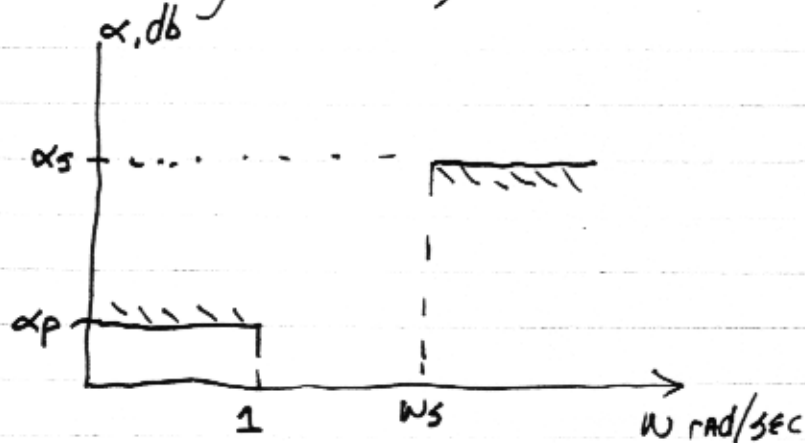
Real part  $\rightarrow \sigma_k = - \left[ \sinh \left( \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right) \sin \frac{(2k+1)\pi}{2N} \right]$

$\omega_k = \left[ \cosh \left( \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right) \cos \left( \frac{(2k+1)\pi}{2N} \right) \right]$

}  $k = 0, 1, 2, 3, \dots$

TABLES PAGE 248

## DESIGN CHEBYSHEV I LPF



$$\alpha(\omega) = 10 \log_{10} \{ 1 + \epsilon^2 C_N^2(\omega) \}$$

$$\epsilon = \sqrt{10^{\alpha_p/10} - 1} \quad (1)$$

$$N = \lceil \epsilon \rceil \left( \frac{\sqrt{10^{\alpha_s/10} - 1}}{10^{\alpha_p/10} - 1} \frac{1}{\cosh^{-1} \omega_s/\omega_p} \right) \quad (2)$$

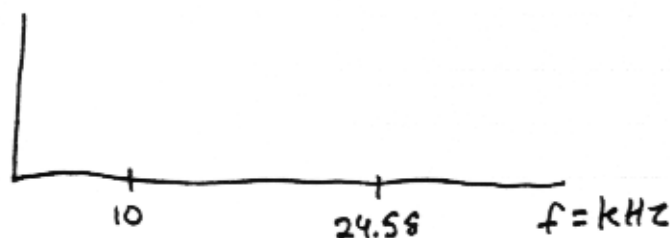
POLES:  $P_k = \sigma_k + j\omega_k$

$$\text{where } \sigma_k = - \left| \sinh \left\{ \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right\} \frac{\sin(2k+1)\pi}{2N} \right|$$

$$\omega_k = \cosh \left\{ \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right\} \frac{\cos(2k+1)\pi}{2N}$$

$k = 1, 2, 3, \dots, N \leftarrow \text{order}$

Example Design a LPF with  $f_p = 10 \text{ kHz}$  w/  $\alpha_p = .3 \text{ dB}$   
 $f_s = 24.58 \text{ kHz}$  &  $\alpha_s = 22 \text{ dB}$



$$\omega_p = 2\pi \times 10^4 \text{ rad/sec}$$

$$\omega_s = 2\pi \times 24.58 \times 10^3 \text{ rad/sec}$$

Normalized so  $\omega_p = 1 \text{ rad/sec}$

$$\therefore K_f = 2\pi \times 10^4$$

Find the order

$$N = 3$$

$$\epsilon = \sqrt{10 \cdot 3/10 - 1} =$$

Find the poles:

$$\sigma_k = -\left/ \sinh \left\{ \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right\} \frac{\sin(2k+1)\pi}{2N} \right/$$

$$\omega_k = \cosh \left\{ \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right\} \frac{\cos(2k+1)\pi}{2N}$$

$N$  odd  $\Rightarrow$  Real pole:  $-\left/ \sinh \frac{1}{N} \sinh^{-1} \frac{1}{\epsilon} \right/ = -0.7293 \text{ rad/sec}$   
( $k=1$ )

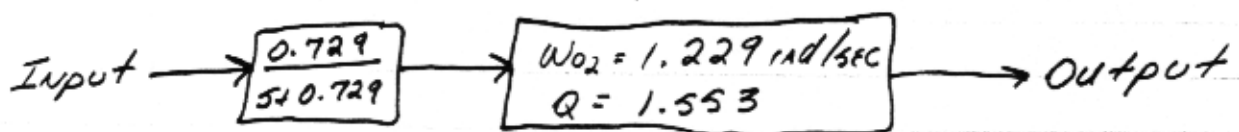
Complex Poles:  $P_2, P_3 = -0.3646 \pm j 1.072$

$$\omega_0 = \sqrt{(0.3646)^2 + (1.072)^2} = 1.22906 \text{ rad/sec}$$

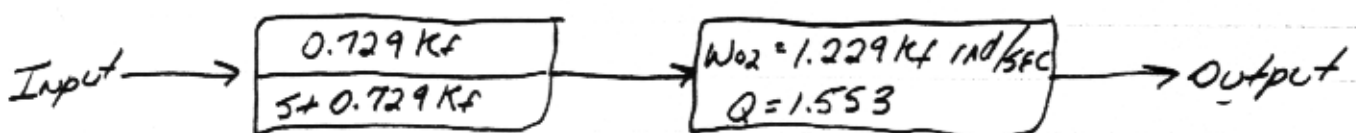
$$Q = \frac{\omega_0}{2 \times 0.3646} = 1.553$$

### REALIZATION

Normalized filter



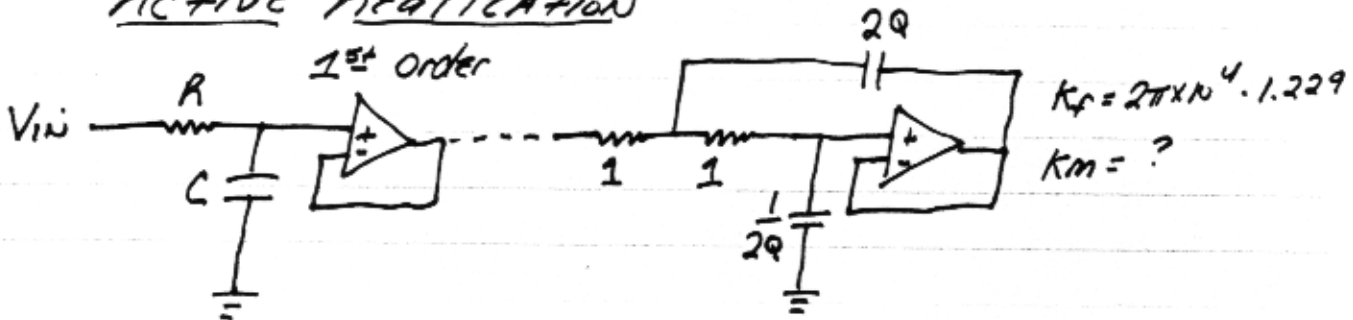
Denormalized filter:  $K_f = 2\pi \times 10^4$



# PAGE 248 CHEBYSHEV POLE LOCATIONS

$$P = -\alpha + j\beta$$

## ACTIVE REALIZATION



$$RC = \frac{1}{0.729 K_f}$$

Assume C to And R

$$\omega_{02} = K_f \times 1.229 = 1.229 \cdot 2\pi \times 10^4$$

$$Q_2 = 1.553$$

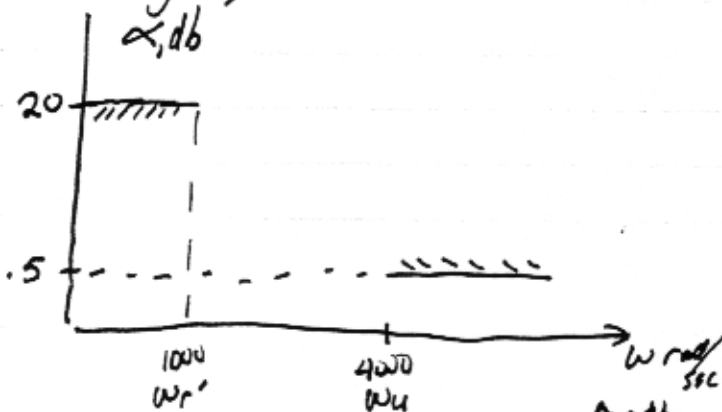
## DESIGN OF PASSIVE CHEBYSHEV I LPF

- PAGE 414

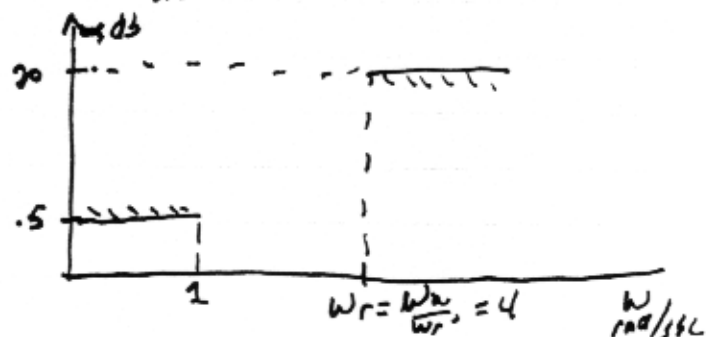
### → HPF DESIGN

EXAMPLE:

DESIGN A HPF WITH CH1 APPROX. TO MEET THE FOLLOWING SPECS.



HPF → LPF x-form



$$N = 2 \text{ (from X-film)}$$

$$\epsilon = \sqrt{10^{0.5} - 1} = 0.3493$$

From table: Poles:  $-.7128 \pm j1.004$

$$\omega_{0(LP)} = \sqrt{(.7128)^2 + (1.004)^2} =$$

$$Q = \frac{\omega_{0(LP)}}{2 \cdot 0.7128} = .863$$

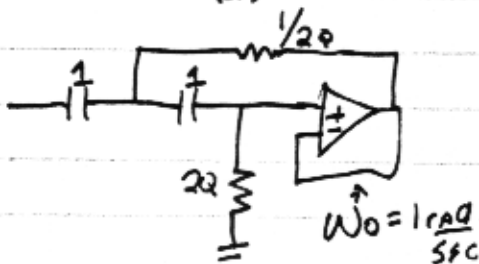
$$G(s) = \frac{\omega_{0(LP)}}{s^2 + s \frac{\omega_{0(LP)}}{Q} + \omega_{0(LP)}^2}$$

$$H(s) = G(s) \Big|_{s = \frac{\omega_{HP}}{s}} = \frac{s^2}{s^2 + s \frac{\omega_{0(LP)}}{Q} + \omega_{0(LP)}^2}$$

$$Q_{HP} = Q_{LP} = .863$$

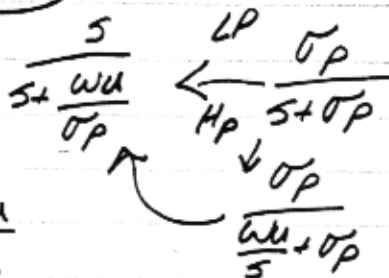
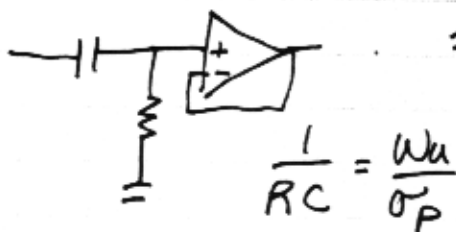
$$\omega_{HP} = \frac{\omega_u}{\omega_{0(LP)}} = 3252 \frac{\text{RAD}}{\text{SEC}}$$

Prototype  
HPF



$$K_f = 3252 \frac{\text{RAD}}{\text{SEC}}$$

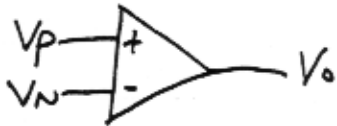
$$Q = .863$$



First (Real)  
Order  
Pole

# The real opamp model

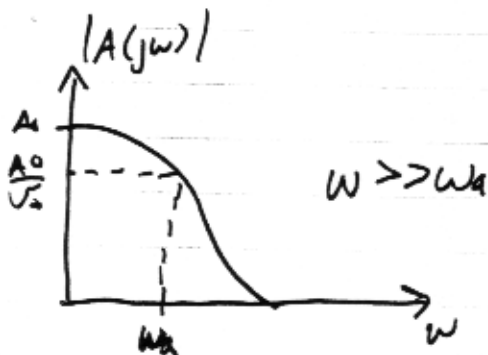
6/22/98



$$V_o = A(s)(V_p - V_n)$$

$$A(s) = \frac{A_o}{1 + s/\omega_o}$$

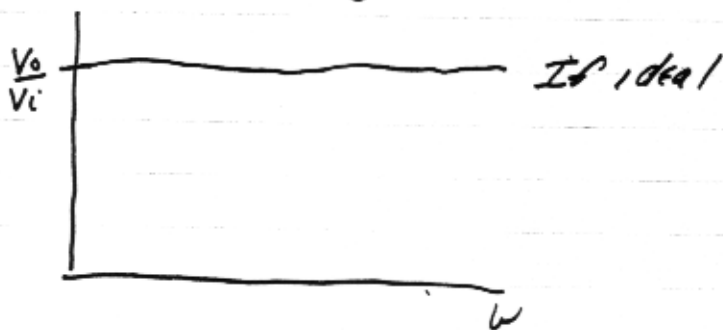
$$A(j\omega) = \frac{A_o}{1 + j\omega/\omega_o}$$



$$A(j\omega) = \frac{A_o \omega_a}{j\omega}$$

$$As = \frac{GB}{s} \Rightarrow \text{gain bandwidth product}$$

## Non-inverting amp



ANALYSIS:  $\frac{R}{R + (K-1)R} V_o = V_n = \frac{V_o}{K}$  (1)

$$V_o = A(s) V_p - V_n = A(s) (V_i - V_n)$$
 (2)

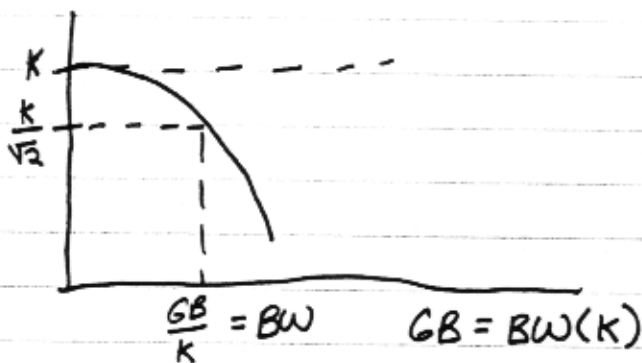
$$V_o = A(s) \left( V_i - \frac{V_o}{K} \right) \quad \frac{V_o}{A(s)} + \frac{V_o}{K} = V_i$$

$$V_o \left( \frac{1}{A(s)} + \frac{1}{K} \right) = V_i \Rightarrow \frac{V_o}{V_i} = \frac{K}{1 + K/A(s)}$$

$$\frac{V_o}{V_i} = \frac{K}{1 + sK/GB} \Leftarrow \text{1st order LPF}$$

$$\text{Freq. Response: } H(j\omega) = \frac{V_o(j\omega)}{V_i(j\omega)} = \frac{K}{1 + j\omega K/GB}$$

$$|H(j\omega)| = \frac{K}{\sqrt{1 + \left(\frac{\omega K}{GB}\right)^2}}$$



$$\angle H(j\omega) = -\tan^{-1} \frac{\omega K}{GB}$$

## Error Analysis

### ① Magnitude Response Error

$$|H(j\omega)| = \frac{K}{\sqrt{1 + \left(\frac{\omega K}{GB}\right)^2}} \quad \text{ASSUME } \omega \ll \frac{GB}{K}$$

$$|H(j\omega)| = K \left\{ 1 - \frac{1}{2} \left(\frac{\omega K}{GB}\right)^2 \right\} \quad \% \text{ Mag. Error} = -\frac{1}{2} \left(\frac{\omega K}{GB}\right)^2$$

VERY SMALL  $\rightarrow$



## ② PHASE RESPONSE ERROR

$$\theta(j\omega) = \angle H(j\omega) = -\tan^{-1}\left(\frac{\omega k}{GB}\right)$$

$$\tan^{-1} x = x - \frac{x^3}{3} + \dots \dots \dots |x| \ll 1$$

$$\tan^{-1} x \approx x$$

$$\theta(j\omega) = -\frac{\omega k}{GB} \leftarrow \text{PHASE ERROR IN RADIANS}$$

Example/

- $\rightarrow k=3 \rightarrow \text{amp } \omega / GB = 2\pi \times 1.5 \times 10^6 \text{ rad/sec}$
- $\rightarrow \text{freq. range } 0-50 \text{ kHz}$

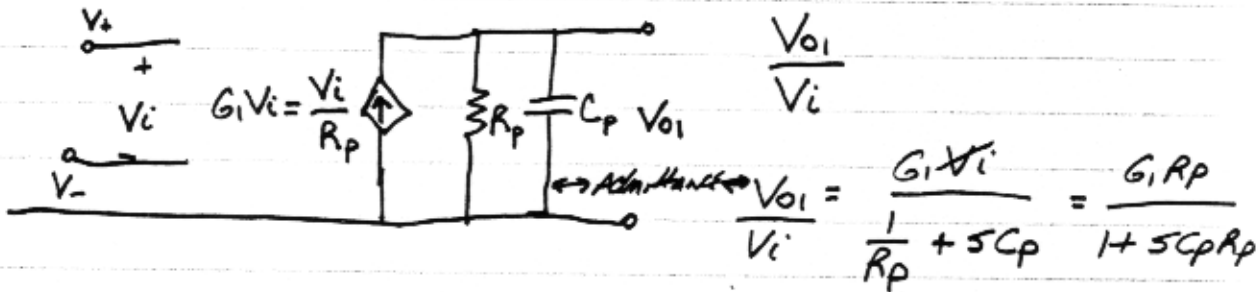
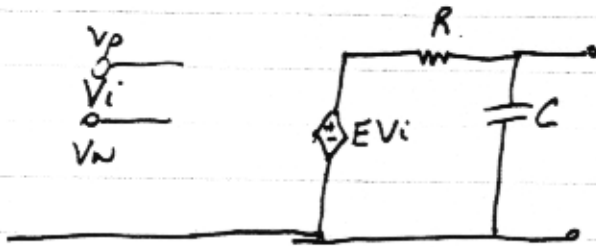
$\rightarrow$  Find the phase error in degrees.  $\leftarrow$

$$\theta(\omega) = \frac{-2\pi \times 50 \times 10^3 (3)}{2\pi \times 1.5 \times 10^6} \text{ (RADIANS)}$$

$$\theta(\omega) \text{ in degrees} = \frac{-2\pi \times 50 \times 10^3 (3)}{2\pi \times 1.5 \times 10^6} \cdot \frac{180}{\pi} = -5.7^\circ$$

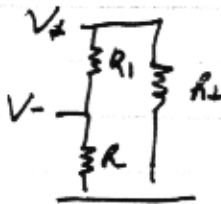
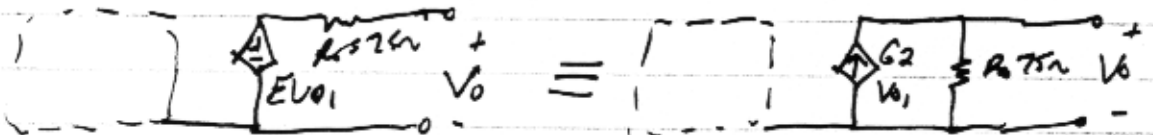
# Simple Opamp Macro Model

$$A(s) = \frac{A_0}{1 + s/\omega_a} = \frac{V_o}{V_i}$$



$$\frac{G_1 R_p}{1 + s C_p R_p} = \frac{A_0}{1 + s/\omega_a} \quad A_0 = G_1 R_p \quad (1)$$

$$\omega_a = \frac{1}{C_p R_p} \quad (2)$$



$$R_1 = 1 \text{ M}\Omega$$

$$R_+ = 10 \text{ M}\Omega$$

$$R_- = 10 \text{ M}\Omega$$

For GB = 1 MHz

$$G_1 = 0.62 \text{ pS} \quad R_0 = 75 \Omega$$

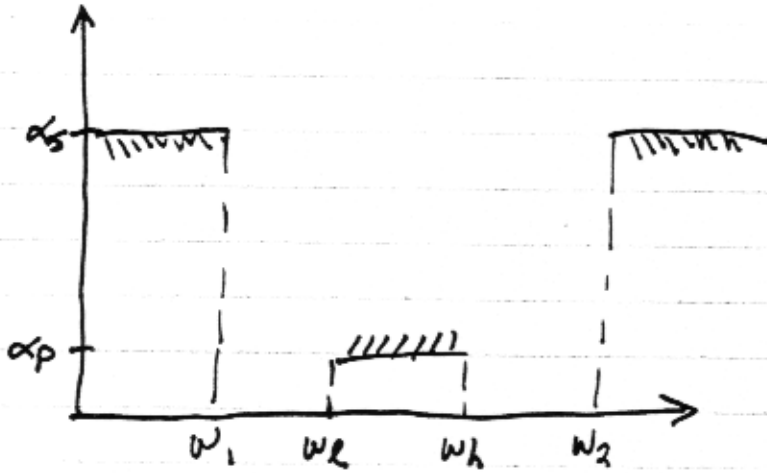
$$G_2 = 1/75 = 0.01333 \quad R_p = 159.155 \text{ k}\Omega$$

$$C_p = 0.1 \mu\text{F}$$

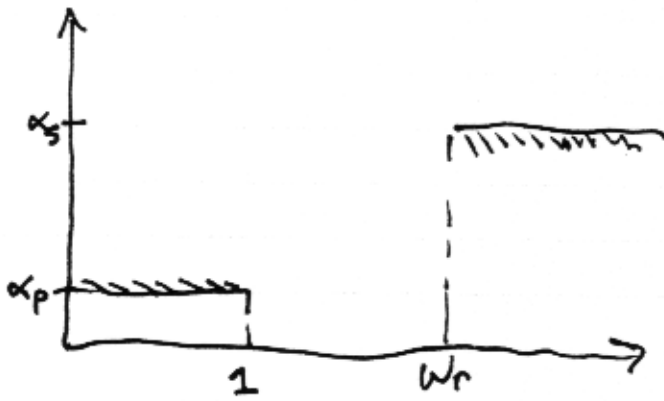


# DESIGN ACTIVE BPF

6/24/98



BP  $\rightarrow$  LP X-form



$$H_{LP}(s) = \frac{E}{s+E} \cdot \frac{\omega_0^2 (LP)}{s^2 + \frac{\omega_0 (LP)}{Q_1} s + \omega_0^2 (LP)}$$

*1<sup>st</sup> order*

$$H_{BPF}(s) = H_{LP}(s) \Big|_{s = \frac{s^2 + \omega_0^2}{sBW}}$$

$$Q = \frac{q_c}{E} \quad q_c = \frac{\omega_0}{BW}$$

## Geffe's Algorithm

$$C = \Omega_2^2 + \epsilon^2$$

$$D = \frac{2\epsilon\Omega_0}{q_c}$$

$$E = 4 + \frac{C}{q_c^2}$$

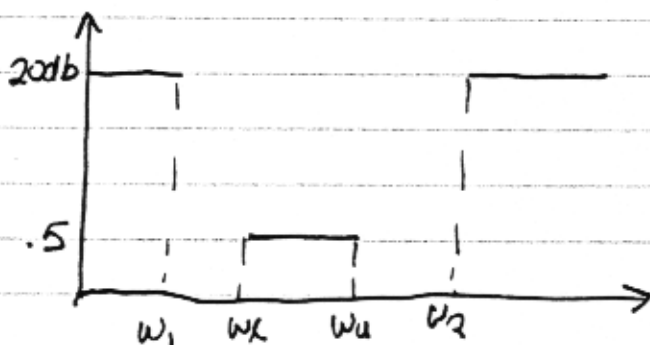
$$G = \sqrt{E^2 - 4D^2}$$

$$Q_{BP} = \frac{1}{D} \sqrt{\frac{E+G}{2}}$$

$$K = \frac{\epsilon_2 Q_{BP}}{q_c}$$

$$W = K + \sqrt{K^2 - 1} \quad \omega_{o(BP)} = \frac{\omega_0}{W} \quad \omega_{2(BP)} = \omega_0 W$$

### EXAMPLE



$$\omega_L = 500 \text{ rad/sec}$$

$$\omega_H = 1000 \text{ " "}$$

$$\omega_1 = 333 \text{ " "}$$

$$\omega_2 = 1500 \text{ " "}$$

$$\omega_0 = \sqrt{\omega_L \omega_H} = 707.1 \text{ rad/sec}$$

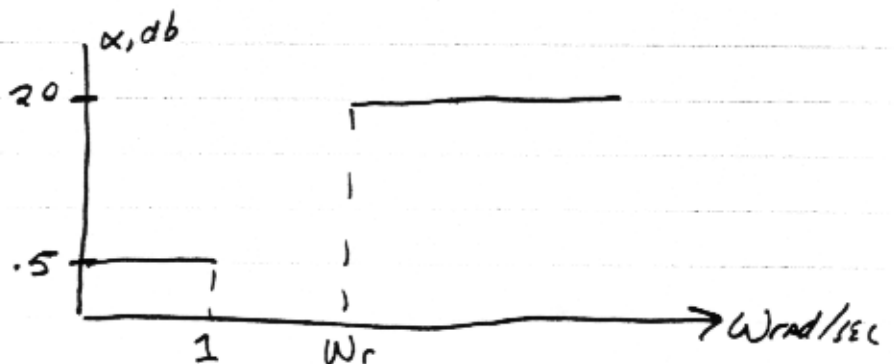
$$q_c = \omega_0 / BW = 1.414$$

$$BW = \omega_H - \omega_L = 500 \text{ rad/sec}$$

$$A = 2.336$$

$$B = 2.333$$

$$\omega_r = 2.333$$



CHOOSE CHEBYSHEV I APPROX.

$N=3 \Rightarrow$  FIND POLES FROM THE TABLE.  $\leftarrow$

$$P_1 = -0.6265 \text{ (REAL)}$$

$$T_1(s) = \frac{E}{s+E} = \frac{0.6265}{s+0.6265}$$

$$P_{2,3} = -0.3132 \pm j1.022$$

$$= -\zeta_2 \pm j\Omega_2$$

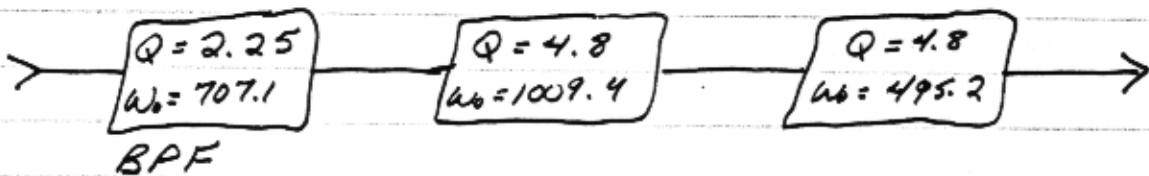
$$T_2(s) =$$

CONSIDER  $T_2(s) / s = \frac{s^2 \omega_0^2}{s^2 + 5s\omega_0} \Rightarrow$   $\boxed{\text{BPF}_1}$  —  $\boxed{\text{BPF}_2}$

$Q = 4.8$   
 $\omega_0 = 1009.4$   
rad/sec

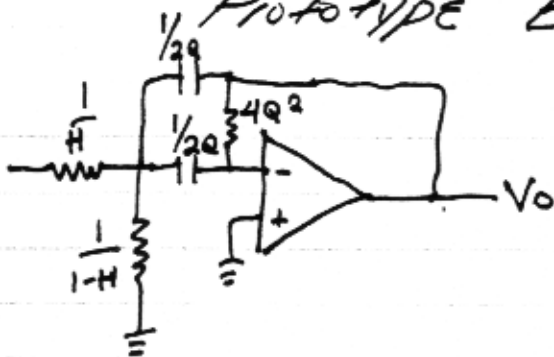
$\omega_0 = 495.2$  rad/sec  
 $Q = 4.8$

FINAL FILTER





### Prototype BPF Circuit



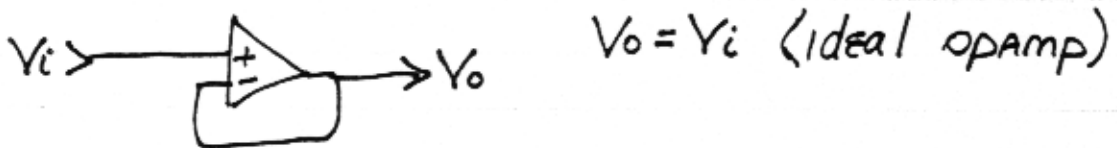
$$\omega_0 = 1 \text{ rad/sec}$$

$$\frac{V_o(s)}{V_i(s)} = \frac{-(Hs/Q)2Q^2}{s^2 + \frac{s}{Q} + 1}$$

$H < 1$  1<sup>st</sup> stage  $Q = 2.757$   $\omega_0 = 707.1$   $H_1 = ?$

$K_{F1} = 707.1$   $K_m = ?$

### THE SLEW RATE EFFECT



MAX VOLT CHANGE / TIME  $\Rightarrow$  SLEW RATE

741 1V/ $\mu$ s Better 1000V/ $\mu$ s

MAX happens where  $\sin(\omega t)$  crosses x-axis

$$\left| \frac{dV}{dt} \right|_{\max} = V \times \omega \cos \omega t \Big|_{t=0} = \boxed{V \times \omega \leq SR}$$